

> DM3610 Dimensioner



DATALOGIC

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DM3610 Reference Manual

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REFERENCE DOCUMENTATION

The documentation related to the DM3610 management is listed below:

- CBX100 Connection Box Installation Manuals
- BM100 Backup Module Reference Manual

SUPPORT THROUGH THE WEBSITE

Datalogic provides several services as well as technical support through its website. Log on to **www.datalogic.com** and click on the **Industrial Automation** <u>links</u> for further information:

Products - Industrial Automation - Identification

Select your product from the links on the **Identification** page. The product page describes specific Info, Features, Applications, Models, Accessories, and Downloads including documentation.

Support & Services - Industrial Automation

Several links from the **Industrial Automation** list take you to additional services such as: <u>Service Program</u> which contains Maintenance Agreements and Warranty Extensions; <u>Repair Centers</u>; <u>On-Line RMA</u> Return Material Authorizations; <u>Technical Support</u> through email or phone, <u>Partner Program</u>; <u>Downloads</u> for additional downloads.

PATENTS

This product may be covered by one or more of the following patents:

Utility patents: EP0652530B1; EP0851206B9; EP0851208B1; EP0851376B1; EP1363228B1; EP1607901B1; GB2440818B; JP3793585B2; JP4033958B2; US5903354; US5969823; US6061645; US6347740; US6442503; US6629639; US7586049; USRE36251.

Additional patents pending.

CONVENTIONS



WARNINGS or CAUTIONS: This symbol identifies a hazard or procedure that, if incorrectly performed, could cause personal injury or result in equipment damage. It is also used to bring the user's attention to details that are considered IMPORTANT.



HIGH VOLTAGE CAUTION: This symbol alerts the user they are about to perform an action involving, either a dangerous level of voltage, or to warn against an action that could result in damage to devices or electrical shock.



LASER CAUTION: This symbol alerts the user they are about to perform an action involving possible exposure to laser light radiation.



ESD CAUTION: This symbol identifies a procedure that requires you take measures to prevent Electrostatic Discharge (ESD) e.g., use an ESD wrist strap. Circuit boards are most at risk. Please follow ESD procedures.



NOTES: This symbol draws attention to details or procedures that may be useful in improving, maintaining, or enhancing the performance of the hardware or software being discussed.

COMPLIANCE

ELECTRICAL SAFETY

This product conforms to the applicable requirements contained in the European Standard for electrical safety EN-60950 at the date of manufacture.

LASER SAFETY

The following information is provided to comply with the rules imposed by international authorities and refers to the correct use of the DM3610 dimensioner.

Standard Regulations

This dimensioner uses a low-power laser diode. Avoid staring at the beam as one would with any very strong light source, such as the sun.

Take care when installing the laser device to avoid inadvertent laser beam contact with the eye of an observer, including through reflective surfaces.

This product conforms to the applicable requirements of both EN60825-1 and CDRH 21 CFR1040 at the date of manufacture. The DM3610 uses a visible laser diode (red) 658nm, Collimated < 1.5mR, <9.6mW peak power, <1.0mW Average power, Class 3R (IEC60825-1), Class II (CDRH 21CFR1040), in the dimensioning process.

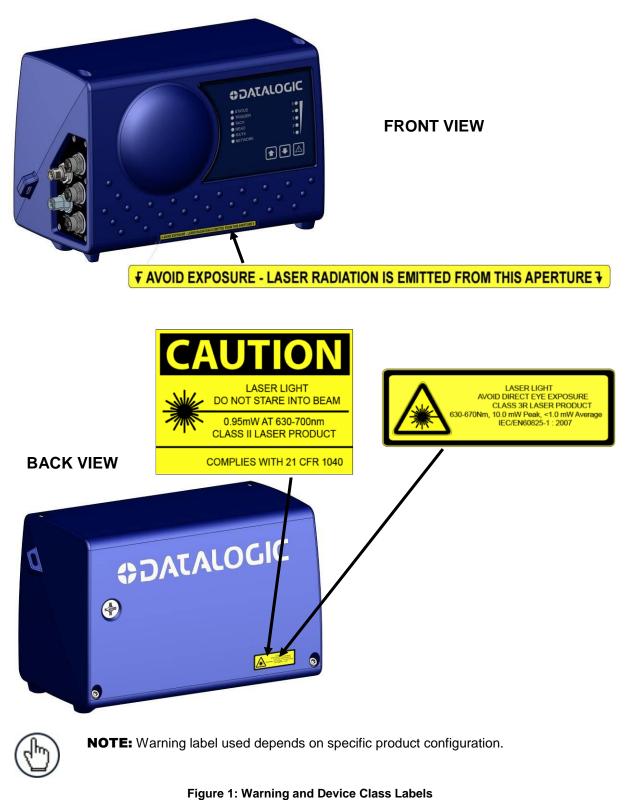
There is a safety device which allows the laser to be switched on only if the motor is rotating above the threshold for its correct scanning speed.



WARNING: Use of controls or adjustments or performance of procedures other than those specified herein may result in exposure to hazardous visible laser light.

WARNING LABELS

Warning labels indicating exposure to laser light and the device classification are applied onto the body of the dimensioner.





WARNING: Disconnect the power supply when installing the device or during maintenance to avoid exposure to hazardous laser light.

WARNING: There are no user serviceable parts inside the DM3610. Service should only be performed by Datalogic trained and certified technicians. Any violation of the optic parts in particular can cause radiation up to the maximum level of the laser diode (30 mW at 630~680 nm).

POWER SUPPLY

This product is intended to be installed by Qualified Personnel only.

This dimensioner is intended to be supplied by a UL/CE Listed power supply marked SELV (Separated Extra Low Voltage), output rated 24 VDC, minimum 4.0 Amp.

UL LISTING



CE COMPLIANCE





WARNING: This is a Class A product. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.

FCC COMPLIANCE

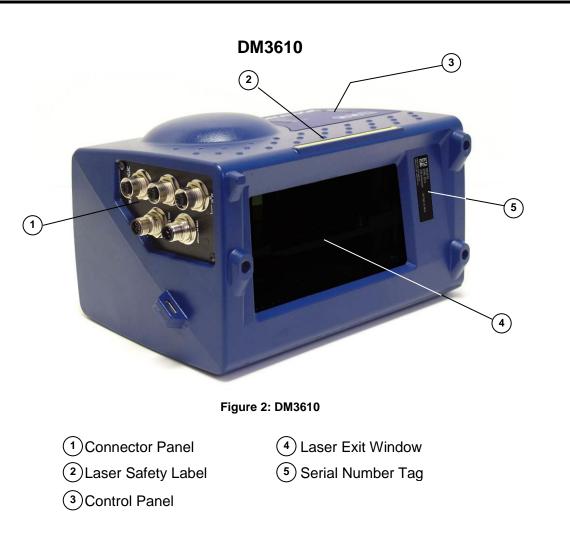


Modifications or changes to this equipment without the expressed written approval of Datalogic could void the authority to use the equipment.

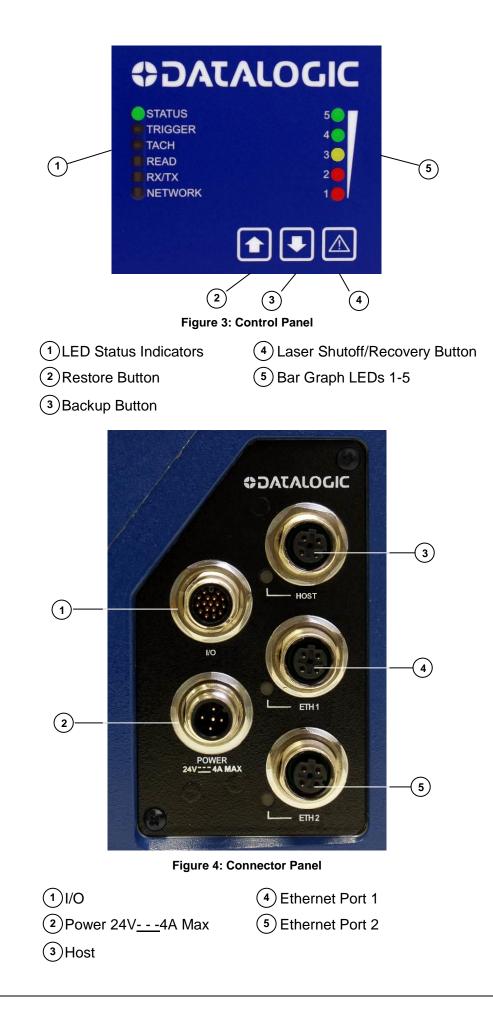
This device complies with PART 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference which may cause undesired operation.

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency

energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his/her own expense.



GENERAL VIEW



1 INTRODUCTION

1.1 SYSTEM OVERVIEW

The DM3610 Dimensioning System provides product dimension data. The DM3610 is a compact overhead, laser-based automatic dimensioning unit. It measures the length, width and height of packages as they move along a conveyor. It accurately dimensions cuboidal conveyable packages, which pass under the unit one at a time.

The DM3610 mounts easily overhead and does not require a break in the conveyor. The unit is lightweight and completely self-contained. The system includes:

- DM3610 Dimensioner that determines all of the box dimensions
- CBX Connection Box
- Tachometer
- Photoelectric sensor (as needed)
- Web-based user interface software

The DM3610 also provides on-line diagnostics and monitoring.



IMPORTANT: Due to the complex and application-specific nature of dimensioning / certified dimensioning installations, the DM3610 must be installed, setup and serviced by a trained and authorized Datalogic technician. There are no user serviceable components inside the DM3610.

Training is available through specific Service Programs and Maintenance Agreements. See our website at <u>www.datalogic.com</u>.

1.1.1 Dimensioning System Benefits

The DM3610 offers unparalleled dimensioning performance:

- Accurate dimensioning at high speed Provides accuracy +/- 5mm [0.2"] at belt speeds up to 3.1 m/s [620 fpm] (application dependent)
- Easy setup Exclusive "Find-Belt" software functionality enables automated setup and plug-and-play operation
- Reliability Uses a solid state laser diode and phase-shift technology

1.2 APPLICATIONS

The DM3610 dimensioning system is specifically designed for industrial applications and for all cases requiring accurate dimensioning performance such as:

- Singulated (cuboidal)
- Non-Singulated (cuboidal, touching and non-touching) In development at release of this manual
- Irregulars (non-cuboidal) In development at release of this manual
- Dimension-Weighing-Scanning (DWS) Systems
- Scanning Tunnels (focusing and token generation) In development at release of this manual

1.2.1 Typical Application

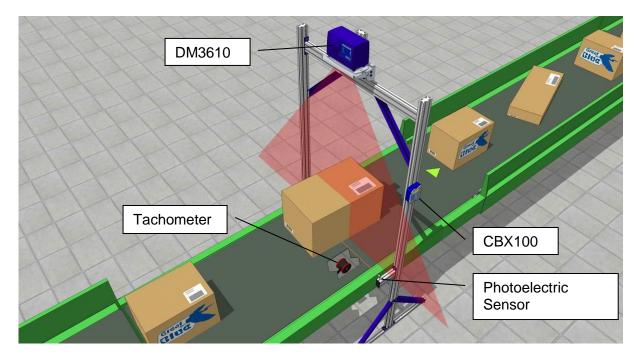


Figure 5: Typical DM3610 Installation (Singulated Version)



NOTE: In certain applications a Photoelectric Sensor is not required. Contact your Datalogic Application Engineer for clarification. An operational description is provided in *chapter 5* For product specifications, see *chapter 8*.

1.2.2 DM3610 in DWS Systems

The DM3610 Dimensioning System is often used in DWS systems that perform product dimensioning, weighing, and bar code scanning. Often, the dimensioner is combined with either a Datalogic laser scanner or camera to scan products for bar codes. The decoded bar code information is combined with the weight and dimension data, which is then transmitted to a HOST computer.

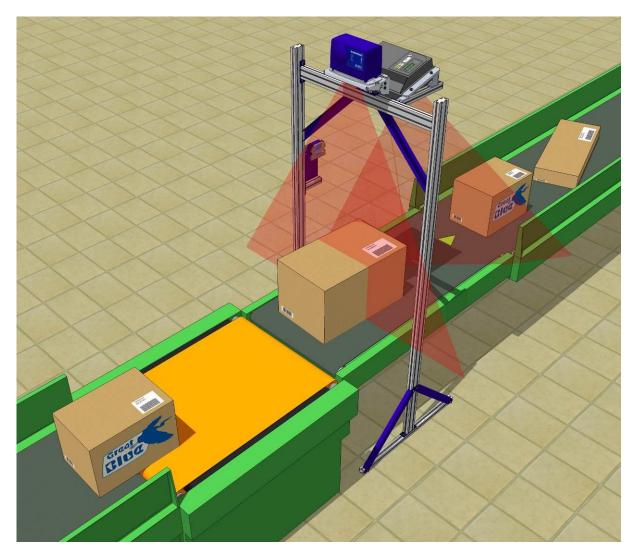


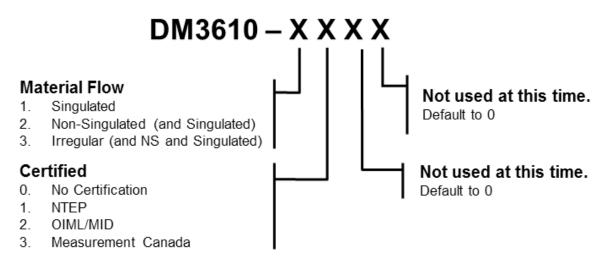
Figure 6: DM3610 in a Dimension-Weigh-Scan (DWS) System

1.2.3 Irregular Dimensioning System

The DM3610 system is also available in a configuration that enables it to dimension 'irregular shaped' (non-cuboidal) products and packages, however, *details and specifications were not available at the publication of this manual revision.*

1.3 MODEL DESCRIPTION

The DM3610 Dimensioner is available in versions that differ depending on the type of material flow, certification, and custom:





1.4 ACCESSORIES, OPTIONS, AND SPARE PARTS

The following accessories are available on request for DM3610:

Name	Description	Part Number
Mounting Bracket	BK-3610 MOUNTING BRACKET KIT, DM3610	93ACC0057
Power Supply	PG-100-K01 PWR SUPPLY 100W KIT DM36 (EU)	93ACC0059
	PG-100-K02 PWR SUPPLY 100W KIT DM36 (UK)	93ACC0060
	PG-100-K03 PWR SUPPLY 100W KIT DM36 (US)	93ACC0058
Calibration Kit	DIM-CAL-IMP-DM3610 DIM CAL KIT IMPERIAL	93ACC0061
	DIM-CAL-MET-DM3610 DIM CAL KIT METRIC	93ACC0062
Certification Kit	DIM-CERT-K01-DM3610 NTEP CERT KIT	93ACC0063
	DIM-CERT-K02-DM3610 OIML CERT KIT	93ACC0064
	DIM-CERT-K03-DM3610 MC CERT KIT	93ACC0065
Cables to CBX	CAB-DS01-S M12-IP67 TO CBX 1M	93A050058
	CAB-DS03-S M12-IP67 TO CBX 3M	93A050059
	CAB-DS05-S M12-IP67 TO CBX 5M	93A050060
Ethernet Adapter Cable	CAB-ETH-M01 M12-IP67 ETHERNET CABLE (1M)	93A051346
	CAB-ETH-M03 M12-IP67 ETHERNET CABLE (3M)	93A051347
	CAB-ETH-M05 M12-IP67 ETHERNET CABLE (5M)	93A051348
CBX100 with BM100	CBX100 ALL-IN-ONE +BM100	93A301076
80/20	80/20 ADAPTERS FOR CBX	1000071630
BA200	BOSCH ADAPTERS FOR CBX	93ACC1822
Photoelectric Sensor and Cable (recommended)	KIT,S60 NPN PHOTOCELL,R3 REFL/BRKT/HDWR	93ACC1894
	CV-A1-22-B-05 SE 4pin CABLE 5m	95ACC1490
Tachometer, 12-Inch Wheel	TACH,PROGR,W/20FT CAB,8-30VDC	1000019875
Tachometer, 30 cm Wheel	OEK-1 OPTICAL ENCODER KIT, W/10M CABLE	93ACC1600
GP018 Remote Display	40 CHAR DISPLAY	0109360001
GP018 Power Supply	ASY, P/S 120V, EXTRL DSPLY	1000016280
GP018 Cable	CBL ASY, 15FT, 40 CH DSPLY-INTFL, FL	0113522015



NOTE: Dimensioning Solution kits are available which include: Dimensioner, Mounting Bracket, Power Supply and Connection Box with mounting hardware, and Communication Cables.

1.4.1 DM3610 Dimensioning Unit

The DM3610 dimensioning unit is designed with industrial and manufacturing applications in mind. The DM3610 is designed for easy setup and operation.



Figure 8: DM3610 Dimensioning Unit

1.4.2 DM3610 Versions

The DM3610 is available in several versions:

- DM3610-1000 STD NLFT (for applications not requiring Legal-for-Trade certification)
- DM3610-1100 SING NTEP (for NTEP certified singulated applications with "non-touching" packages)
- DM3610-1200 SING OIML/MID (for OIML certified singulated applications with "nontouching" packages)
- **DM3610-1300 SING MC** (for Measurement Canada certified singulated applications with "non-touching" packages)
- **DM3610-2100 NONSING NTEP** (for NTEP certified non-singulated applications with "touching" packages)
- DM3610-2200 NONSING OIML/MID (for OIML certified non-singulated applications with "touching" packages)
- DM3610-2300 NONSING MC (for Measurement Canada certified non-singulated applications with "touching" packages)
- **DM3610-3100 IRREG NTEP** (for NTEP certified applications running non-cuboidal (irregular) items)
- DM3610-3200 IRREG OIML/MID (for OIML certified applications running non-cuboidal (irregular) items)
- DM3610-3300 IRREG MC (for Measurement Canada certified applications running noncuboidal (irregular) items)

DM3610	Conveyor Conveyor		Package Length		Package Width		Package Height	
Versions	Speed	Width	Min	Max	Min	Max	Min	Max
DM3610-1X00	3.1 m/s [620 fpm]	1200mm [48"]	60mm [2.4"]	2500mm [98"]	60mm [2.4"]	1200mm [48"]	30mm [1.2"]	900mm [36"]
DM3610-2X00	tbd	tbd	tbd	tbd	tbd	tbd	tbd	tbd
DM3610-3X00	tbd	tbd	tbd	tbd	tbd	tbd	tbd	tbd

Performance for DM3610 Dimensioner Versions (see also chapter 8, Technical Features)

NOTE: See your specifications for range of package sizes. Not all version details were available at the release of this manual.

NOTE: Specifications may differ depending on local Legal-for-Trade requirements. See certification certificate for details.

1.4.3 DM3610 Certified Dimensioning

The DM3610 has been certified for legal-for-trade applications including:

- NCWM/NTEP (National Conference On Weights and Measure)
- **OIML R129** (International Organization of Legal Metrology)
- MID (Measuring Instruments Directive)
- Measurement Canada

A certification label is applied to the top of the DM3610, and in some cases another is mounted on a steel plate on the mounting structure.



Figure 9: Certification Labels on DM3610 and displayed remotely



Certification Sealing

The DM3610 Dimensioner may require sealing in legal-for-trade applications. Specific sealing requirements vary based on national laws. In some cases, a paper or wire tamper-proof seal is applied across the seam in the DM3610 housing. These seals may be applied after certification by a field inspector or, in some cases, at the factory. Examples of these types of seals are shown below.

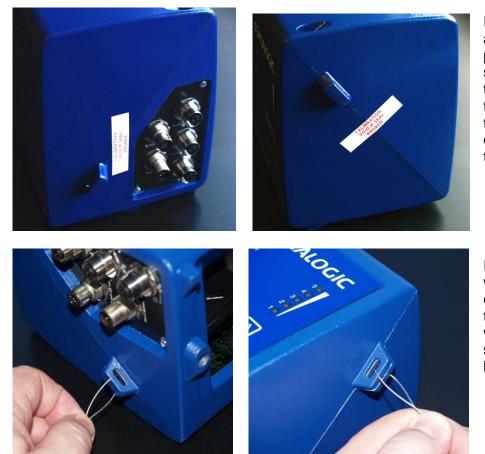


Figure 10: Sealing the DM3610 housing

If required, adhesive-backed, paper tamper-proof seals may bridge the seam between the two halves of the housing, on opposite sides of the device.

If required, two wire tamper seals can be placed through the tamper wire holes on each side of the device housing.

1.5 DATALOGIC PHOTOELECTRIC SENSOR

The optional **Datalogic Photoelectric Sensor** is used in DM3610 system to detect the presence of an item in the dimensioning area.

The photoelectric sensor is used in singulated systems where the packages are separated by an open space between the trailing edge of one package and the leading edge of the next. The photoelectric sensor enables a programmable transmit point at a defined distance from the sensor. Without the photoelectric sensor, the DM3610 can be run in continuous trigger mode (see **Modify Settings | Tach/Trigger/Transmit** in chapter 4).

Depending on the application, these devices may need to be configured differently. While the photoelectric sensor and tachometer work well with belt conveyors, a special configuration is needed for tilt-tray and cross-belt sorter applications.



Figure 11: Photoelectric Sensors

1.6 TACHOMETER

The tachometer provides a continuous pulse to the system, which provides feedback on conveyor speed and can be used to help track the package position along the length of the conveyor. A tachometer is required for certified systems, but is optional for non-certified. For non-certified systems, an internal *tach* signal can often be used.



Figure 12: Tachometer, Mounting Bracket, and Cable

1.7 CBX INDUSTRIAL CONNECTION BOX

CBX Series are industrial connection boxes that can be used to connect the DM3610 to the external display, tachometer, photoelectric sensor, serial devices, relays, or other peripherals. The CBX100 All-in-One includes a BM100 backup module, which allows easy parameter restore and backup operations to and from the DM3610. The backup module also provides an easy way to upload existing parameters to a replacement DM3610 when necessary. (See chapter 5, Dimensioning Features.)



Figure 13: CBX100 Industrial Connection Box

1.8 REMOTE DISPLAY

In all legal-for-trade applications, the DM3610 certified dimensioning system is required to have at least one remote display per site for inspection purposes. The number of displays required per site vary according to certification type.

The Datalogic GP018 Remote Display is a 2 line x 20 character vacuum fluorescent display. The display shows the dimensions for the most recent two boxes (with the most recent box on the lower line). The display shows:



Figure 14: Dedicated Remote Display

Legend:

BOX displays box number (0 to 9)
L displays longest horizontal dimension (length)
W displays shortest horizontal dimension (width)
H displays height
UNITS displays Metric (mm) or Imperial (in) dimension units used

1.9 CALIBRATION BOXES

The DM3610 system requires at least one set of calibration boxes, which aid in system setup and calibration. Two boxes and two margin spacers come with the system in calibration kits in your choice of Metric or Imperial configuration and in the following sizes:

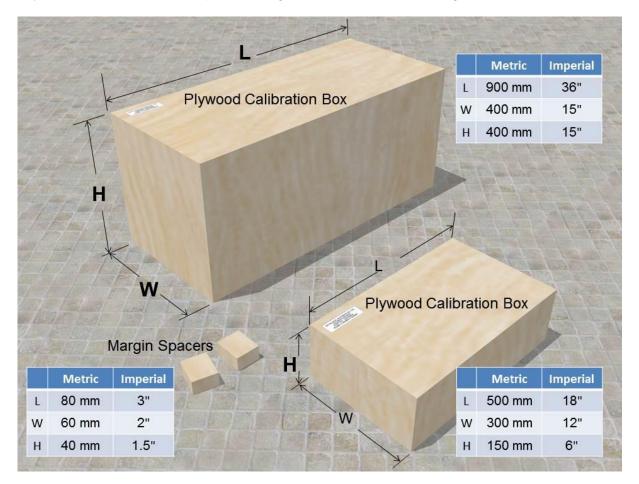


Figure 15: Calibration Kit

For information on using this kit for calibration, see Dimensioner Calibration in chapter 5.

2 MECHANICAL INSTALLATION



WARNING: Electrical Installation by Qualified Service Technicians Only! Procedures may involve exposure to high-voltage. A trained and authorized technician must perform these procedures. Do not attempt to perform any electrical installation procedures unless you are a trained technician.



IMPORTANT: The DM3610 contains electronics that may be affected by electrostatic discharge (ESD). To prevent personal injury or damage to the unit, please follow the safety precautions and warnings found in the *References* section at the beginning of this manual. Failure to follow these precautions may void your warranty.

2.1 PREPARING FOR MECHANICAL INSTALLION



IMPORTANT: Application-specific drawings and documents provided by Datalogic supersede any contradictory content in this manual.

Before mounting any components, please do the following:

- Read all instructions before beginning your installation.
- Define and confirm the accuracy of your application's requirements and structure position, especially the height of the conveyor from the floor.
- Review all installation-specific drawings provided with your equipment.
- Review and plan the mechanical installation of all devices used in your application. Be sure to allow adequate clearance for maintenance.
- Review and plan the power requirements for your application.
- · Check the contents of the shipping cartons against the packing list.
- Record all product serial numbers.



NOTE: Refer to the Reference Documentation for details on connecting your DM3610 dimensioner to other devices in the system.

2.2 UNPACKING INSTRUCTIONS

Verify that the DM3610 dimensioner and all the parts supplied with the equipment are present and intact when opening the separate DM3610 and mounting bracket packaging (2 boxes); the list of parts includes:

Box #1:

2

• DM3610 dimensioner and mounting screws

Box #2

- Universal Mounting Bracket (UMB)
- UMB Mounting Plate (attached to UMB)
- UMB Mounting Disk and screws



IMPORTANT: The DM3610 packaging is designed to protect the unit(s) during shipment. Do not throw the packaging away. Save all packing material in case you need to transport your unit(s).



Figure 16: DM3610 and UMB Package Contents

2.3 INSTALLATION SEQUENCE(S)



NOTE: Everything should be **MECHANICALLY INSTALLED** before performing any **ELECTRICAL INSTALLATION**. See *chapter 3* for electrical installation details.

To complete mechanical installation and setup, you must:

- Review the details of your application's requirements
- Erect mounting structure or other supporting structures
- Determine and mark the Universal Mounting Bracket (UMB) location
- Mount the UMB Mounting Plate to the UMB (if not already installed)
- Mount the UMB to the mounting structure
- Mount the DM3610 to the UMB
- Mount the photoelectric sensor to the mounting structure (optional)
- Mount the tachometer to the mounting structure (optional)
- Mount the Remote Display to the mounting structure (required for Legal-for-Trade installations, dependent on requirements)
- Mount the CBX100 connection box to the mounting structure (See section 2.5.12)
- Complete electrical installation (See chapter 3)
- Align the DM3610 for proper operation
- Calibrate the DM3610 (See chapter 5)
- Configure the DM3610 (See chapter 4)
- Check DM3610 operations (See chapter 5)

2.4 WHAT YOU NEED TO KNOW ABOUT YOUR APPLICATION

To assure you get optimal performance out of your DM3610 Dimensioning System, it must be installed to meet the complete needs of your application. Therefore, take the time to know the details of your application. The better you know your application, the easier it is to apply the DM3610's capabilities to meet your application's requirements.

Below is what you will need to know before you can begin installation:

• Conveyor Specifications

2

- Conveyor type: Belt, tilt-tray, cross belt, other?
- What is the conveyor width?
- What is the conveyor speed?
- Does conveyor speed vary or is it constant?
- Will bar code scanning also take place?
- Where is the dimensioning area to be located on your conveyor?

• Product and Dimensioning Specifications

- Are the packages being transported always singulated (not touching) or nonsingulated (possibly touching)?
- Are products always cuboidal (box shaped), non-cuboidal (irregular shaped) or is there a mixture of both?
- o Is side-by-side object dimensioning (non-singulated) required?
- How many different product sizes may be involved?
- Are products justified: toward/away from dimensioner/reader, centered, or variable?

• Application Specifications

- What will be done with the dimensioning information?
- How will this information be used in your application?
- What are your communication requirements?

While it is nearly impossible to cover all application configurations, the next several pages provide the basics on determining how to mechanically install your DM3610. If you need additional assistance, feel free to contact your sales representative or customer service.

2.5 MECHANICAL INSTALLATION

Because the DM3610 is a measuring device, calibration and proper usage of this device are necessary for proper operation. The DM3610 is shipped from Datalogic calibrated. It is therefore essential that the unit be mounted exactly as detailed on that drawing to retain proper calibration. The critical parameters are:

- Minimal vibration of unit on mounting structure any movement of the DM3610 due to vibration/swaying of the mounting structure will directly impact the dimensioning accuracy.
- Mounting height above the conveyor.
- The DM3610 scan line must be perpendicular to conveyor travel.
- If used, the photoelectric sensor's beam path must be parallel to the DM3610 scan line.
- Tachometer assembly mounted on the same conveyor belt that the DM3610 scan line is on, to insure proper speed indication
- The DM3610 scan line should be located at least 7 8 cm [3 inches] away from any other scan pattern on the conveyor belt, to eliminate the possibility of reflections interfering with dimensioning accuracy.

2.5.1 Dimensions and Clearances

The overall dimensions of the DM3610 are provided in *section 2.5.6 and chapter 8, Technical Features.*

The DM3610 is a sealed, unventilated unit. Mounting the unit with 300 mm [12"] of clearance (front, top, and sides) is recommended for ease-of-access and cooling.



IMPORTANT: For installation, maintenance and service reasons, approximately 300 mm [12 inches] of clearance is recommended.

2.5.2 Physical Support Requirements

For details on the weight of the DM3610, *see chapter 8, Technical Features*. Multiple-head systems may include further details on the physical support requirements with any application-specific documentation provided.

2.5.3 Vibration Limitations

The DM3610 is designed and tested to withstand continuous sine wave vibrations between 10 and 500 hertz (limited to a displacement of 0.40 mm [0.0157 inches] for frequencies between 10 and 50 Hz and limited to 2 G acceleration for frequencies between 50 and 500 Hz).

2.5.4 General Mounting Guidelines

It is important that you follow these general precautions when installing, setting up, operating, maintaining, troubleshooting, or replacing any Datalogic products, parts or related equipment.



CAUTION: The DM3610 uses a visible laser diode (red) 658nm, Collimated < 1.5mR, <9.6mW peak power, <1.0mW Average power, Class 3R (IEC60825-1), Class II (CDRH 21CFR1040), in the dimensioning process. Avoid staring at the laser light source. While laser light does not constitute a health hazard, staring at the laser for prolonged periods could result in eye damage.

As you plan and install your DM3610 dimensioning system application, be sure to keep the following guidelines in mind:

- All mounting structure assembly and equipment installation can be performed by one installer.
- Determine the proper orientation and position of the DM3610.
- Leave adequate clearances (approximately 300 mm [12 inches]) for wiring.
- Route wires carefully to reduce or minimize electrical noise. When power and communication wiring must cross, make their intersection perpendicular.
- Proper grounding limits the effects of noise due to Electromagnetic Interference (EMI).

2.5.5 Conveyor Considerations

In the process of dimensioning a package, the DM3610 is measuring the distance between the package and itself. Therefore, any motion of the package other than that in the conveyor direction will impact dimensioning accuracy. Consider the following:

- Make sure the DM3610 is mounted at least 300 mm [12 inches] plus the longest box away from any belt transitions. This applies to both packages entering and leaving the system. This means the DM3610 requires a conveyor belt length of at least 600 mm [24 inches] plus twice the longest box to ensure box stability under the system.
- The DM3610 should be placed so packages are not sliding, tumbling, or accelerating/decelerating when they pass under the scan line.
- Belt seams that elevate packages above the normal belt surface will impact dimensioning accuracy.

2.5.6 Mounting Structure Considerations

Your first task is to mount your DM3610 unit. You can provide your own mounting structure or Datalogic can design one for you. We recommend using a Datalogic mounting structure for standard applications.

Your mounting structure must provide the following capabilities:

- It is adjustable enough for you to move your DM3610 unit to the optimum position for proper dimensioning.
- It is able to hold 16 kg [36 lbs] (three times the weight of the DM3610).
- It allows a technician access to the DM3610 while it is mounted.
- It must be as vibration free as possible so as not to affect the dimensioning accuracy.
- It is constructed of steel or aluminum.
- It provides approximately 300 mm [12 inches] minimum clearance on all sides. This clearance is necessary to provide proper ventilation, allow access to all panels of the DM3610, and allow room for proper servicing.

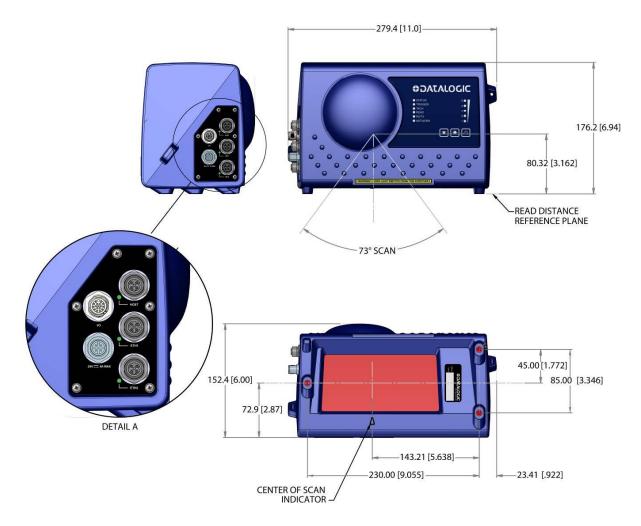


Figure 17: DM3610 Dimensions

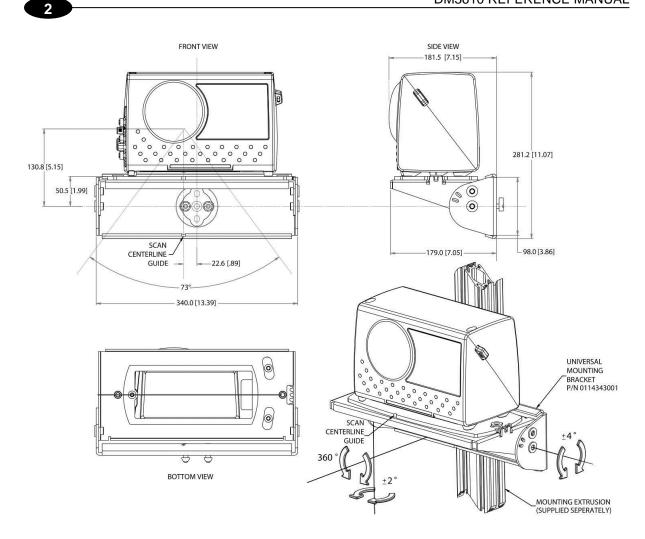


Figure 18: DM3610 Mounting Dimensions with UMB

2.5.7 Mounting the Dimensioner with the Universal Mounting Bracket (UMB)

The Universal Mounting Bracket (UMB) allows you to install and make fine adjustments to the position of the DM3610. The bracket assembly includes the UMB, UMB Mounting Plate, and UMB Mounting Disk.

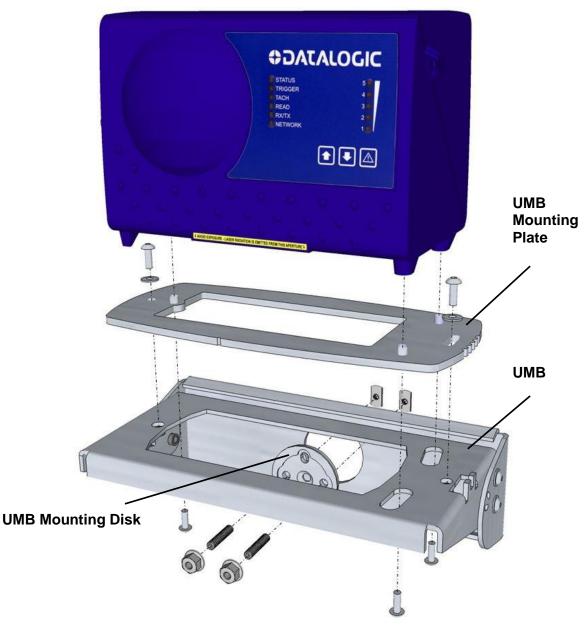


Figure 19: DM3610 and UMB Assembly

- 1. Mount the **UMB Mounting Plate** to the **UMB**, if it has not yet been attached.
- 2. Mount the **UMB** to the mounting structure using the **UMB Mounting Disk** and hardware provided. Hardware is provided for standard Bosch or 80/20 mounting structure extrusion.
- 3. Mount the DM3610 to the UMB Mounting Plate and UMB.

2.5.8 Typical Installation Considerations

You must mount the following components of the DM3610 system before you power it on:

- DM3610
- CBX100 Connection Box
- Tachometer (if used)
- Photoelectric Sensor (if used)



2

NOTE: A photoelectric sensor is typically used for DM3610 singulated, non-touching applications. The photoelectric sensor is an object-sensing trigger device. A tachometer is used to measure conveyor speed. (*Your installation may use other devices.*)

A photoelectric sensor is not required for DM3610 applications unless your system requires a defined transmit point.

All DM3610 series dimensioning units must always be mounted above the conveyor. The following diagrams show different views of a typical system installation. They give you an idea of what your system will look like when you mount all your components.

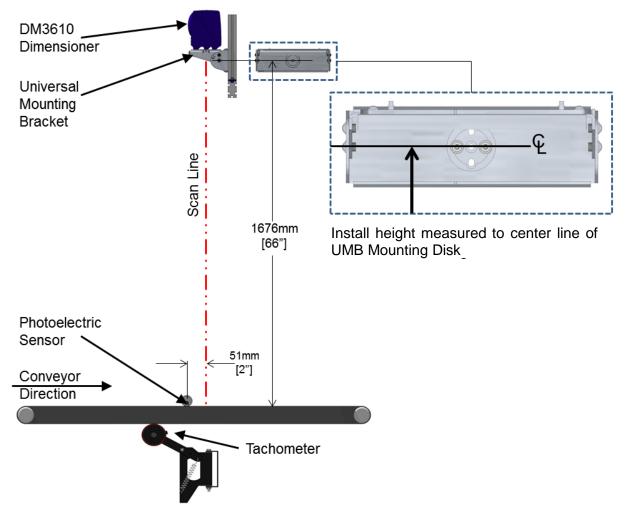


Figure 20: DM3610 Mounting Dimensions – SIDE VIEW

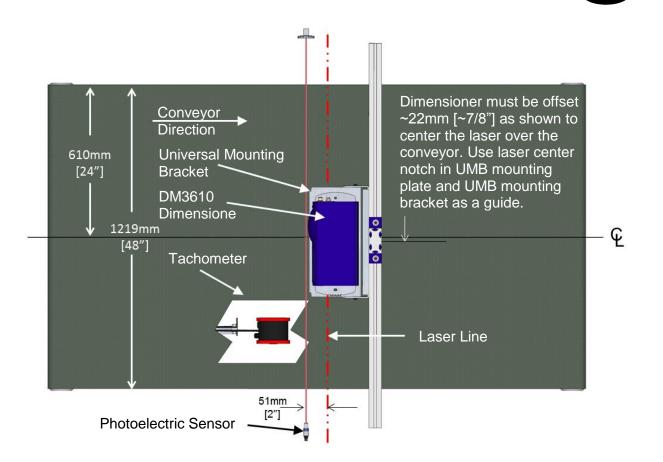


Figure 21: DM3610 Dimensioning System Installation - TOP VIEW

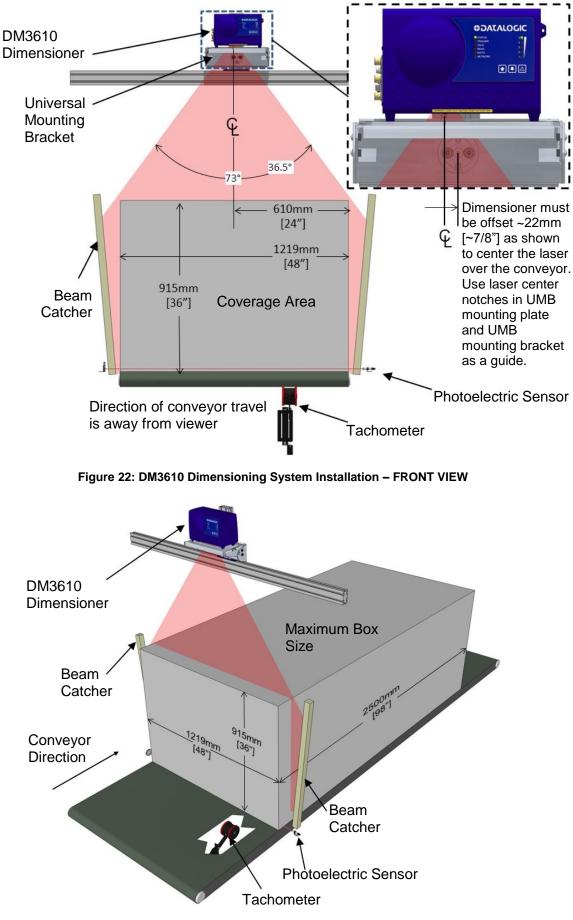


Figure 23: DM3610 Dimensioning System Installation – 3 QUARTER VIEW

2.5.9 Mounting Structure Assembly

When using the standard mounting structure provided by Datalogic, assemble as defined in the application information provided with the structure.



NOTE: This manual addresses standard DM3610 installation. The information provided here may be superseded by any application specific drawings provided by Datalogic.



NOTE: Depending on your specific installation, beam catchers may be needed to avoid false dimensioning data points (See Figure 22).

2.5.10 Prepare the Mounting Structure and Universal Mounting Bracket

1. In standard installations, the DM3610 Universal Mounting Bracket (UMB) is mounted to a short upright mounting support (from mounting structure extrusion). Install the mounting support approximately centered over the conveyor belt as shown below.

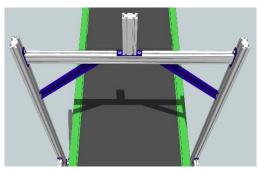


Figure 24: Center the Upright Mounting Support

2. Using a tape measure and marker or pencil, make an installation mark on the upright at 1680mm [approx. 66"] above the conveyor surface, as shown below. This measurement is used for positioning the Universal Mounting Bracket (UMB). The final height of the base of the DM3610 will be 51mm [2"] higher than this point.

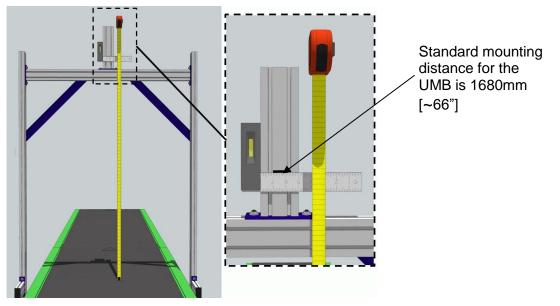


Figure 25: UMB positioning mark

3. If the UMB Mounting Plate is not yet attached to the UMB, attach it now with the screws provided.

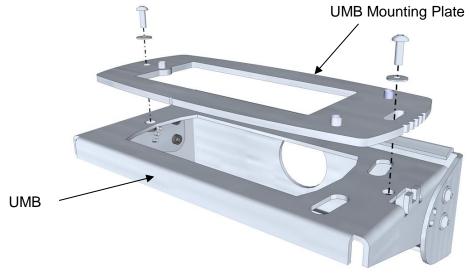


Figure 26: UMB Mounting Plate to UMB Assembly

2.5.11 Mounting the UMB and DM3610

1. The UMB is fastened to the mounting structure with the UMB Mounting Disk, threaded inserts, set screws, and matching nuts. Place the threaded inserts into the mounting extrusion tracks one at a time and secure them at the mounting mark with the set screws provided.

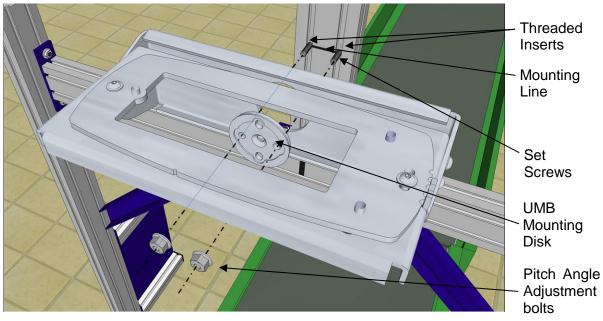


Figure 27: Securing the UMB to the structure

2. Adjust the UMB so that the installation mark is at the center slot of the UMB Mounting Disk.

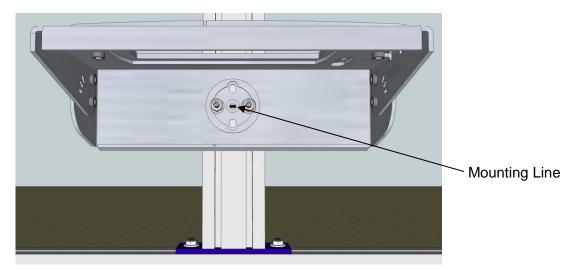


Figure 28: Aligning the UMB with the installation mark



NOTE: DO NOT over-tighten hardware that holds the UMB in-place.

3. Set the DM3610 dimensioner on top of the UMB assembly, placing the feet of the DM3610 over the positioning posts on the UMB Mounting Plate.

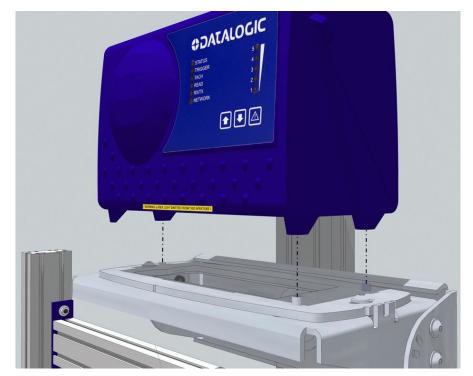


Figure 29: Placing the DM3610 on the positioning posts of the UMB Mounting Plate

4. Secure the DM3610 with the three mounting screws provided. The mounting screws pass through the positioning posts and into the feet of the DM3610.

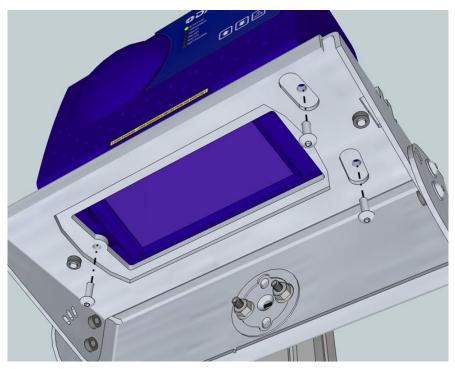


Figure 30: Securing the DM3610



NOTE: When viewing from conveyor downstream, in standard configuration the connector panel will be facing to the RIGHT side of the conveyor.

2.5.12 Mounting the CBX Connection Box

CBX Series industrial connection boxes can be used to connect the DM3610 to the external display or other peripherals.



Figure 31: CBX100 Connection Box

The CBX100 All-in-One includes a BM100 backup module, which allows parameters to be downloaded from the DM3610. The backup module provides an easy way to upload existing parameters to a replacement DM3610 when necessary. The BM100 is only required if local parameter backup is desired. (See chapter 5, Dimensioning Features)

Mount the CBX100 to the mounting structure in a location to facilitate easy access to wiring. Secure the CBX100 with the bolts and drop-in T-nuts provided.

When mounting CBX100 to a fixed surface, the stencil include in the package can be used to drill the appropriate mounting holes.

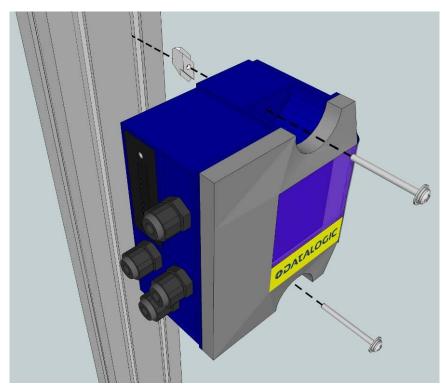


Figure 32: Securing the CBX100 using the 80/20 Mounting Kit

2

2.5.13 Mounting the Datalogic Photoelectric Sensor

The standard DM3610 hardware trigger is a Datalogic photoelectric sensor. It works by emitting a light beam that is returned by a simple reflector. When a package breaks the path of light, the trigger signal is activated.

In order for photoelectric sensor to work properly, make sure the following things are done when mounting the trigger photoelectric sensor.

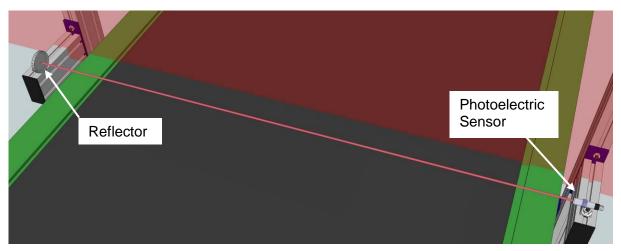


Figure 33: Mounting the Photoelectric Sensor



NOTE: Mounting supports may differ from the extrusion shown in the image above.

• Mount the photoelectric sensor so it is parallel to and 50 to 150mm [2 to 6] inches upstream from the DM3610 laser.



NOTE: The distance from the photoelectric sensor to the DM3610 laser line must be entered in the **Modify Settings | Tach/Trigger/Transmit** window of the User Interface in the **Trigger Reference Point** text field. See chapter 4, User Interface.

- Mount the reflector directly opposite the emitter on the other side of the conveyor.
- The emitter must be mounted so the light exit window is perpendicular to the conveyor, facing the reflector.
- Mount the reflector perpendicular to the conveyor, facing the emitter.

2.5.14 Mounting the Tachometer

The tachometer (tach) outputs a set number of pulses for each wheel rotation. This tells the DM3610 the precise conveyor speed, allowing it to determine the exact package position. Because the exact layout of many conveyors is unique, it is impossible to give exact directions for tachometer mounting. Follow the guidelines below as closely as possible:

- Mount tach on the conveyor section where dimensioning is performed.
- Mount tach on the underside of the conveyor, away from areas where the conveyor bows downward. A good place to mount the tach is on one end of the conveyor, close to the drive shaft.
- Make sure tach assembly angles in the same direction that the underside of the conveyor travels.
- The tach must make good contact with the conveyor.
- The anti-static brush provided with the tach must be installed to assure proper operation.
- Use the tachometer mounting kit to make tachometer mounting and setup easier.

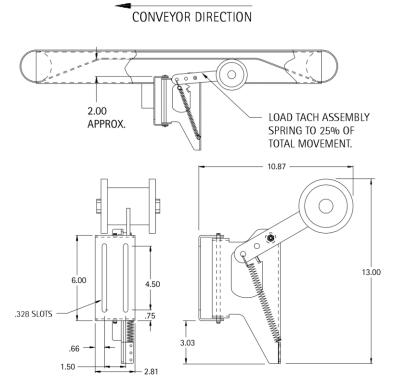


Figure 34: Tachometer Mounting Kit Installation

2.5.15 Mounting the Remote Display

The remote display should be mounted for easy visibility. It is used to display DM3610 certification mode data (box length, width, height) in both inches and centimeters. Interconnections to the DM3610 are covered in *chapter 3, Electrical Installation.*



Figure 35: Datalogic GP018 40 Character Remote Display

2.5.16 Mounting the Power Supply

Mount the power supply in a location on the structure where its cables can reach both the DM3610 and a power source. Secure the power supply to the mounting structure using the supplied hex screws and drop-in T-nuts as shown below.

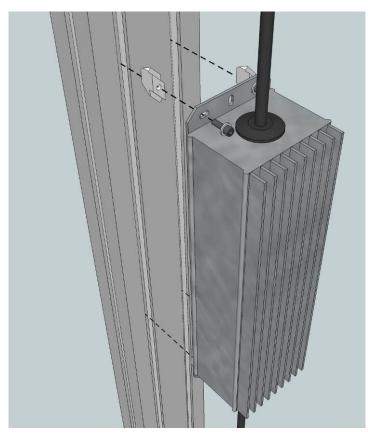


Figure 36: Securing the power supply to the mounting structure.

2.5.17 Connect Communication and Power Cables to the Installation



WARNING: DO NOT connect the power supply to a power source until after all wiring connections have been made to the DM3610 and CBX100.

Connect all communication cabling for the DM3610 system as explained in *chapter 3, Electrical Installation*, including:

• Communications and power supply connections to the DM3610



Figure 37: Connections to the DM3610 Connector Panel

- Connections to the CBX100 connection box
 - Connections to a photoelectric sensor
 - Connections to a tachometer
 - Connections to a remote display
 - Serial communication (if used)

After the communications cables have been connected, connect the power supply cable to the DM3610, and then attach the power supply to a power source.



NOTE: For information on setting up network or serial communication parameters, see *chapter 4, User Interface*.

2.6 ALIGNING DM3610 DIMENSIONING SYSTEM

For the DM3610 to function properly and provide accurate dimensioning information, the unit must be carefully aligned.

2.6.1 Centering the Dimensioner

Laser center marks on the UMB, UMB Mounting Plate, and underside of the DM3610 help you align the laser over the center of the conveyor.

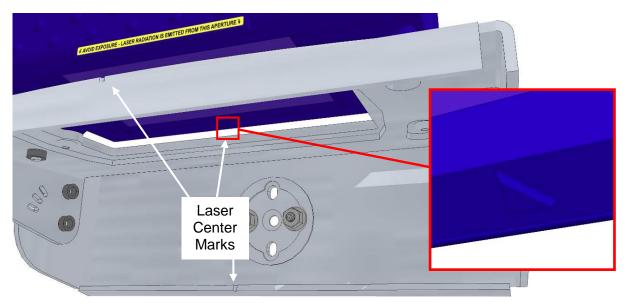


Figure 38: Laser Center Marks

Center the dimensioner over the conveyor:

- 1. If the mounting structure is exactly centered over the conveyor, you can measure and mark the center of the mounting structure cross piece. If the structure is not centered, you may need to drop a plumb bob from the laser center notch in the UMB to the conveyor to align with the center of the conveyor.
- 2. Slightly loosen the nuts securing the mounting structure upright.

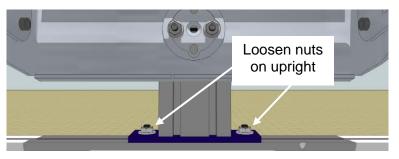


Figure 39: Laser Center Marks

- 5. Align the laser center marks on the UMB or DM3610 with the center mark on the mounting structure cross piece or the center of the conveyor by sliding the upright along the mounting structure cross piece.
- 6. Retighten the nuts securing the uprights when the laser center marks have been aligned with the center of the conveyor.

2.6.2 Adjusting the Pitch

2

- 1. Using a bubble level or angle meter to determine the angle of the conveyor surface.
- 2. Adjust the UMB so the DM3610 is set to the same angle as (parallel to) the conveyor. This will allow the DM3610 to report the same dimensions whether the box is sent down the left or right side of the conveyor. This will be confirmed in a step later on in this document.



Figure 40: Adjusting the Pitch

3. Slightly loosen the nuts on the UMB Mounting Disk on the UMB to adjust the pitch angle.



NOTE: Take care to only loosen the nuts and not the two set screws that anchor the UMB to the mounting structure

2.6.3 Adjusting the Tilt

- 1. With the DM3610 powered up and the laser active, set the largest test box (see Calibration Kit in *chapter 1, Introduction*) perpendicular to the conveyor with its edge even with the edge of the conveyor.
- 2. While keeping the test box aligned with the conveyor, adjust its position until the laser is just touching the edge of the box. The goal is to adjust the alignment of the DM3610 until the laser is parallel to the edge of the test box.

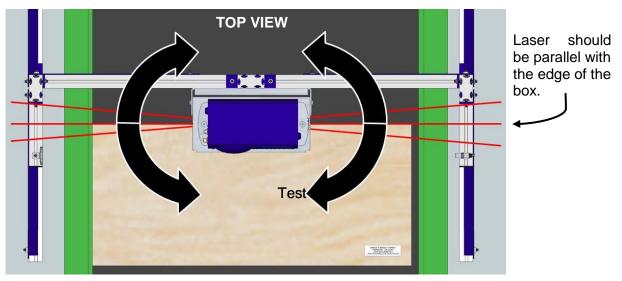


Figure 41: Adjusting the Tilt

3. To adjust the laser tilt, loosen the screws securing the UMB Mounting Plate to the UMB and using a flathead screwdriver carefully pry the plate back and forth until the laser is exactly parallel to the edge of the test box. When adjusted correctly, tighten the UMB Mounting Play screws.

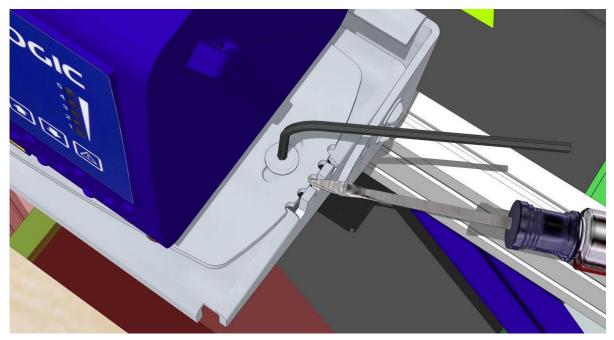


Figure 42: Adjusting UMB Mounting Plate with a Screwdriver

2.6.4 Adjusting the Skew

2

To adjust the laser skew, loosen the screws securing the front of the UMB to its back and use a flathead screwdriver to carefully pry the front of the UMB up and down using the adjustment slots until the laser is exactly 90° to the conveyor. Again, use the edge of the box as a guide. When adjusted correctly, tighten the UMB screws.

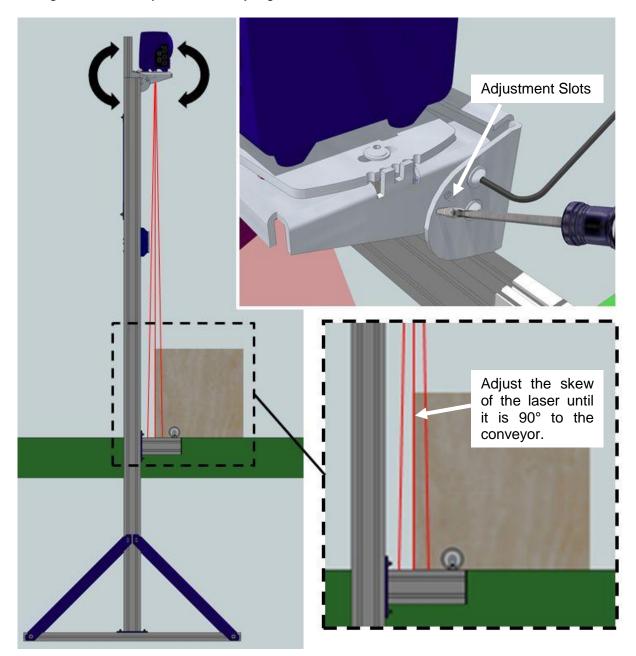


Figure 43: Adjusting the Skew

2.6.5 Adjust Photoelectric Sensor Alignment

With the DM3610 laser aligned, measure the distance from the photo sensor to the DM3610 scan line. Enter the distance into the **Trigger Reference Point** parameter field in the DM3610 User Interface (see chapter 4, User Interface). The photoelectric sensor should be set up 50 to 150mm [2 to 6"] from the DM3610 laser line.

2.7 CALIBRATION AND SETUP

After the DM3610 dimensioning system has been installed, it must be calibrated and configured for precise package dimensioning. See *chapter 5, Dimensioning Features* for complete procedures for calibrating your system.

3 ELECTRICAL INSTALLATION



WARNING: Electrical Installation must be performed by a Qualified Service Technicians Only! A trained technician must perform any procedures involving potential exposure to high voltage electricity. Do not attempt to perform any electrical installation procedures unless you are a trained technician.



IMPORTANT: The DM3610 contains electronics that may be affected by electrostatic discharge (ESD). To prevent personal injury or damage to the unit, please follow the safety precautions and warnings found in the Introduction to this manual. Failure to follow these precautions may void your warranty.

3.1 PREPARING FOR ELECTRICAL INSTALLATION

Before mounting any components, please do the following:

- Read all instructions before beginning your installation.
- Observe all electrical safety requirements discussed in the Introduction to this manual.
- Define and confirm the accuracy of your application's requirements.
- Review all installation-specific drawings.
- Review and plan the power requirements for your application.
- Review and plan the communications requirements for your application.



IMPORTANT: The content of this manual may be superseded by any customer-specific documentation provided by Datalogic. Before proceeding with any installation procedures, be sure to review ALL documentation, especially content that contains details specific to your installation.

3.2 INSTALLATION SEQUENCE



NOTE: Everything should be **MECHANICALLY INSTALLED** before performing any **ELECTRICAL INSTALLATION**. See chapter 2 for mechanical installation details.

Most DM3610 applications are shipped with the CBX100 connection box and all the necessary cabling required to electrically install the system. If your system requires custom-length cables or other special wiring, documentation specific to these requirements has been provided in your shipment. This special documentation supersedes any contradictory content in this manual.



NOTE: To reduce the possibility of damage to the unit, check all cabling between the DM3610 and other devices for accuracy.

3.2.1 Connecting a DM3610-1000/1100/1200/1300 Singulated, non-touching

To install a DM3610 Dimensioner, follow this sequence:

- Complete mechanical installation (See chapter 2.)
- Complete electrical installation. (See wiring illustrations provided in this chapter.)
- Observe all electrical safety requirements outlined in this chapter.
- Ground the mounting structure to protective earth (PE) ground.
- If used, wire the photoelectric sensor (or other trigger) to the CBX100.
- Wire the tachometer to the CBX100 (if used).
- Wire serial ports to the CBX100 if needed.
- Connect the M12 end of the Ethernet cable to the DM3610 HOST port and network switch as required by your application.
- Wire the Remote Display to the CBX100 (if used).
- Connect the DM3610 to its power supply.
- Connect the power supply to the power source.
- Setup / check DM3610 operations (See chapter 5.)

3.2.2 Connecting a DM3610-2100/2200 Non-Singulated, touching

[Details on DM3610-2100, 2200 installation were not available at time of publication.]

3.2.3 Connecting a DM3610-3100/3200 Irregular System

[Details on DM3610-3100, 3200 installation were not available at time of publication.]

3.3 GENERAL ELECTRICAL INSTALLATION GUIDELINES AND PRECAUTIONS

It is important that you follow these general precautions when installing, setting up, operating, maintaining, troubleshooting or replacing any Datalogic products, parts or related equipment. As you plan and install your DM3610, be sure to keep the following guidelines in mind:

- Determine the DM3610 is in the proper location as outlined in *chapter 2*.
- Leave adequate clearances (approximately 200-300 mm [8-12 inches]) for wiring.
- Route wires carefully to reduce or minimize electrical noise.
- When power and communication wiring must cross, make their intersection perpendicular. Avoid running power and data wiring parallel to each other. If possible, maintain one of the following separations between the power and data wiring:
 - 300 mm [12 inch] gap
 - o use steel conduit and 25 mm [1 inch] gap
 - 6.5 mm [0.25 inch] of aluminum.



IMPORTANT: When planning your installation wiring, remember all power connections must be quick-disconnect. For **PERMANENTLY CONNECTED EQUIPMENT** a readily accessible disconnect device must be incorporated in the building installation wiring. For **PLUGGABLE EQUIPMENT** the socket-outlet must be installed near the equipment and must be easily accessible.



WARNING: To assure no ESD damage will occur, be sure to observe the precautions outlined in the Introduction to this manual.



IMPORTANT: Ground the mounting structure to safety ground (protective earth ground (PE)). See wiring recommendations for safety ground.

3.4 DM3610 CONNECTOR PANEL

After completing mechanical installation, use this section to properly wire your DM3610 for optimal performance in your application. DM3610 wiring connections are made to the connector panel and through the CBX100 connection box (connected to the I/O port of the DM3610). In most dimensioning applications, the cable connections to the DM3610 will include:

- 1. I/O (Connects directly to the 25-pin D type connector on the CBX100)
- 2. POWER 24V --- 4A MAX (Power)
- 3. HOST (Host Computer)
- 4. ETH 1 (Ethernet)
- 5. ETH 2 (Ethernet)



Figure 44: DM3610 Connector Panel

Route wiring to the DM3610's connector panel through the wiring channels (if available) on the Datalogic mounting structure when running interconnecting cables between other devices and the dimensioner.



Figure 45: Wiring Channels

3.5 POWER CONNECTOR PIN-OUT TABLE

A recommended power supply and cabling is available either as an accessory or included in the Dimensioning Solution kit. However, if your installation requires custom power supply wiring, the pin-outs of the unit power connector are provided below for your convenience.

24V 4A MAX		POWER INPUT	
		CONNECTOR (SHOWN)	MATING CONNECTOR
		5-PIN M12-TYPE MALE	5-PIN M12-TYPE FEMALE
MALE 5-PIN M12-TYPE	PIN	FUNCTION	
	1	+24 VDC	
	2	N/C	
	3	DC RETURN	
2-((000))-4	4	N/C	
3	5	PROTECTIVE EARTH (CHASSIS)	



NOTE: When using the DM3610 Dimensioner, no power supply is required for the CBX100 connection box. All power and some communication options are fed to the CBX100 through the DM3610's 17-pin I/O connector to the CBX100 25-pin connector.

3.6 POWER CONNECTIONS



IMPORTANT: When planning your installation wiring, remember all power connections must be quick-disconnect.

CAUTION: While performing the following wiring connection procedures, be sure to follow all safety procedures regarding high-voltage as outlined in the Introduction to this manual. No power should be applied to any device until all wiring is completed and checked for accuracy.



IMPORTANT: The socket-outlet must be installed near the DM3610. The outlet must be a readily accessible disconnect device.



Ground the DM3610 to safety ground (protective earth ground (PE)). See wiring recommendations for safety ground.

The CBX100 connection box provides flexible connectivity to a range of I/O devices as well as serial hosting. The DM3610 connects to the CBX100 via its I/O port using a single 17-pin M12 to 25-pin D cable. The CBX100 also provides space for an optional BM100 backup module (recommended) for parameter storage, allowing quick replacement and configuration of the DM3610.

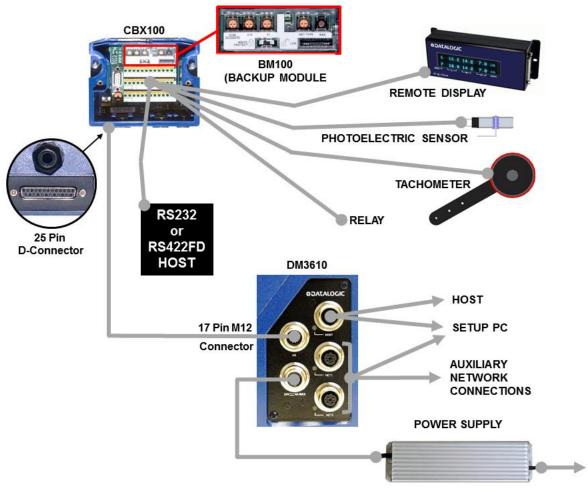


Figure 46: Wiring Block Diagram

3.7 CBX100 CONNECTION BOX INITIAL CONFIGURATION

Complete installation information is available in the *CBX100 Installation Manual* available at <u>www.datalogic.com</u>. Please verify that the CBX100 connection box is configured for the DM3610 application as follows:

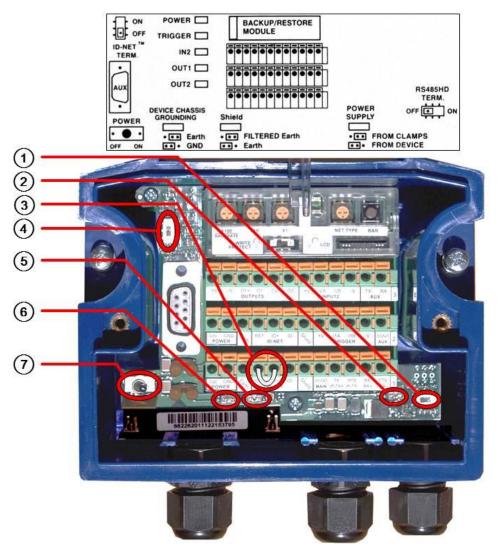


Figure 47: CBX100 Initial Setup

Reference the image and diagram above:

- 1. Set RS485HD TERM switch to OFF.
- 2. Set POWER SUPPLY jumper to FROM DEVICE.
- 3. Insert jumper wire in pin block from REF to ID+ (one jumper in either block is sufficient).



NOTE: This jumper indicates to the DM3610 that the CBX100 is connected. It also indicates that the DM3610 should supply 24VDC to the CBX100.

4. Set ID-NET TERM. switch to OFF.

- 5. Set Shield jumper to FILTERED Earth.
- 6. Set DEVICE CHASSIS GROUNDING to Earth.
- 7. Set POWER switch to ON.

3

3.8 CONNECTING A PC TO THE DM3610 HOST PORT

During initial setup, a PC (laptop) may be connected to the DM3610 with an M12 to RJ45 cable. Screw the M12 connector to the HOST port of the DM3610 and plug the RJ45 into the Ethernet port of your PC. If the HOST port is in use, ETH 1 or ETH 2 ports can be used. For information on connecting to the DM3610 User Interface, *see chapter 4.*

3.9 WIRING INTO THE CBX100 CONNECTION BOX



WARNING: DO NOT connect a separate power source to the CBX100 connection box. The CBX100 receives its power through its connection to the DM3610. Connecting a separate power source will be detrimental to the system operation.

As shown below, loose-lead cables must pass through the water-tight seals in the base of the CBX100 connection box. Insert the cables allowing enough slack for the individual wires to reach the appropriate pin block connectors. Securely tighten the water-tight seals after the cables have been inserted.

Insulation on individual wires should be removed to expose 13 mm [0.5 inch] of bare metal before inserting into the pin block.

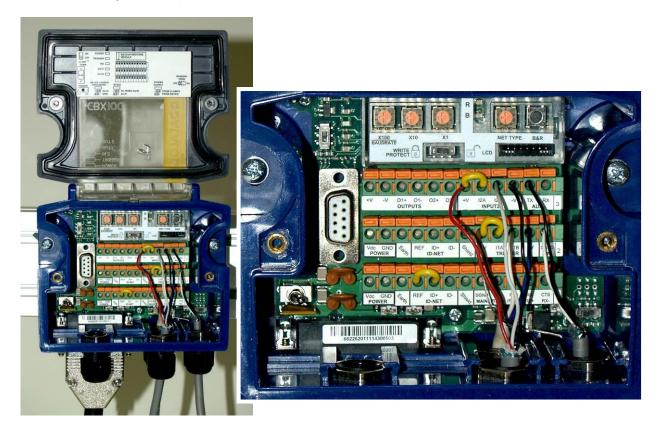


Figure 48: Securing wires with water-tight seals

3.10 PHOTOELECTRIC SENSOR CONNECTIONS

Standard DM3610 singulated applications may use a Datalogic photoelectric sensor as its trigger device. The photoelectric sensor is only required if dimension data is transmitted at a certain transmit point. The photoelectric sensor is wired directly into the CBX100.

If your application uses a trigger other than the one specified by Datalogic, follow the appropriate wiring diagram to assure proper wiring.



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IMPORTANT: You must use shielded interface cables with this product. To maintain FCC compliance, the cable shield must make a 360-degree connection to the shielded mating connector.



NOTE: To confirm the photoelectric sensor is functioning properly, watch the TRIG LED while the photoelectric sensor's beam is blocked. The Datalogic photoelectric sensor also includes a status LED.

3.10.1 Photoelectric Sensor Standard Wiring (NPN Output)

The following diagram illustrates standard/recommended wiring of the Photoelectric Sensor in a DM3610 application.

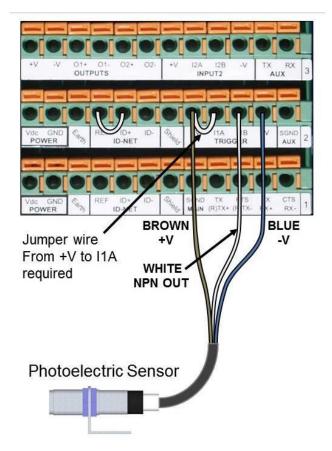


Figure 49: Photoelectric Sensor Wiring (NPN Output)

3.10.2 Photoelectric Sensor Wiring (PNP Output)

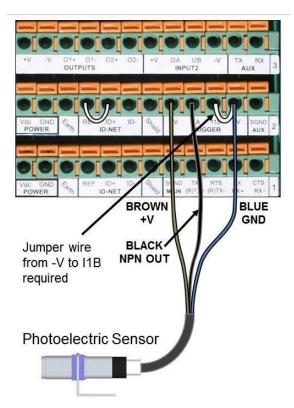


Figure 50: Photoelectric Sensor Wiring (PNP Output)

3.11 TACHOMETER WIRING

3

DM3610 applications over a conveyor belt use an accessory tachometer and mounting kit. Use the cable provided with the tachometer to connect to the CBX100 pin block as shown below.

3.11.1 Standard Tachometer Wiring (NPN Output)

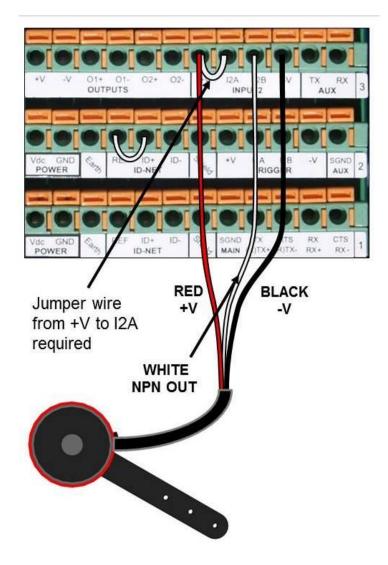


Figure 51: Tachometer Wiring (NPN Output)

3.11.2 Tachometer Wiring (PNP Output)

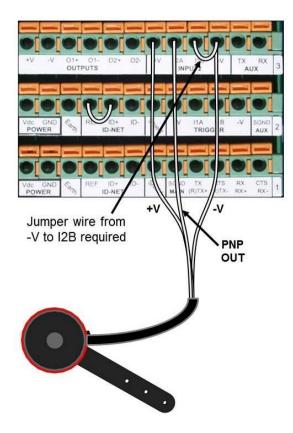


Figure 52: Tachometer Wiring (PNP Output)

3.12 REMOTE DISPLAY WIRING

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A Datalogic GP018 40-Character Remote Display is required for some certified dimensioning applications. The display is wired directly to the CBX100 pin block as shown below.

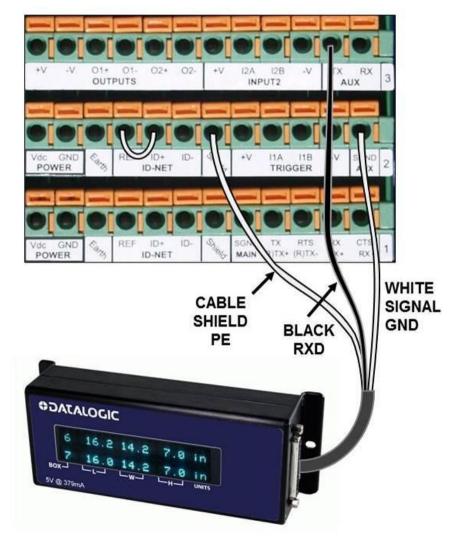


Figure 53: Remote Display Wiring

3.13 SERIAL COMMUNICATION WIRING

The DM3610 provides serial RS232/422 communications to other devices through the CBX100.

- RS232 provides point-to-point communications at distances up to 15 meters [50 feet].
- RS422 provides point-to-point communications at distances up to 1200 meters [3940 feet]

The following wiring diagrams illustrate the different types of serial communications available via the CBX100 pin block. It is very important that you make the proper pin connections.

3.13.1 RS232 with No Handshaking

Use RS232 for a direct connection to a controller, personal computer, or other device. RS232 provides point-to-point communications at distances up to 15 meters [50 feet]. If longer cable lengths are needed, use RS422.

Use the following illustration as a guide when you want to connect your DM3610 to a device using RS232 communication with no handshaking.

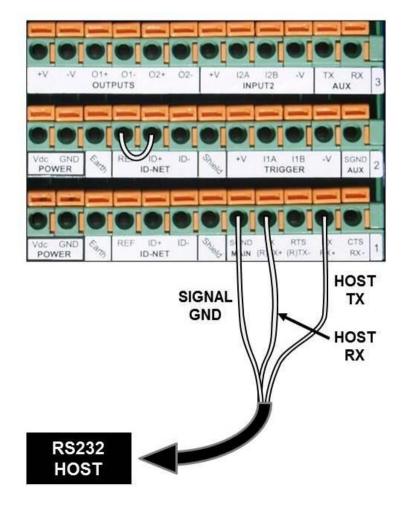


Figure 54: RS232 HOST (No Handshaking)

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3.13.2 RS422FD HOST (Full Duplex)

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Use RS422 for a direct connection to a controller, personal computer, or other device. RS422 provides point-to-point communications at distances up to 1200 meters [3940 feet]. Full duplex wiring supports a four wire, double twisted pair RxD/TxD. The Signal GND and shield cables are also required as shown.

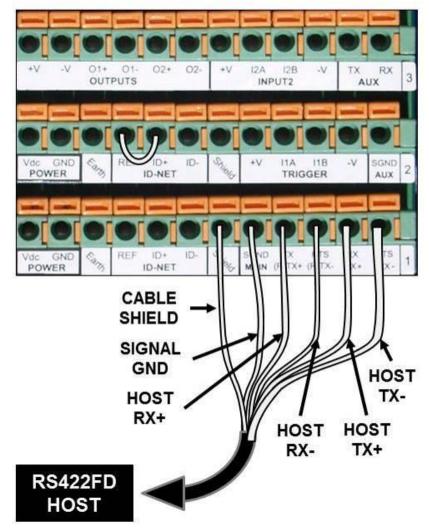
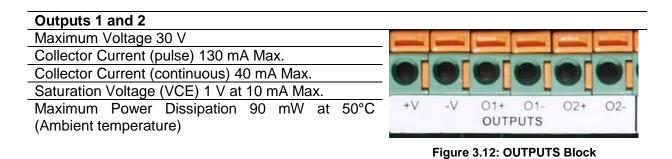


Figure 55: RS422FD HOST (Full Duplex)

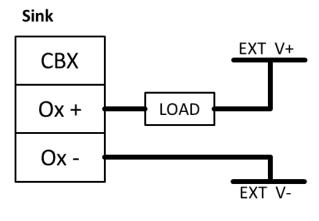
3.14 RELAY CONFIGURATION

The CBX100 includes an OUTPUTS block for wiring relays as needed for external accessories. The DM3610 User Interface Modify | Relays window includes options for outputs 1 and 2 including Life Light, Trigger Output, Error Light, Ready Light, Good Dim, and No Dim.

Schematics for Isolated and Non-Isolated relays are provided below.



3.14.1 Isolated Relay



Source

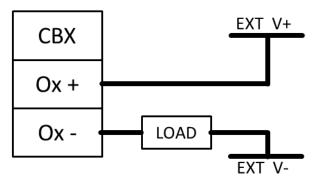
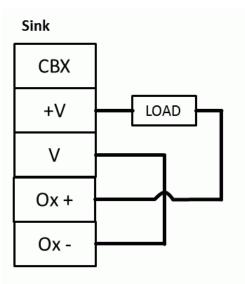


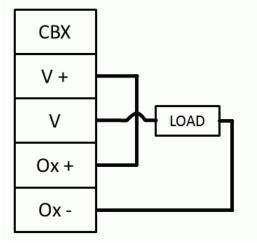
Figure 56: Isolated Relay Connection

3.14.2 Non-Isolated Relay

3



Source





3.15 CHECK DM3610 INSTALLATION

After completing the installation of your DM3610:

- Confirm that the DM3610 and CBX100 have been properly installed mechanically and electrically. Use the Installation Sequence at the beginning of this chapter and your application specifications to check your installation.
- All interconnections should match the drawing in *Appendix A* as is applicable to your system's configuration. (These drawings are superseded by any customer-specific documentation provided by Datalogic.)
- The next step is to configure the parameters to meet the needs of your application. Details on using the DM3610 User Interface are provided in *chapter 4*.

4 USER INTERFACE

4.1 GETTING STARTED

The DM3610 dimensioner is designed for ease-of-setup. The DM3610 User Interface is a browser-based application. It is the tool you will use to define operating parameters, monitor dimension quality, construct output messages, and view diagnostics. The DM3610 User Interface enables you to easily configure, fine-tune, and monitor your DM3610's operation.

The DM3610 User Interface provides ease-of-use for any operator level. A beginner operator follows basic setup procedures for a standard configuration. More experienced operators may use the advanced setup features that allow access to more complex options.

4.1.1 Prerequisites

Before setting up your DM3610 you will need the following:

Computer	Laptop
Browser	Internet Explorer 8 (or later) NOTE : Internet Explorer 10 (or later) is required to view Diagnostic DimView .

Firefox 18.0 (or later)

Chrome 24.0.1312 (or later)

Java	Version 7, Update 9 (or later)

4.1.2 Accessing the DM3610 User Interface

To access the DM3610 User Interface:

- 1. Connect your computer to the DM3610 HOST port using either the CAB-ETH-M0x M12-IP67 ETHERNET CABLE or CBL-1534-0.2 ADAPT.CABLE ETH M12-TO-RJ45F. If the HOST port is taken, ETH 1 or ETH 2 can be used.
- 2. Turn on your computer.
- If you are connecting to a stand-alone unit (not connected to an in-house network), you must configure your PC's IP Address to be in the same network as the DM3610's IP Address.

To change your PC's IP Address:

- a. From the desktop, click the Start button, and then select Control Panel.
- b. Type adapter in the search box, and then from the results, under Network and Sharing Center, click View network connections.
- c. Right-click Local Area Connection, and then select Properties.
- d. Select the Networking tab. Under This connection uses the following items, click Internet Protocol Version 4 (TCP/IPv4), and then click Properties.
- e. Select Use the following IP address.
- f. In the **IP address** field, type the first 3 octets of the IP address of the DM3610 unit.
- g. For the last octet, type a number that differs from the last octet in the DM3610's IP address. The actual number used is not important as long as it does not match that of the DM3610.

Example: If the DM3610 IP Address is 192.168.3.100, set your PC's IP Address to 192.168.3.101.

- h. In the Subnet mask field, type 255.255.255.0
- i. In the **Default gateway** field, type 0.0.0.0
- j. Click Okay.
- Open a web browser and enter the IP address for your DM3610 unit. If the correct IP address is entered, the DM3610 Login screen will appear (If you don't know the IP address, see IP Address Discovery.)

The default IP address for all DM3610 units is: 192.168.3.100

User ID		
Password		
Language	ENGLISH	•
	Log On	

- 5. Enter the **User ID** and **Password** for your system in the fields provided. The default User ID is "DM3610" and the default password is "DM3610." Your site administrator may have modified these defaults.
- 6. Select a language from the Language drop-down list.
- 7. Click Log On.

If the user name and password are valid, the application enables all functions available to the user and displays the main window.



If the user name and password are not valid, the application displays a results box with the message, "Wrong User Name or Password!" Click OK to return to the Log On window and enter the correct user name and password.

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To log out of the DM3610 User Interface:

Click at the upper right corner of the User Interface window to Log Out. When logged out, the **Log On** window will appear.

4.2 IP ADDRESS DISCOVERY

To discover the IP address of the dimensioner:

- 1. Power down the dimensioner (disconnect power).
- 2. Connect Laptop to the HOST port of the DM3610 with an M12 to RJ45 adapter cable.



Figure 58: Connector Panel

- 3. Hold down the "!" key on the dimensioner control panel while reapplying power to the unit.
- 4. As the dimensioner starts up, continue holding down the "!" key on the control panel. The Status LED will alternate between green and red, but continue holding the "!" key until the **Status** LED remains solid red (about seven seconds).
- 5. Open a web browser and enter the default IP address (192.168.3.100).
- 6. A window opens with information about your system including the units IP address.

Bootloader Version:	1.1(3)
System Username is:	DM3610
System Password is:	DM3610
System IP Address is:	10.0.40.25
Show Message Log:	MSGLOG
Boot Application code:	BOOTAPP
Clear Parameters in FLAS	H: <u>CLEARPARM</u>
Test DDR RAM:	<u>TESTRAM</u>
Reboot scanner:	<u>REBOOT</u>
Kernel to Upoad:	Browse_ No file selected.
	Upload Kernel

7. Power down the dimensioner to exit this feature.

4

Upon normal power up you can connect to the dimensioner using the IP Address, Username and Password indicated in the system info window.

4.3 USER INTERFACE BASICS

4.3.1 DM3610 User Interface Menu Tree

The functions that you can select are displayed in a menu tree on the left-hand side of the DM3610 User Interface. The function list is organized much like the hierarchy of a file system, where you can expand items that begin with a plus sign (+) to further sub-levels until you find a function of interest.

Modify Setting	s >
Configuration	
Dimensioning	
Settings	
Calibration	
Tach/Trigger/Transr	nit
Network	
Settings	
Message Definition	#1
Message Definition	#2
Serial	
Port #1	
Port #2	
Message Definition	1 #1
Message Definition	1 #2
Relay	
Save/Retrieve	
Diagnostics	>
 Monitor 	
 DimView Log Viewer 	
 Log viewer Audit and Alibi 	
 Update Firmware 	
 Help 	

Sub-levels appear indented below the items from which they are expanded. Items that are expanded are preceded by a minus sign (-). You can expand no further when an item displays neither a plus or minus sign.

The DM3610 User Interface menu tree appears with no items expanded. Click the folders to display the active window for the setup function and/or expand the folders to view any additional setup features.

4.3.2 Getting Help

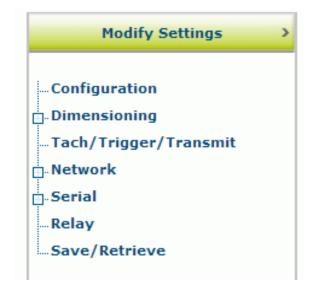
DM3610 User Interface provides complete online help. To display help for a current window:

- 1. Click the Help icon isplayed at the top right of the screen. A help window appears, providing you with information and an index of topics associated with the current application window.
- 2. Click on a topic of interest to display more detailed information.

You can use the menus or buttons in the help window to navigate to other topics of interest, or from the File menu in the help window, you can choose Exit to quit from Help.

4.4 MODIFY SETTINGS

Use the Modify Settings menu tree selections during initial setup to configure your DM3610 Dimensioner. If necessary, you can later make modifications to the dimensioner's configuration using the same menu selections, including:



4.5 MODIFY SETTINGS | CONFIGURATION

Use Configuration to identify and configure a DM3610 Dimensioner. This includes access to dimensioner information as well as configuration options (scan rate, control panel and network access).

To set the dimensioner Configuration:

1. In the tree menu under **Modify Settings**, click **Configuration**. The **Configuration** window opens.

DM3610_RELEASE DSP Software Name/Rev DM3610_DSP FPGA Device Id/Revision	1.4(7)
DM3610_DSP FPGA Device Id/Revision	1.4(7)
FPGA Device Id/Revision	
provide the star the star the star star star star	
0x3c40	3.8(0)
LFT Library Name/Revisio	on
DM3610_LFT	1.4(4)
Username	DM3610
New Password	•••••
Confirm Password	•••••
	DM3610_LFT Control Panel Option Control Panel Option Enable Control Pa Network Access Opt Username New Password

2. Enter the appropriate information in the form as described below.

Field Name	Action/Definition
Dimensioner Inform	nation
Dimensioner Name	Enter a user-defined dimensioner name (up to 15 characters) in the field provided. This is useful when it is necessary to identify multiple dimensioners within the same building or application.
Dimensioner Model	Displays the dimensioner model (DM3610-1000, DM3610-1100, etc.)
Serial Number	Displays the 9 character Datalogic serial number of the dimensioner to which the user interface has established a connection.
Software Name/Revision	Displays the name and revision number of the DM3610 application software.
DSP Software Name/Revision	Displays the name and revision number of the Digital Signal Processor (DSP)
FPGA Device Id/Revision	Displays the FPGA (field-programmable gate array) device name and revision number.
LFT Library Name/Revision	Displays the name and revision of the Legal For Trade (Certified Dimensioning) component of the DM3610 application software.
Configuration Optic	ons
Units	Select Imperial or Metric from the drop-down list. This setting affects the user interface only and not the dimensioning output. To change the dimensioning output, see Modify Settings Dimensioning Settings.
Control Panel Optic	ons
Enable Control Panel Buttons	Select this check box to activate the Control Panel Buttons on the front of the DM3610. Deselect this check box to deactivate.
Network Access Options	Use these fields to change the unit's username and password.
Username	Enter a new username.
New Password	Enter a new password.
Confirm Password	Enter the new password again.

3. When you have finished making changes, click **Update** to save or click **Reset** to revert to the previously saved values.

4.6 MODIFY SETTINGS | DIMENSIONING

Use the **Modify Settings | Dimensioning** menu tree selections to setup and calibrate the DM3610 for certified or non-certified installations.

The menu selections include:

• Settings

4

Calibration

4.6.1 Modify Settings | Dimensioning | Settings

Use Dimensioning | Settings to turn certification mode on or off, set dimension resolution, and define package size requirements.

To adjust the settings of the dimensioner:

1. In the tree menu under **Modify Settings**, navigate to **Dimensioning | Settings**. The **Settings** window opens.

DIM-in-Head Enabled	Off	•	
Units	Inch	•	
Length Reporting	Descending Order	•	
Certification Mode	Off	•	
Length, Width Resolution (d)	0.2 inch	•	
Height Resolution (d)	0.1 inch	-	
Minimum Package Size	Length (in) Width (in)	2.4	
	Length (in)	2.4	
and the set of the set	Height (in)	2.4	
	Length (in)	98.0	
Maximum Package Size	Width (in)	48.0	
	Height (in)	36.0	
Discord Deckson Cine	Length/Width (in)	0.5	
Discard Package Size	Height (in)	0.5	

2. Enter the appropriate information in the form as described below.

Field Name	Action/Definition	
Outputs		
DIM-in-Head Enabled	Select On or Off from the drop-down list.	
	If On is selected, the DM3610 is using the scan poin data to calculate the object dimensions within the head itself.	
	If Off is selected, the DM3610 is not calculating dimensions, but gives you the option to transmit scan point data to a remote device over the network. This data can be used when dimensioning irregular shaped objects.	
Units	Select inch or mm from the drop-down list. Once the window is updated, the dimensions displayed on this window will be displayed in the unit type selected.	
	NOTE : Changing the units on this window will not affect other windows in this user interface. To change the measurement units globally for the interface, see Modify Settings Configuration .	
Length Reporting	Select Longest Side, Direction of Travel, or Descending order from the drop-down list.	
	• Longest Side: The system assigns the length as the larger of the two parcel measurement axes that are parallel to the surface of the conveyor. The height is the measurement axis that is perpendicular to the conveyor surface.	
	• Direction of Travel: The "length" will always be defined as that parallel with the package direction of travel on the conveyor.	
	• Descending Order: The "length" is the largest value, then width, and the smallest value is height. This definition results in the same L, W, H assignment of the measurements regardless of the parcel's orientation when measured.	
Certification Mode	Select On or Off from the drop-down list. Turn certification mode on for certified / Legal-for-Trade applications. Turning certification mode on causes many of the input fields in the Dimensioning Settings, Dimensioning Calibration , Configuration , and Tach/Trigger windows to be disabled.	

Field Name	Action/Definition
Length, Width Resolution (d)	Select the dimensioning length/width resolution from the choices provided in the drop-down list. (d) represents the smallest interval between two consecutive values used in the dimension calculations.
Height Resolution (d)	Select the dimensioning height resolution from the choices provided in the drop-down list.(d) represents the smallest interval between two consecutive values used in the dimension calculations.
Package Size Options	
Minimum Package Size: Length (mm)/(inch) Width (mm)/(inch) Height (mm)/(inch)	Enter the minimum package size length, width, and height in inches or millimeters as indicated. Any package below these minimums will be designated as a NoDim. Minimum units must be greater than the (d) value <i>(See above).</i>
Maximum Package Size Length (mm)/(inch) Width (mm)/(inch) Height (mm)/(inch)	Enter the maximum package size length, width, and height in inches or millimeters as indicated. Any package above these maximums will be designated as a NoDim.
Discard Package Size Length/Width (mm)/(inch) Height (mm)/(inch)	Enter the minimum length/width and height below which a dimension result will be ignored. This accounts for possible anomalies on the belt surface.

3. When you have finished making changes, click **Update** to save or click **Reset** to revert to the previously saved values.

4.6.2 Modify Settings | Dimensioning | Calibration

Use Dimensioning | Calibration to calibrate an installed DM3610 dimensioner.

To calibrate the dimensioner (See also, **Dimensioner Calibration** in chapter 5 section 5.6, Dimensioning Features):

1. In the tree menu under **Modify Settings**, navigate to **Dimensioning | Calibration**. The **Calibration** window opens.

Belt Analysis	-			
Side Margins	0	in	Find Belt	Use Belt
Dimensioning Area				
	Current		Find Belt	
Scan Points (100-1000)	1000		0	
Field of View (2-73°)	73		0	
Angle Offset (0-32°)	16		0	
Scanner Height	64	in	0	in
Left Ignore	21.875	in	0	in
Right Ignore	21.875	in	0	in
	,		,	
				Update Rese

2. Enter the appropriate information in the form as described below.

Field Name	Action/Definition
Belt Analysis	
Side Margins	Side margins equal the width of spacers (the aluminum extrusion pieces shown in the drawing below) that help the dimensioner find the edges of the conveyor belt.
	If the spacers are placed inside the belt width, the spacer width must be entered into the Side Margins text field. <i>For example,</i> if 3-inch spacers are used, the Side Margins field value must be 3. The spacers must be the same width.
	If the spacers can be placed outside the edge of the belt, or if side rails are present, a "0" must be entered into the Side Margins text field for the spacer width.

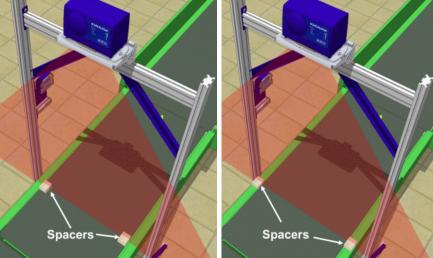


Figure 59: Side Margin Spacer Placement

Scan Points (100-

Field of View (2-119

1000)

degrees)

Field Name	Action/Definition
Belt Analysis	
Find Belt	Click Find Belt to automatically determine the scan points, field of view, angle offset, scanner height, left ignore, and right ignore.
	NOTE: When Find Belt is clicked, the system calculates the dimensioner's position over the conveyor. If the system determines that the dimensioner is not centered on the belt, it will return this message:
	WARNING: DM3610 mounting misses belt center by more than 1". Recommend remounting.
	If the system determines that the mounting height compared to the system's maximum package size (See Modify Settings Dimensioning Settings in chapter 4) does not allow the system to adequately dimension the package, it will return this message:
	WARNING: FINDBELT calculated FOV > 73°. Confirm Maximum Package Height setting and check DM3610 mounting height.
	If the system determines that the mounting height is above 1727mm [68"], it will return this message:
	WARNING: FINDBELT calculated Scanner Height > 68". Recommend mounting DM3610 lower.
	The Find Belt calculation measures the dimensioner height from the bottom of the DM3610 housing to the belt. <i>Maximum</i> height to this point for best results is 1727mm [68"].
	Find Belt measures dimensioner height to bottom of housing
	Figure 60: Dimensioner Height
Use Belt	Click Use Belt to transfer the "found" or calculated dimensions to the Dimensioning Area fields.
Dimensioning Area	NOTE: All these values are automatically

populated

commands

This is the number of points across the laser scan line.

swing angle of coverage for the laser from left to right.

Enter the coverage angle of the dimensioner's laser. This is the total

by the Find Belt/Use

4

Belt

Field Name	Action/Definition
Belt Analysis	
Angle Offset (0-32 degrees)	Enter the angle offset of the dimensioner's laser. The correct angle offset leads to a scan line centered on a particular point on the belt so that when the field of view is expanded or contracted, this central point does not change. The scan line expands and contracts about it, and the left and right extremities of the scan line are of equal distance from this point for any field of view.
Scanner Height	Enter the distance from the scanner to conveyor belt surface. If Use Belt is clicked, this field will be populated automatically.
Left Ignore	Enter the distance from the center of the scan line to the left edge of the belt. Scan points beyond this distance will be ignored. If Use Belt is clicked, this field will be populated automatically.
Right Ignore	Enter the distance from the center of the scan line to the right edge of the belt. Scan points beyond this distance will be ignored. If Use Belt is clicked, this field will be populated automatically.

3. When you have finished making changes, click **Update** to save or click **Reset** to revert to the previously saved values.

4.7 MODIFY SETTINGS | TACH/TRIGGER/TRANSMIT

Use Tach/Trigger/Transmit to set up the tachometer source and trigger source. A range of settings are definable based on use of hardware or software sources.

To set up tachometer and trigger sources:

1. In the tree menu under **Modify Settings**, navigate to **Tach/Trigger/Transmit**. The **Tach/Trigger/Transmit** window opens.

Tachometer Tach Source Hardware/External Pulse per in 16.00 Tach Scale Factor 1.000 Tach Controlled Laser Image: Controlled Laser	Trigger Trigger Source Polarity Debounce Duration (ms) Trigger Reference Point	Hardware Trigger Active High 5 6.0 in
Transmit Transmit Type Trigger Based Scans 💌	Extends Extend Front Extend Back	0.0 in 0.0 in
		Update Reset

Δ

2. Enter the appropriate information in the form as described below.

Field Name Action/Definition

Tachometer						
Tach Source	Select Hardware/External or Constant/Internal the tachometer source from the drop-down list.					
	Hardware/ External	Used for external hardware tachometer. When this tachometer mode is used, you must also set the number of pulses per centimeter [inch] generated by the tachometer.				
		Tachometer Trigger Tach Source Hardware/External Trigger Source Pulse per in 16.00 Polarity Active High Tach Scale Factor 1.000 Debounce Duration (ms) 5 Trigger Reference Point 6.0 in				
		Transmit Transmit Edge Trailing Edge Trailing Edge Trailing Edge In Transmit Point 20.0 in				
		Update Reset				
	Pulse per cm [in]	Enter the number of tachometer pulses used per cm [in] traveled.				
	Tach Scale Factor	Enter a factor to eliminate deviations in the expected versus actual tachometer pulses/inch or cm. For example: If you notice that the length (in the direction of travel) of your package is too short and you have a tachometer pulse of 16 pulses per inch, enter a Tach Scale Factor of less than 1.0. If you enter 0.97 your effective pulses per inch become 15.52 pulses per inch. If, however, your package is too long, enter Tach Scale Factor greater than 1.0. Adjust by small increments.				
	Tach Controlled Laser	Enable this check box for the laser to automatically turn off whenever the belt speed is zero for one minute or more.				

Field Name Action/Definition

Constant/ Internal	Specify the tach rate to be used (from .05 - 3.05 m/sec [from 10 - 600 ft/min]). No external hardware is used.			
	Tachometer Trigger Tach Source Constant/Internal Pulse per in 16.00 Tach Scale Factor 1.000 Speed 200.0 fpm Tach Controlled Laser Trigger Source Hardware Trigger Controlled Laser Transmit Transmit Edge Transmit Point 20.0 in 			
	Update Reset			
Pulse per cm [in]	Enter the number of tachometer pulses used per cm [in] traveled.			
Tach Scale Factor	Enter a factor to eliminate deviations in the expected versus actual tachometer pulses/inch or cm. For example: If you notice that the length (in the direction of travel) of your package is too short and you have a tachometer pulse of 16 pulses per inch, enter a Tach Scale Factor of less than 1.0. If you enter 0.97 your effective pulses per inch become 15.52 pulses per inch. If, however, your package is too long, enter Tach Scale Factor greater than 1.0. Adjust by small increments.			
Speed	Enter the actual measured speed of your conveyor belt in cm/sec or fpm (feet per minute)			
Tach Controlled Laser	Enable this check box for the laser to automatically turn off whenever the belt speed is zero for one minute or more.			

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Field Name Action/Definition

		-				
Trigger						
Trigger Source	Select Hardware Trigger, Software Trigger, or Continuous Trigger from the drop-down list.					
	Hardware Trigger	This refers to an actual photoelectric sensor used as the trigger.				
		Tachometer Trigger Tach Source Hardware/External Pulse per in 16.00 Tach Scale Factor 1.000 Tach Scale Factor 1.000 Tach Controlled Laser Debounce Duration (ms) Transmit Transmit Edge Trailing Edge Transmit Point in				
		Update Reset				
	Polarity	 Select Active High or Active Low from the drop-down list Active High: The trigger is active when the inpusional is high Active Low: The trigger is active when the inpusional is low. 				
	Debounce Duration (ms)	Enter the minimum number of milliseconds required for detection of a change in the hardware trigger status.				
	Trigger Reference Point	Enter the distance from your trigger source to the DM361 laser scan line.				

Trigger	Tachometer Tach Source Hardware/External Pulse per in 16.00 Tach Scale Factor 1.000 Tach Controlled Laser Image: Controlled Laser Transmit Training Edge Transmit Point 20.0 in	Trigger Software Trigger Software Trigger Host - 1 Start Char S End Char E Trigger Reference Point 6.0 Update Reset
Software Trigger	down list.	Net - 1, or Net - 2 from the drop- be any "host port" either serial or
Start Char	Define the ASCII characte trigger for the reader.	ers that, when received, will start
End Char	Define the ASCII character trigger for the reader.	ers that, when received, will end
Trigger Reference Point		our trigger source to the DM3610
Continuous Trigger		sioner is always in trigger mode the dimensions of any package
	SEEN.	Trigger Trigger Source Continuous Trigger I
	Tachometer Tach Source Hardware/External • Pulse per in 16.00 Tach Scale Factor 1.000	Trigger

Transmit	Transmit is hid	den if Continuous Trigger is selected as the trigger source.
Transmit Type	Settings Di	nly visible when DIM-in-Head Enabled is set to Off in Modify mensioning Settings. Select No Transmit, Continuous r Based Scans, Calibration Scans , or Averaged Scans from list.
	Þ	NOTE : This data is transmitted by UDP messaging to the remote IP address and port specified in the Data Transmit section of the Network Settings page.
	No Transmit	When selected, no scan line data is transmitted.
	Continuous	When selected, every scan line is transmitted.
	Scans	WARNING: This mode should only be used for controller-based dimensioning. The high-throughput can have adverse effects on the system and/or diagnostic utilities.
	Trigger Based Scans	When selected, scan lines are transmitted at a slow rate, but when a trigger source is active scan lines are sent at the full rate. This mode is useful when using Diagnostics DimView. The system defaults to this mode when DIM-in- Head Enabled is turned off.
	Calibration Scans	When selected, this behaves like Trigger Based Scans but provides additional debugging capability to an advanced user.
	Averaged Scans	When selected, this behaves like Trigger Based Scans, except that it averages scan line data over time. This mode is useful when using Diagnostics DimView as it smooths away image noise.
Transmit Edge	Settings Dim	nly visible when DIM-in-Head Enabled is set to On in Modify nensioning Settings. Specifies which edge of the package ling) is used to reference the transmit point. View window.
Transmit Point	Settings Din transmitted. D	nly visible when DIM-in-Head Enabled is set to On in Modify nensioning Settings. The point at which dimension data is befines the number of inches or centimeters after the specified ckage passes the trigger before data transmission occurs.

Field Name Action/Definition

Extend Front

Field Name Action/Definition

Extends These inputs are only available when DIM-in-Head Enabled is set to Off in Modify Settings | Dimensioning | Settings and a Transmit Type of Trigger Based Scans, Calibration Scans, or Averaged Scans is selected. Tachometer Trigger Hardware/External Hardware Trigger Tach Source Trigger Source -16.00 Active High 💌 Pulse per in Polarity 1.000 Tach Scale Factor 5 Debounce Duration (ms) Tach Controlled Laser 🗐 6.0 Trigger Reference Point in Transmit Extends 0.0 Transmit Type Trigger Based Scans 💌 Extend Front in Extend Back 0.0 in

Extend Back Scan lines will return from full rate to slow/nominal rate this many inches after the back of the package passes the scan line.

package crosses the scan line.

Scan lines will be sent at the full rate this many inches before the front of the

3. When you have finished making changes, click **Update** to save or click **Reset** to revert to the previously saved values.

81

4

Update

Reset

4.8 MODIFY SETTINGS | NETWORK

Use **Modify Settings | Network** to specify network settings (including the IP address) for the dimensioner. Net Host Connection 1 and Net Host Connection 2 define two network connections for sending messages. The Connection Type and Message Format for each port can be set independently. Message formatting is the same as for the serial port. The menu selections include:

Network Settings Message Definition #1 Message Definition #2

Definitions:

IP Address - An IP address specifies a unique host ID for the reader on a particular TCP/IP network. Consult your network administrator for a valid IP address for the reader.

Net Mask - A netmask modifies a standard IP address into subnets. A default class C net mask should be valid in most cases (either 255.255.255.0 or 255.255.240.0).Consult your network administrator for the net mask value.

Gateway IP Address - A gateway allows the reader to reach other systems not on the local network and remote systems to reach the reader. If the reader requires external connectivity, consult your network administrator for a valid gateway address.

4.8.1 Modify Settings | Network | Network Settings

Use **Modify Settings | Network | Network Settings** to specify network settings (including the IP address) for the dimensioner.

Net Host Connection 1 and **Net Host Connection 2** define two network connections for sending messages. The **Connection Type** and **Message Format** for each port can be set independently. Message formatting is the same as for the serial port.

To adjust the network settings of the dimensioner:

1. In the tree menu under **Modify Settings**, navigate to **Network | Network Settings**. The **Network Settings** window opens.

IP Address 1	Net Host Connection 1
10 27 152 191	Connection Type TCP/IP Server
Net Mask 1 255 255 248 0	Message Format User Defined Message 💌 Port 3001
Gateway IP Address	Net Host Connection 2
0 0 0	Connection Type TCP/IP Server
Enable IP Address 2 IP Address 2 192 168 3 100	Message Format Standard Message 💌 Port 3002
Net Mask 2	Telnet Port
255 255 0	Data Transmit 10 27 154 166 10001 27 154 166
	Update Reset

2. Enter the appropriate information in the form as described below.

Field Name	Action/Definition
IP Address 1	An IP address specifies a unique host ID for the reader on a particular TCP/IP network. Consult your network administrator for a valid IP address for the reader.
	NOTE: If you choose to enable a second IP address, the local IP address must be entered in the IP Address 1 text fields. The Host IP address must then be entered in the IP Address 2 text fields. This is because the Gateway Address is associated with IP address 2.
Net Mask	A net mask modifies a standard IP address into subnets. A default net mask should be valid in most cases (255.255.255.0). Consult your network administrator for the net mask value.
Gateway IP Address	A gateway allows the reader to reach other systems not on the local network and remote systems to reach the reader. If the reader requires external connectivity, consult your network administrator for a valid gateway address.
Enable IP Address 2	Check this box to enable an optional second IP address for the unit. When checked, IP Address 2 and Net Mask 2 fields become active.
IP Address 2	Enter a secondary IP address for the unit.
	NOTE : If you choose to enable a second IP address, the local IP address must be entered in the IP Address 1 text fields. The Host IP address must then be entered in the IP Address 2 text fields. This is because the Gateway Address is associated with IP address 2.
Net Mask 2	Enter a secondary Net Mask for the unit.
Net Host Connection <i>n</i>	Select a connection types from the drop-down list:
	TCP/IP Server: As a TCP/IP server, a Port # must be specified. In this case it is the TCP/IP client's responsibility to initiate a connection.
	TCP/IP Client: As a TCP/IP client, aside from the Port #, the Remote IP Address of the TCP/IP server which is to receive messages must be specified.
	When used, a Reconnect Time must be entered in the field provided. The Reconnect Time specifies the interval (in seconds) at which the reader attempts to establish a connection.
	A remote IP address must also be entered in the fields provided.
	UDP Messaging (User Datagram Protocol): In some instances, it may be desirable to use a connection-less UDP message to send data. In this case, only the Port # and Remote IP Address of the receiver need to be specified.

When used, a remote IP address must also be entered in the fields provided.



NOTE: Selecting a new Net Host **Connection Type** and clicking **Update** will cause the DM3610 to reboot. A reboot message is displayed. Click **OK** to return to the Log On window.

The page at 10.27.152.191 says:	23
Parameter change requires a reboot. The syst in two seconds.	em will reboot
ſ	ОК

Select a Message Format from the drop-down list:

Custom Message: This selection may only be available when custom dimensioner software has been developed and installed for your system by Datalogic.



NOTE: When **Custom Message** is selected, editable fields in the **Message Definition #n** window may be defined by the custom software installed.

Standard Message: When Standard Message is selected, the system uses a message format as defined by the standard DM3610 software.



NOTE: When **Standard Message** is selected, no user input is permitted in the **Message Definition** *#n* window.

User Defined Message: This selection allows the user to define messages used. Messages can be defined in the Message Definition #n window.

Telnet PortEnter a Telnet port ID. Telnet is a network protocol that allows a user
on one computer to log on to another computer remotely.

Data TransmitWhen DIM-in-Head Enabled is set to Off in Modify Settings |
Dimensioning | Settings scan line data can be sent to this IP
address and port for off-line analysis and troubleshooting. The various
modes of this data transmission can be set using the Transmit Type
selection on the Tach/Trigger/Transmit page.



WARNING: The **Data Transmit** IP Address must be kept at its default of 0.0.0.0 if you do not need to transmit scan line data for off-line analysis and troubleshooting.

3. When you have finished making changes, click **Update** to save or click **Reset** to revert to the previously saved values.

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4.8.2 Modify Settings | Network | Message Definition #N

Use **Modify Settings | Network | Message Definition** *#n* to define messages when User Defined Messages has been selected in the **Network Settings** window.

To define the appearance of dimensioner messages:

4

1. In the tree menu under Modify Settings, navigate to Network | Message Definition #*n*. The Message Definition #*n* window opens.

Header \02 Trailer \0d\0a			Sequence No Check Digits No		•	
lessages						
Dim	Send Di	mensions 💌				
NoDim	Send Di	mensions 💌				
Dimensions Format	LWH	•	Field Width	-		
Dimension Units	in	•	Precision 1	•		
Field Delimiter	;	1				
Omit Decimal						
Lead Padding						
Trail Padding			-			
Append Units	V	Separator	;			
Append Ready Stat	is 🔽	Separator	;			
Append NoDim Stat	is 🔽	Separator	;			
Append Alibi Info	V	Separator	;			
Append Volume	N	Separator	;			
Volume Units	ft ^a	•	Volume Field	Width 6	•	
			Volume Precis	ion 3	•	
Heart Beat Message						
Heart Beat Time Ou	t (0-30,00	00 ms)	0			

2. Enter the appropriate information in the form as described below.

Field Name	Action/Definition				
Framing	Define the message framing				
Header	Enter a character string for the header (ASCII or Hex). These characters will be sent at beginning of every message. Up to 25 characters are allowed.				
Trailer	Enter a character string for the trailer. These characters will be sent to terminate every message.				
Sequence	Select No Sequence No., 1 Digit Sequence No., 2 Digit Sequence No., or 3 Digit Sequence No. from the drop down list. When a digit sequence is selected, a sequence number consisting of the specified number of digits is inserted just after the header.				
Check Digits	Select BCC or CRC from the drop-down list. When enabled, a two- character hexadecimal check character is inserted just prior to the trailer.				
Messages					
Dim	Select None, Send Dimensions, or User Defined from the drop-down list.				
	None: No dimension data is sent in the message.				
	Send Dimensions: This selection sends the package dimensions in the message.				
	User Defined: When selected, a text field is provided for entry of a user defined message.				
	Dim User Defined 💌				
No Dim	Select None, Send Dimensions, or User Defined from the drop-down list.				
	None: No dimension data is sent in the message.				
	Send Dimensions: This selection sends the package dimensions in the message.				
	User Defined: When selected, a text field is provided for entry of a user defined message.				
	NoDim User Defined ????,????				
Dimensions Format	Select in what order you would like the Length, Width, and Height measurements to appear in the message. L=Length / W =Width / H=Height				

Field Name	Action/Definition		
Field Width	Select the field width of the minimal number of characters for length, width, and height from the drop-down list. 2 to 7 characters are available. If the value has fewer characters than the field width, it will be padded with zeros on the left.		
	For example:		
	If Precision is set at 1 (1 decimal place), field width is set at 5, and the dimension is 12.3, then the returned value in the host message will be 012.3		
	If Precision is set at 2 (2 decimal place), field width is set at 7, and the dimension is 12.3, then the returned value in the host message will be 0012.30		
Dimension Units	Select in (inches), mm (millimeters), or cm (centimeters) from the drop down list.		
Precision	Select 0, 1, or 2 from the drop-down list. This is the number of digits appearing after the decimal point.		
Field Delimiter	Enter a character to be used as a delimiter between length, width, and height fields. A semicolon is often used to separate data.		
Omit Decimal	Select this check box to remove the decimal point character from the message. Only the decimal point character is removed, and digits before and after the decimal point remain.		
Lead Padding	Enter characters to proceed the length, width, and height field.		
Trail Padding	Enter characters to follow the length, width, and height field.		
Append Units	Select the check box to enable. When checked, a Separator text field is revealed. Enter a separator character in the text field provided. A unit abbreviation (mm, cm, or in) will be appended after the separator.		
Append Ready Status	Select the check box to enable. When checked, a Separator text field is revealed. Enter a separator character in the text field provided. NOTREADY or READY will be appended after the separator. NOTREADY indicates that this package result is not legal-for-trade.		
Append NoDim Status	Select the check box to enable. When checked, a Separator text field is revealed. Enter a separator character in the text field provided. If the package is a NoDim, a reason code is appended after the separator.		
	For example:		
	NODIM_BOX_STACKED, NODIM_BOX_SIDES_TO_NOISY		
	A NoDim reason indicates that this package result is not legal-for-trade.		

Field Name	Action/Definition			
Append Alibi Info	Select the check box to enable. When checked, a Separator text field is revealed. Enter a separator character in the text field provided. Alibi storage information is appended after the separator. Format: <sequence # -yyyymmddhhmmss<="" th=""></sequence>			
Append Volume	e Select the check box to enable. When checked, Volume Units, Vol Field Width, and Volume Precision drop-down boxes are revealed.			
	Volume Units ft ^s Volume Field Width 6 Volume Precision 3			
	Select cubic Volume Units from the drop-down list. Selections include in ³ (inches cubed), ft ³ (feet cubed), cm ³ (centimeters cubed), and dm ³ (decimeters cubed).			
	Select a Volume Field Width of 2 to 8 from the drop-down list. This represents the number of characters available for the field width. If the value has fewer characters than the field width, it will be padded with zeros on the left.			
	Select a Volume Precision of 0 to 3 from the drop-down list. This is the number of digits appearing after the decimal point.			
	For example:			
	If Volume Precision is set at 1 (1 decimal place), Volume Field Width is set at 5, and the volume is 25.8 cm ³ , then the returned value in the host message will be 025.8			
	If Volume Precision is set at 2 (2 decimal place), Volume Field Width is set at 8, and the volume is 25.8 cm ³ , then the returned value in the host message will be 00025.80			
Heart Beat Message	Enter a heart beat message in milliseconds if desired. If no other message is sent for the time period specified in Heart Beat Time Out , the specified heart beat message string is sent.			
	NOTE : A time-out of zero disables the heart beat message.			
Heart Beat Time Out (0-30,000	Enter an interval for heart beat time out in milliseconds.			
ms)	0 = Disable Heart Beat Message,			
	1-30,000 = Delay before sending Heart Beat Message			

3. When you have finished making changes, click **Update** to save or click **Reset** to revert to the previously saved values.

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4.9 MODIFY SETTINGS | SERIAL

Use Modify Settings | Serial to specify serial settings for the dimensioner. Port #1 and Port #2 define two serial connections for sending messages. The Connection Type and Message Format for each port can be set independently. The menu selections include:

Port #1 Port #2 Message Definition #1 Message Definition #2

4

4.9.1 Modify Settings | Serial | Port #N

Use Modify Settings | Serial | Port #1 (or #2) to define the format of message the dimensioner sends to your host computer (or other device) connected to Serial Port n.

To adjust the serial port settings for the dimensioner:

1. In the tree menu under **Modify Settings**, navigate to **Serial | Port #n**. The **Port #n** window opens.

Baud Rate	Data Bits	Stop Bits	1
© 600 © 19200	© 7 Bits	© 1 Bits	
0 1200 0 38400	8 Bits	2 Bits	
 2400 57600 4800 115200 9600 	Parity None Even Odd		1
Mode	-Message Format		
RS232 Direct RS232 Backup Module	Legal for Trade Dis		device for Certified
			Update Reset

2. Select the appropriate information in the form as described below.

Field Name	Action/Definition				
Baud Rate	Select a baud rate from the options provided (signal events per second).				
Data Bits	Select the number of data bits from the options provided (bits per second).				
Stop Bits	Select the number of stop bits from the options provided.				
Parity	Select a parity option of None , Even , or Odd .				
Mode	Select a mode of RS232 Direct or RS232 Backup Module . RS232 Backup Module . RS232 Backup Module (default) indicates that communications go through a CBX100 connection box with an installed BM100 backup module.				
	RS232 Direct indicates communications are going through a CBX100 connection box without a backup module installed, or you are completely bypassing a CBX100 connection box.				
Message Format	Select a message format from the drop-down list:				
	Custom Message: Custom messaging is enabled here if your application uses custom software.				
	Standard Message: The standard message format begins with a (STX) character and ends with a (CR)(LF).				
	NOTE : When Standard Message is selected, no user input is permitted in the Message Definition # <i>n</i> window.				
	User-Defined Message: Use the Message Definition form to specify your message format.				
	Legal for Trade: Select this option to use an external display device for certified dimensioning.				

3. When you have finished making changes, click **Update** to save or click **Reset** to revert to the previously saved values.

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4.9.2 Modify Settings | Serial | Message Definition #N

Use Modify Settings | Serial | Message Definition #n to define messages when User Defined Messages has been selected in the Serial Port #n window.

To define the appearance of dimensioner messages:

4

1. In the tree menu under **Modify Settings**, navigate to **Serial | Message Definition** *#n*. The Message Definition *#n* window opens.

- Framing				
Header \02			No Sequence No.	
Trailer \\0d\0a		Check Digits	None	•
Messages				
Dim	Send Dimensions 💌			
NoDim	Send Dimensions			
Dimensions Format	LWH 💌	Field Widt	n 4 💌	
Dimension Units	in 💌	Precision	1	
Field Delimiter				
Omit Decimal				
Lead Padding				
Trail Padding				
Append Units	Separator			
Append Ready Statu	us 🗹 Separator	;		
Append NoDim Statu	us 🗹 Separator	;		
Append Alibi Info	Separator	;		
Append Volume	Separator	;		
Volume Units	ft³ ▼	Volume Fie	eld Width 6	•
		Volume Pro	ecision 3	•
Heart Beat Message				
Heart Beat Time Out	t (0-30,000 ms)	0		
				Update Reset

2. Enter the appropriate information in the form as described below.



NOTE: Available user interaction with this form will vary depending on the Message Format selected in **Modify Settings | Serial | Port #***n*.

Field Name	Action/Definition				
Framing	Define the message framing				
Header	Enter a character string for the header (ASCII or Hex). These characters will be sent at beginning of every message. Up to 25 characters are allowed.				
Trailer	Enter a character string for the trailer. These characters will be sent to terminate every message.				
Sequence	Select No Sequence No., 1 Digit Sequence No., 2 Digit Sequence No., or 3 Digit Sequence No. from the drop down list. When a digit sequence is selected, a sequence number consisting of the specified number of digits is inserted just after the header.				
Check Digits	Select BCC or CRC from the drop-down list. When enabled, a two-character hexadecimal check character is inserted just prior to the trailer.				
Messages					
Dim	Select None, Send Dimensions, or User Defined from the drop-down list.				
	None: No dimension data is sent in the message.				
	Send Dimensions: This selection sends the package dimensions in the message.				
	User Defined: When selected, a text field is provided for entry of a user defined message.				
	Dim User Defined				
No Dim	Select None, Send Dimensions, or User Defined from the drop-down list.				
	None: No dimension data is sent in the message.				
	Send Dimensions: This selection sends the package dimensions in the message.				
	User Defined: When selected, a text field is provided for entry of a user defined message.				
	NoDim User Defined ????,????				

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Field Name	Action/Definition			
Dimensions Format	Select in what order you would like the Length, Width, and Height measurements to appear in the message. L=Length / W =Width / H=Height			
Field Width	Select the field width of the minimal number of characters for length, width, and height from the drop-down list. 2 to 7 characters are available. If the value has fewer characters than the field width, it will be padded with zeros on the left.			
	For example:			
	If Precision is set at 1 (1 decimal place), field width is set at 5, and the dimension is 12.3, then the returned value in the host message will be 012.3			
	If Precision is set at 2 (2 decimal place), field width is set at 7, and the dimension is 12.3, then the returned value in the host message will be 0012.30			
Dimension Units	Select in (inches), mm (millimeters), or cm (centimeters) from the drop down list.			
Precision	Select 0, 1, or 2 from the drop-down list. This is the number of digits appearing after the decimal point.			
Field Delimiter	Enter a character to be used as a delimiter between length, width, and height fields. A semicolon is often used to separate data.			
Omit Decimal	Select this check box to remove the decimal point character from the message. Only the decimal point character is removed, and digits before and after the decimal point remain.			
Lead Padding	Enter characters to proceed the length, width, and height field.			
Trail Padding	Enter characters to follow the length, width, and height field.			
Append Units	Select the check box to enable. When checked, a Separator text field is revealed. Enter a separator character in the text field provided. A unit abbreviation (mm, cm, or in) will be appended after the separator.			
Append Ready Status	Select the check box to enable. When checked, a Separator text field is revealed. Enter a separator character in the text field provided. NOTREADY or READY will be appended after the separator. NOTREADY indicates that this package result is not legal-for-trade.			
Append NoDim Status	Select the check box to enable. When checked, a Separator text field is revealed. Enter a separator character in the text field provided. If the package is a NoDim, a reason code is appended after the separator. For example: NODIM_BOX_STACKED, NODIM_BOX_SIDES_TO_NOISY A NoDim reason indicates that this package result is not legal-for-trade.			

Field Name	Action/Definition				
Append Alibi Info	Select the check box to enable. When checked, a Separator text field is revealed. Enter a separator character in the text field provided. Alibi storage information is appended after the separator. Format: <sequence # -yyyymmddhhmmss<="" th=""></sequence>				
Append Volume	Select the check box to enable. When checked, Volume Units , Volume Field Width , and Volume Precision drop-down boxes are revealed.				
	Volume Units ft [®] Volume Field Width 6				
	Volume Precision 3				
	Select cubic Volume Units from the drop-down list. Selections include in ³ (inches cubed), ft ³ (feet cubed), cm ³ (centimeters cubed), and dm ³ (decimeters cubed).				
	Select a Volume Field Width of 2 to 8 from the drop-down list. This represents the number of characters available for the field width. If the value has fewer characters than the field width, it will be padded with zeros on the left.				
	Select a Volume Precision of 0 to 3 from the drop-down list. This is the number of digits appearing after the decimal point.				
	For example:				
	If Volume Precision is set at 1 (1 decimal place), Volume Field Width is set at 5, and the volume is 25.8 cm ³ , then the returned value in the host message will be 025.8				
	If Volume Precision is set at 2 (2 decimal place), Volume Field Width is set at 8, and the volume is 25.8 cm ³ , then the returned value in the host message will be 00025.80				
Heart Beat Message	Enter a heart beat message in milliseconds if desired. If no other message is sent for the time period specified in Heart Beat Time Out , the specified heart beat message string is sent.				
	NOTE : A time-out of zero disables the heart beat message.				
Heart Beat Time Out (0-30,000 ms)	Enter an interval for heart beat time out in milliseconds. 0 = Disable Heart Beat Message, 1-30,000 = Delay before sending Heart Beat Message				

3. When you have finished making changes, click **Update** to save or click **Reset** to revert to the previously saved values.

4

4.10 MODIFY SETTINGS | RELAY

Use Relay to configure output and auxiliary relays.

To configure the relays:

1. In the tree menu under Modify Settings, click Relay. The Relay window opens.

OUT 1 Configuration Not in use	
OUT 2 Configuration Not in use	
AUX IN Configuration Not in use	
Update	t

2. Enter the appropriate information in the form as described below.

Field Name	Action/Definition
OUT 1(2) Configuration	Select Not in use, Used as input, or Used as output from the drop- down list.
Not in use	This relay will not be used.
Used as input	The Used as input selection is not currently available.
Used as output	When Used as output is selected, other user-defined options become available including output type, Active High/Low , and Output Signal Duration (ms) .

OUT 1 Configuration			Output Signal Duration (ms)
Used as output 💌	Good Dim 💌	Active High 💌	500
OUT 2 Configuration	Custom Output Life Light Trigger Output Error Light Ready Light Good Dim		
AUX IN Configuratio	No Dim		

Field Name	Action/Definit	lon					
	Output Type	Select an output type from the drop-down list. Options include:					
		Custom Output: Used for applications involving custom software to select a customized output option.					
		Life Light: Always on while the reader is operating.					
		Trigger Output: Echoes the status of the trigger signal.					
		Error Light: Active in the event of an error condition (see later section on errors currently detected).					
		Ready Light: Indicates the system is ready to produce Legal-for-Trade dimension results.					
		Good Dim: Active if all expected dimensions are read.					
		No Dim: Active if not all expected dimensions are read.					
	Active High/Active Low	Select Active High or Active Low from the drop-down list.					
	Output Signal Duration (ms)	Enter a duration in milliseconds for the signal duration.					
AUX IN Configuration	Select Not in list.	use, Use as input, or Use as output from the drop-down					
Not in use	This relay will I	not be used.					
Used as input		as input is selected, other user-defined options become ding input type and Active High/Low					
	-AUX IN Co	nfiguration					
	Used as input Custom Input Active Low						
	Input Type	Currently, only Custom Input is available.					
	Active High/A	Active Low Select Active High or Active Low from the drop- down list.					
Used as output	The Used as a	output selection is not currently available.					

3. When you have finished making changes, click **Update** to save or click **Reset** to revert to the previously saved values.

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4.11 MODIFY SETTINGS | SAVE / RETRIEVE

Use Save/Retrieve to save all the settings to the dimensioner and backup the settings to the backup module and/or file.

To use the Save/Retrieve functions:

4

1. In the tree menu under **Modify Settings**, navigate to **Save/Retrieve**. The **Save/Retrieve** window opens.

Action	То	
Save •	File	OK
	specify a file name and location to store the	current narameter settings o
Save to File - Use to a your computer.		content peraneter settings o
		content perenteter sectings o

2. Enter the appropriate information in the form as described below.

Field Name	Action/Definition
Save/Retrieve	Select an action and location (To or From) from the corresponding drop-down lists:
Save / To File	 Use to download the file to your computer. Depending on your browser's settings, when you click OK: a dialog box may open and ask you to provide a store location for the file. the file may be immediately downloaded to the computers downloads folder.
Save / To Backup Module	Use to save the current set of dimensioner parameters to the backup module as a backup copy. Click OK to execute the command. NOTE : This option is only shown when Serial Port #1 mode is set to RS232 Backup Module.

Field Name	Action/Definition
Retrieve / From File	Use to retrieve a parameters set from a specific file name and location on your computer. Click Choose File to navigate to the parameter file you wish to retrieve.
	Save/Retrieve Action From Retrieve File OK Choose File No file chosen Retrieve from File - Use to retrieve a parameters set from a specific file name and location on your computer.
	Reboot DM3610 Use this function to reboot the dimensioner. Reboot
Retrieve / From Backup Module	Use to retrieve the parameters stored in the dimensioner's backup module. This is especially useful when it becomes necessary to load previously saved parameters to a replacement dimensioner module. Click OK to execute the command. NOTE : This option is only shown when Serial Port #1 set to RS232 Backup Module.
Default	Use to return the dimensioner's parameters to the hard-coded "default" values built into the dimensioner software. WARNING: Selecting Default will return your reader to the default factory settings. Since your reader may already be configured for your application, it is recommended that you ALWAYS Save current parameters to a file or the backup module before using the default function.
Reboot DM3610	Click Reboot to re-initialize the scanner. A warning dialog appears. Click OK to reboot, or click Cancel to return to the Save/Retrieve window.

4.12 DIAGNOSTICS

4

Use the **Diagnostics** menu tree selections to monitor your dimensioning system performance, view system messages, update the dimensioner firmware, and access online help. The Diagnostic windows include:



4.12.1 Diagnostics | Monitor

Use the **Diagnostics | Monitor** as the primary tool to monitor the dimensioner's operation and system information in real-time. Status indicators and vital statistics appear on a single screen, enabling you to effectively and efficiently detect and troubleshoot any problems that may occur.



NOTE: The Monitor is a Java application and requires Java and the appropriate browser plug-in.

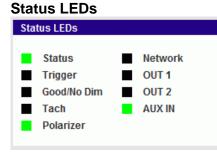
To View the Monitor:

1. In the tree menu under **Diagnostics**, click **Monitor**. The **Monitor** window opens.

Status LEDs Status Trigger Good/No Dim Tach Polarizer	Network OUT 1 OUT 2 AUX IN	System InformationBelt Speed (fpm)0Scan Rate0600Scan Rate Variance017	Legal For Trade Status Ready Show Temp Comp Scan Rate
Messages Started Legal for Trade: NOT-F CERT mode off Conveyor speed Legal for Trade: NOT-F CERT mode off Conveyor speed		101	
Message Monitor Started		Start Stop	
None Reconnect	 Serial Port 1 	O Seri <u>a</u> l Port 2	O Net Port 1 O Net Port 2

2. View system information and interact with the **Monitor** as described below.

Field Name



Action/Definition

Status – **GREEN** to indicate the overall "health" of the reader. (If **RED**, troubleshooting is required.)

Trigger – **GREEN** indicates the trigger input. The LED is activated upon trigger input regardless of trigger source (including software trigger).

Good/No Dim – **GREEN** indicates a good (valid) dimension has been calculated. **RED** indicates a no-read (or incomplete decode).

Tach – **GREEN** indicates the tachometer input. The LED is activated upon tachometer input regardless of tachometer source and indicates a non-zero belt speed.

Polarizer In – Indicates that the dimensioner's polarizer is in place.

Network – GREEN indicates a network host connection has been made. **RED** indicates a problem with the reader network.

Example: A red Network LED upon power up could indicate the MAC address is not set.

OUT 1(2) – Indicates the status of the programmable relay

AUX IN – Indicates the status of the auxiliary input relay

Belt Speed – The conveyor speed is displayed in feet per minute (fpm) or meters per second (m/s)

Belt Speed (fpm)0Scan Rate0600Scan Rate Variance012

System Information

System Information

Scan Rate – The laser scan rate is displayed in scans per second.

Scan Rate Variance – A measure of the stability of the scan rate. When this settles at a lower value it indicates a stable scan rate.

Legal For Trade Status

Temp Comp Scan Rate

Legal for Trade Status

Show

Field Name

Ready

Action/Definition

Ready – **GREEN** indicates the system settings meet Legal for Trade requirements. **RED** indicates that a system setting or performance does not meet Legal- for-Trade requirements. Click **Show** to display status details in the Message pane.

Temp Comp –

The DM3610 has a temperature compensation control loop that continuously monitors input signals (the phase reference signal amplitude for example) and makes adjustment (such as adjusting an amplifier gain) in order to maintain accurate dimension results over the 0 to 50 degree operating temperature range.

When the **Temp Comp** LED is **GREEN**, this indicates that the control loop is operating correctly and all input conditions being monitored are within tolerance of their setpoint.

When the **Temp Comp** LED is **RED**, one or more of these inputs are not within tolerance and the system is not in a state that permits it to produce accurate dimensions. When **RED**, any packages dimensioned will be marked as **NoDim** and system will be in its **Not Ready** state and not capable of producing Legal-for-Trade results.

Scan Rate – GREEN indicates that the scan rate is within the required tolerance. RED indicates that the scan rate is out of tolerance and during this time scan lines will be discarded.

Messages Messages Started Legal for Trade: NOT-READY, status = 0xa01 CERT mode off DSP signature Library signature	Displays diagnostic messages and dimension results. Click Stop to pause the message flow, and click Start to begin or unpause the message flow.			
Message Monitor	Displays the outgoing host message from the port selected below.			
Option Buttons	Select an option button for None, Serial Port 1, Serial Port 2, Net Port 1 , or Net Port 2 to view messages for that connection.			
Reconnect	Click Reconnect to re-establish communications between the Monitor page and the DM3610.			

4.12.2 Diagnostics | DimView

4

Use the **Diagnostics | DimView** to view a graphical representation of the dimension point information captured for a package.

The **DimView** monitor is explained in the image below.

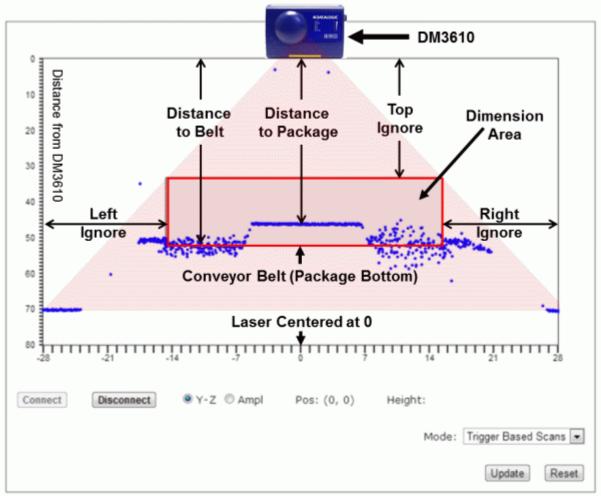
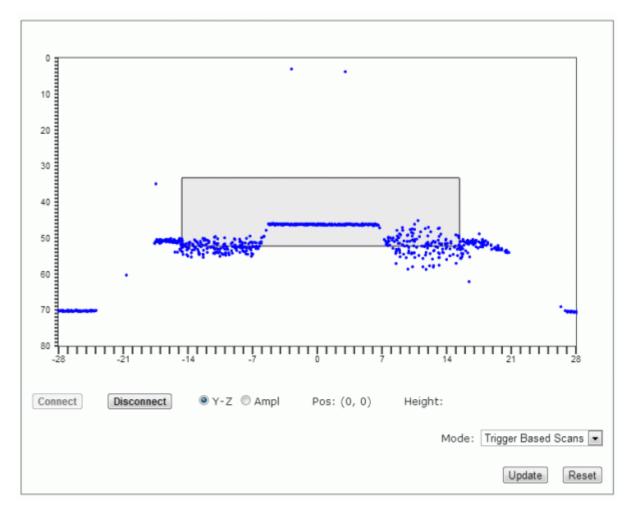


Figure 4.5: Understanding DimView

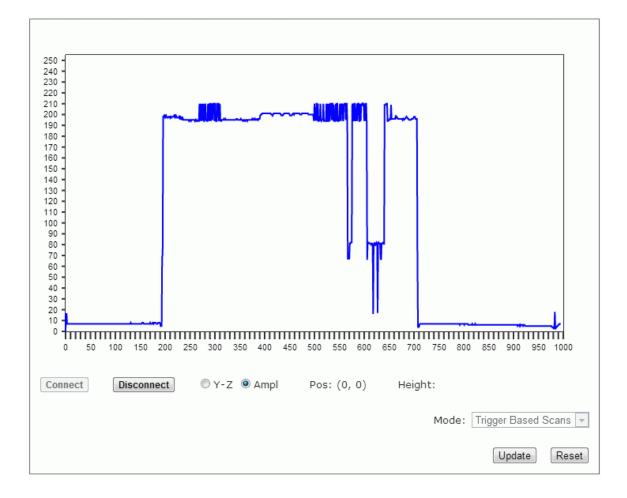
To View DimView:

1. In the tree menu under **Diagnostics**, click **DimView**. The **DimView** window opens.



2. Click Connect to activate the DimView monitor, or Click Disconnect to deactivate.

3. Use the option buttons provided to view either the Y-Z plain or wave Ampl (amplitude).



4. Select a mode from the Mode drop-down list. Mode option results are as follows:



NOTE: These options are not available when Certification Mode is on.



WARNING: If you switch from Dim-in-Head Enabled to one of the other selections your system will no longer be dimensioning packages.

Mode Selection	Action/	Action/Definition							
No Transmit	When	Vhen selected, no scan line data is transmitted. S							See
	Tach/T	rigger/Trans	mit.						
Continuous Scans	When	selected,	eve	ry s	scan	line	is	transmitted.	See
	Tach/T	rigger/Trans	mit.						

Mode Selection	Action/Definition
Trigger Based Scans	When selected, scan lines are transmitted at a slow rate, but when a trigger source is active scan lines are sent at the full rate. This mode is useful when using Diagnostics DimView. The system defaults to this mode when DIM-in-Head Enabled is turned off. See Tach/Trigger/Transmit.
Dim-in-Head Enabled	If selected, the DM3610 will use the scan point data to calculate the object dimensions within the head itself. See Dimensioning Settings.
	WARNING: If you switch from Dim-in-Head Enabled to one of the other selections your system will no longer be dimensioning packages.
Calibration Scans	When selected, this behaves like Trigger Based Scans but provides additional debugging capability to an advanced user. See Tach/Trigger/Transmit.
Averaged Scans	When selected, this behaves like Trigger Based Scans, except that it averages scan line data over time. This mode is useful when using Diagnostics DimView as it smooths away image noise. See Tach/Trigger/Transmit .

5. When you have selected a mode, click **Update** to activate it or click **Reset** to revert to the previously active mode.

4.12.3 Diagnostics | Log Viewer

The Diagnostics | Log Viewer lets you review the performance logs saved by the dimensioner.

To View the Log Viewer:

In the tree menu under **Diagnostics**, click **Log Viewer**. The **Log Viewer** window opens.

The two most commonly viewed logs are Counters and Message Logs, which are available by selecting one of the buttons:

Counters

Scan Rate(var):	0600(012)	Belt	t Speed:	0		*
Triggers:	1	Good	i Dims:	0		
No Dims:	0	Mult	: Dims:	0		
Lost Dims:	0	Miss	ed Tx:	0		
Scan Ints:	36133	Aux	Input:	8		=
Queue Size:	1024	Bad	Scan:	0		
Full Scans:	0	Mem	Full:	0		
Scans Trunc:	0	Max	Trunc:	0		
Laser Faults:	0					
ARM Restarts:	0	DSP	Restarts	: 0		
NODIM_BOX_NODIM				0		
NODIM_BOX_TOL_F			:	0		
NODIM_BOX_TOL_F	_			0		
NODIM_BOX_TOL_F				0		
NODIM_BOX_WRITE			-	0		
NODIM_BOX_SAME_		D		0		
NODIM_BOX_STACK				0		
NODIM_BOX_NO_HI				0		-
				Counters	Message Log	Clear
Command						
				(example: DI		Command

Message Log

```
DM3610 Log Viewer
0-00:00:00.000: DM3610 software DM3610_RELEASE initializing.
                                                                                           .
0-00:00:00.005: Invalid Laser ID 0.
0-00:00:00.005: Laser #1 Module Serial 0.
0-00:00:00.182: Checksum error reading ACTIVE LFT parameters from FLASH using
defaults.
0-00:00:00.182: Checksum error reading CERT LFT parameters from FLASH using
defaults.
defaults.
0-00:00:00.182: LFT parameters load failed. Active=-1, Cert=-1.
0-00:00:00.182: LFT library open failed, status = 0x10.
0-00:00:00.182: Updating FLASH with LFT Defaults.
0-00:00:00.182: Defaulting Serial Comm parameters on port #0.
0-00:00:00.182: Reset Clock Chip
0-00:00:00.382: Configure Clock Chip (0)
0-00:00:01.018: FPGA Load Complete
0-00:00:02.018: FPGA device id: 3c40.
0-00:00:02.018: FPGA version: 3.0(0).
0-00:00:02.039: Set initial APD DAC to 820, polarizer is in, prss 116, temp
35
0-00:00:02.039: Sysdata ptr = 8801d500, size=28436132
0-00:00:02.039: ArmDSP_Memory bff0 (8801d500), Sys_data 8801d500, Sys_VarPtr
8801d500
0-00:00:02.040: TX Port 0 Started.
0-00:00:02.040: TX Port 1 Started.
 -00:00:02.075: Reset Clock Chip
0-00:00:02.076: Mac Address: 00:0E:13:05:00:01
                                                                   Message Log
                                                                                     Clear
                                                     Counters
Command
                                                                            Send Command
   Use this field to enter and send commands (example: DISP ENET)
```

You can also enter a log request in the Command field.

For example: DISPENET will provide Ethernet data (No space is required between DISP and ENET as shown in the DM3610 Log Viewer above).

The log view field remains empty until you select a button or enter a command.

To determine which log is currently being shown in the log viewer, the log's name is shown just below the words log view in the window.

To use commands to view a log:

1. Enter a command in the Log Viewer Command field without using spaces (i.e., DISPCOUNTS, DISPMSGLOG, etc.)

Common Commands	Definition
CLEARALL	Clears all information from the Message Monitor.
DISPCOUNTS	Display the System Counter log view.
DISPENET	Display the Ethernet interface status, including MAC address.
DISPMSGLOG	Display the Message log view.

- 2. Click Send Command.
- 3. Log Viewer displays the most current information for the log you requested.
- 4. Click Clear to empty the Log Viewer.

4.12.4 Diagnostics | Audit and Alibi

Use Diagnostics | Audit and Alibi to search for and view system audit trail and alibi logs.

To View Audit and Alibi:

4

1. In the tree menu under **Diagnostics**, click **Audit and Alibi**. The **Audit and Alibi** window opens.

Logging Options							
Audit Trail Log			Alibi Storage Log				
AATM Options							
Query First Record							
Query Last Record							
Query Storage Statistics			Chart	-			
Query Time Range	2013 • Year	0: 💌 Month	Start Ot Day End	1. Hour	3: 💌 Minutes	5(💌 Seconds	
	2013 💌	04 💌	Ol 💌 Day	1₂ ▼ Hour	3: 💌 Minutes	5(💌	
Log File Datalogic DM3610 Dimensioning Sy. #1 2013-02-19 13:32:44		=Off [CR	C OK]				

F				
Field Name Logging Options (Dimensioning- specific)	Action/Definition Audit Trail Log Opens the Audit Trail Log for viewing in the Log File section of the screen. Results are scrollable.			
. ,	Alibi Storage Log Opens the Alibi Storage Log for viewing in the Log File section of the screen. Results are scrollable.			
AATM Options (Alibi and Audit	Query First Record Displays the first record when selected.			
Trail Manager)	Query Last Record Displays the last record when selected.			
	Query Storage Statistics Displays the storage space used and the remaining space available.			
	Query Time Range Select a Start Time and End Time by defining the Year, Month, Day, Hour, Minutes and Seconds for each.			
	NOTE : For accurate Alibi and Audit management, the dimensioner clock is set to GMT (Greenwich Mean Time) at the factory and should never be changed.			
Get Updated Log File	After making the desired selection from the option buttons, click Update to view the log in the Log File area of the screen.			

2. View system information and interact with the Monitor as described below.



4.12.5 Diagnostics | Update Firmware

Use Diagnostics | Update Firmware to reload the dimensioner firmware.



CAUTION: This function should only be performed under the guidance of Datalogic Technical Support.

To Extract Image:

1. In the tree menu under **Diagnostics**, click **Update Firmware**. The **Update Firmware** window opens.



- 2. Click Extract Image.
- 3. In Save as window, save the image (*.as) files to your computer. The graphic onscreen indicates Extract Image is in-process.



A message will appear when Extract Image is complete.

To Burn Flash:

1. Click Choose File. In the browse window, select an image file (*.as) to burn to flash.



NOTE: The appearance of these functions may vary from browser to browser.

2. Click Burn Flash.



The graphic on-screen indicates Burn Flash is in-process.

3. A message will appear when Burn Flash is complete.

4.12.6 Diagnostics | Help

4

Clicking **Diagnostics | Help** opens the full online help system for the DM3610 User Interface. You can use the **Contents, Index,** and **Search** options of the online help system to find information about and procedures for configuring and using the DM3610.

🙀 Contents 🗧 Index 🏴 Search	- Search - GO
2 Home 2 Getting Started 2 User Interface Basics 1 Modify Settings	Home > Home Home Home
 Configuration Dimensioning Settings Calibration Tach/Trigger Network Network Settings Message Definition #n Serial Port #n Message Definition - Port#n Save/Retrieve Diagnostics Monitor DimView Log Viewer Audit and Alibi Update Firmware 	The DM3610 is Datalogic's laser-based, compact dimensioning solution. The user interface provides an easy-to-use series of configuration and diagnostics features that enable you to have your dimensioner up and running in minutes. Because the interface is browser-based, you can remotely configure and monitor reader performance using an Ethernet network connection and your desktop or laptop computer. Getting Started
	Click on any of the links below to learn how to access and use some of FAST Monitor's best features:
	<u>Getting Started</u> <u>User Interface Basics</u>
	Modify Settings
	• <u>Diagnostics</u> Contact
	Telephone: 1-800-BAR-CODE™ or 215-723-0981
	E-mail: info.automation.us@datalogic.com
	Website: www.datalogic.com
	\$DATALOGIC
	Copyright © 2013 Datalogic. All rights reserved.
	DM3610 Online Help Revision 2.0
	This manual refers to software package x.xx and later

Notes:

5 DIMENSIONING FEATURES

This chapter provides details on how the DM3610 Dimensioning System functions during normal operation. It also helps familiarize the user with status indicator LEDs, Control Panel operation, system calibration, and how the DM3610 can be easily and quickly be replaced with a new unit if necessary.



5

IMPORTANT: The procedures outlined in this chapter should only be performed by a Datalogic trained technician.

Training is available through specific Service Programs and Maintenance Agreements. See our website at <u>www.datalogic.com</u>.

5.1 HOW THE DM3610 DIMENSIONER WORKS

The DM3610 uses a modulated laser and rotating mirror wheel to take height range at close intervals. The phase shift between the transmitted laser and its subsequent reflection is used to calculate the distance to the object being scanned. Successive scans on a package passing through the scan line are used to define the edges of the package, and therefore length and width.

A high resolution conveyor tachometer (optional) is used to measure the speed of the conveyor as an aid in calculating package length, and a photoelectric sensor can be used as a trigger.

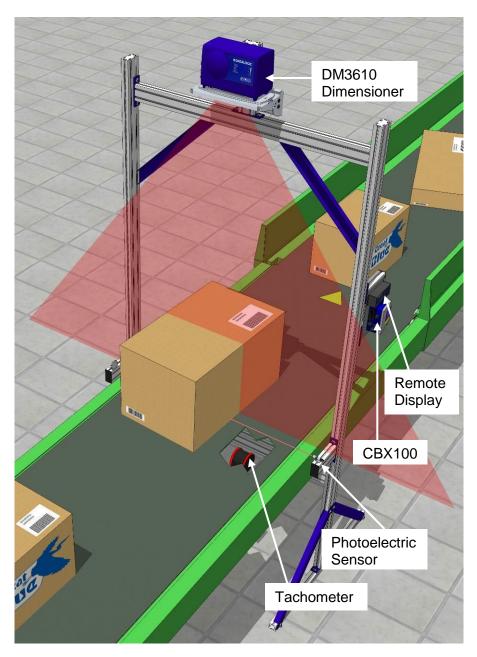


Figure 61: DM3610 Determining Package Height

5.1.1 How the DM3610 Dimensions Packages

The following steps explain how the DM3610 dimensions packages:

Step 1: As a package approaches the DM3610, it breaks the beam of the photoelectric sensor (if present). The tachometer connected to the DM3610 continually measures the speed of the conveyor, sending a constant number of tachometer pulses per unit of measure. This tracks the position of the package as it moves through space. If no photoelectric sensor is present, a non-zero scan of the DM3610 acts as the trigger.

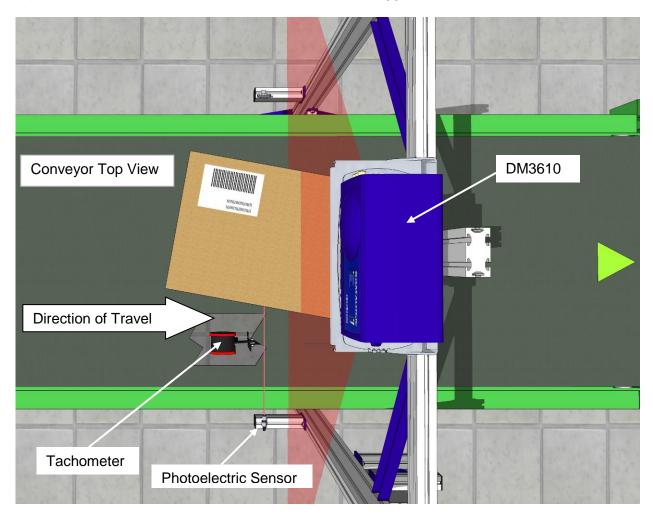


Figure 62: DM3610 Dimensioning Overview

While the tachometer relays the conveyor speed, the DM3610 is constantly scanning across the conveyor belt, gathering range data at close intervals. When the package intersects the modulated laser scan line of the DM3610, the phase shift determines the distance at a multitude of specific points across the field. The software then calculates the height measurement of the object.

Step 2: The height measurements taken with each scan line, are then repeated on successive scans as the package moves under the dimensioner's laser. The resulting height data is used in conjunction with the tachometer counts to create a profile of the package.

Step 3: The DM3610 discards the data outside the edges of the packages. The height measurement of the package is obtained by averaging all of the height sample points on top of the box.

Step 4: The edge points are then processed by an algorithm that filters and arranges them into components of four straight lines (the four sides of the package) and correlates this with the conveyor speed determined by the tachometer, to determine the length, width, height and volume of the package.

Step 5: An algorithm connects the edge points to create the outline of the package.

This sequence explains the data gathered for the DM3610 to use in determining the dimensions of a package.

5.2 INDICATORS

5

The DM3610 has twelve (12) LEDs on the control panel.

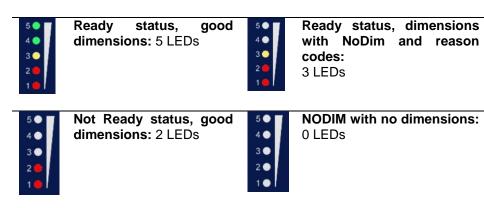


Figure 63: DM3610 Control Panel

The indicators have the following functions:

LED	Description		
STATUS	Solid GREEN indicates the overall good health of the unit.		
	(If RED , see chapter 8, Troubleshooting.)		
	Flashing GREEN indicates that the laser has been shut off using the "!" button on the control panel.		
TRIGGER	Indicates the trigger input. The LED is activated upon trigger input regardless of trigger source (incl. software trigger).		
ТАСН	Indicates a non-zero belt speed, i.e.: the belt is in motion.		
READ	Flashes red or green based upon the software criteria. READ = Dimension.		
RX/TX	LED for serial port 1. GREEN = Transmitting data		
	RED = Receiving data		
NETWORK	Flashes red or green to indicate connection status.		
	GREEN indicates at least one active host connection.		
	RED indicates an internal software error or no MAC address found		

LED	Description
BAR GRAPH LEDs (LEDs 1 - 5)	• Power Up: LEDs #3, #5 and #1 go on for a second or two, then LEDs #2 and #4 join in, then they all go out.
	• Dimension quality indicators flash once for each package (except NODIM)



• Flashes when a parameter save/retrieve operation is initiated by the **arrow buttons** on the control panel.

Fast twinkle, 5 LEDs				
Waiting for Confirm				
Light consecutively, LEDs 5 to 1 (save) or 1 to 5				
(retrieve)				
YELLOW on solid, 1 LED (#3)				
GREEN on for 2 seconds, 2 LEDs (#4 and #5)				
RED on for 2 seconds, 2 LEDs (#1 and #2)				

- When firmware is being updated, Bar Graph LEDs #1, 2, 4, and 5 stay on while #3 blinks.
- Bar Graph LEDs stay on when A is pressed during the laser shutoff or turn on procedure.

When \bigtriangleup is pressed for 5 seconds to toggle the laser on or off, the Bar Graph LEDs 1-5 stay on. LEDs 1-5 go out to indicate the laser has now been turned off *or* on

5.3 CONTROL PANEL BUTTONS



Figure 64: Control Panel Buttons

Ref	Button	Description
	Restore	 Restores parameters from CBX100 backup module to DM3610 Button must be pressed twice to initiate action. See below for procedure.
₽	Backup	 Downloads parameters from DM3610 to CBX100 backup module Button must be pressed twice to initiate action. See below for procedure.
	!	Used for both laser shutoff and recovery
	Laser Shutoff	Hold in to perform laser shutoff.
	Recovery	 Hold in while cycling power. In the browser, navigate to default IP 192.168.3.100. The browser displays software version and current IP address for the unit.



5

REMEMBER: DM3610's control panel buttons can be enabled / disabled through the User Interface on the **Modify Settings | Configuration** window. (See chapter 4, User Interface.)

5.4 CONTROL PANEL BACKUP AND RESTORE PROCEDURE

To backup parameters from DM3610 to the CBX100 backup module:

- 1. Make sure the BM100 write protect switch is in the unlocked position (see Figure 65).
- 2. Press and hold **I** for one second or more. When you release the button you will notice the Bar Graph LEDs (1-5) flashing quickly.
- 3. Press 💽 again for less than one second.

If the download initiation is successful, the Bar Graph LEDs will cycle (5 to 1), and then LED 3 (yellow) will light indicating the parameters are being transmitted to the BM100. Next, LEDs 4 & 5 will light for 2 seconds, and when they turn off, the save is complete.

If the Bar Graph LEDs never cycle (5 to 1) then the parameters were not saved and you must repeat step 1 and 2 again.

4. Once parameters have been saved, you can protect the parameters by placing the backup module's write protect switch in the lock position. *See Figure 65.*

To restore parameters the CBX100 backup module to the DM3610:

- 1. On the DM3610 interface panel, press and hold for at least one second. When you release the button you will notice the Bar Graph LEDs (1-5) flashing quickly.
- 2. Press again for less than one second. If the action was successful, the Bar Graph LEDs (1 to 5) will cycle, and then LED 3 (yellow) will light indicating the parameters are being retrieved from the BM100. Next, LEDs 4 & 5 will light for 2 seconds, and when they turn off, the retrieval is complete.

If, however, the Bar Graph LEDs never cycle (1 to 5) with an upward motion, the parameters were not retrieved and you must repeat step 1 and 2 again.



NOTE: Please note that the B&R button on the backup module inside the CBX100 should not be used.

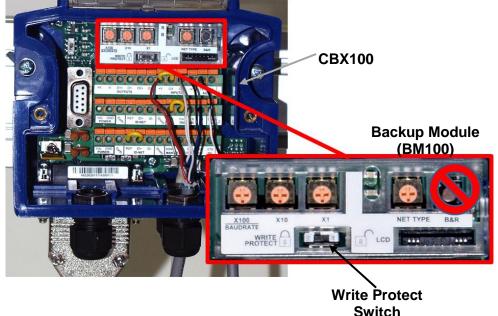


Figure 65: CBX100 with BM100 backup module installed



NOTE: If the parameters were saved to a file on your PC hard drive or on a network using the DM3610 User Interface, they can be retrieved and uploaded to the DM3610. See *Modify Settings | Save/Retrieve in chapter 4.*

5.5 REPLACING AN INSTALLED DM3610

If you ever need to replace your DM3610, the following procedure will allow you to do so with the least interruption to operations.



IMPORTANT: This process should be performed by a certified Datalogic field service technician or a Datalogic trained and certified customer technician.

Prerequisites:

- Product Specification or Product requirements document
- A PC equipped with a web browser like Mozilla Firefox or Internet Explorer (Not needed if only using Interface panel buttons for parameter backup and retrieval)
- Set of Metric Hex wrenches
- Calibration kit boxes (See section 5.6 Dimensioner Calibration)

5.5.1 Saving the Parameter Data to the Backup Module

DM3610 parameters should be saved to the backup module as the final step of the setup procedure. However, if you feel this may not have been completed, you should save DM3610 parameters to the backup module now if possible. DM3610 parameters should be saved to the backup module and to a file on your computer or network for each installed unit.

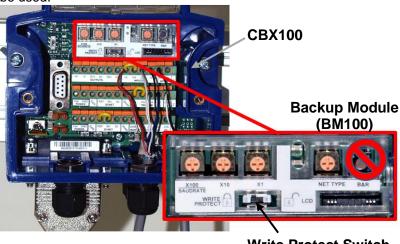
There are three buttons on the DM3610 interface panel. The down arrow button is used to save the parameter file to the backup module (BM100), which is installed inside the CBX100 Interface Box.



Figure 66: DM3610 Control Panel



NOTE: Please note that the B&R button on the backup module should not be used.



Write Protect Switch

Figure 67: CBX100 with BM100 backup module installed

To Save the Parameters to the Backup Module:

- 1. Make sure the BM100 write protect switch is in the unlocked position (see Figure 5.7).
- 2. Press and hold if for one second or more. When you release the button you will notice the Bar Graph LEDs (1-5) flashing quickly.
- 3. Press 💽 again for less than one second.

If the download initiation is successful, the Bar Graph LEDs will cycle (5 to 1), and then LED 3 (yellow) will light indicating the parameters are being transmitted to the BM100. Next, LEDs 4 & 5 will light for 2 seconds, and when they turn off, the save is complete.

If the Bar Graph LEDs never cycle (5 to 1) then the parameters were not saved and you must repeat step 1 and 2 again.



NOTE: The parameters can also be saved to a file on your PC hard drive or to a network through the DM3610 User Interface. See *Modify Settings | Save/Retrieve in chapter 4.*



NOTE: If the unit is still able to provide dimension information, run the calibration kit boxes through the system to determine whether the current unit is still in calibration. If the correct dimensions are not returned by the unit, make adjustments to the settings to correct the issue, and then record the parameters.



NOTE: Please make note of the IP address of the unit. You will need to switch back to this after you restore the parameters if the IP address is other than the default.

To find the unit's IP address, in the user interface menu tree under **Modify Settings**, navigate to **Network | Settings**. The unit's IP address is displayed in the **IP Address 1** text fields.

5.5.2 Removing the Existing DM3610

- 1. Remove power from the DM3610.
- 2. Label and then disconnect all cables from the side panel. It is a good practice to label all the cables so they can easily be reconnected to their original location.

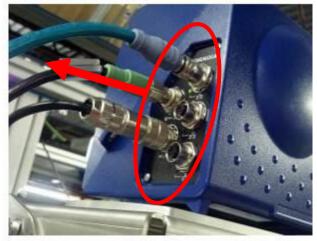


Figure 68: Remove Cables from DM3610

3. Remove the three bolts on the bottom of the Universal Mounting Bracket (UMB) shown below using a 4mm Allen[™] wrench.



Figure 5.9: Mounting bolt location



Figure 69: Removing a mounting bolt

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- 4. Once these screws are removed lift the unit straight up and off the 3 hollow Spirol[™] spring dowels. These dowels are used to ensure each unit is mounted in exactly the same place.
- 5. Place the three screws you just removed in the hollow Spirol[™] spring dowels from the top while unpacking the new unit so they don't get misplaced.

5.5.3 Installing the Replacement DM3610



NOTE: It is important to avoid getting finger prints on the exit glass while installing the new unit.

- 1. Remove the three screws from the hollow Spirol[™] spring dowel holes (if you placed them there at the end of the removal operation.
- 2. Place the new DM3610 on the three hollow Spirol[™] spring dowels as shown below.

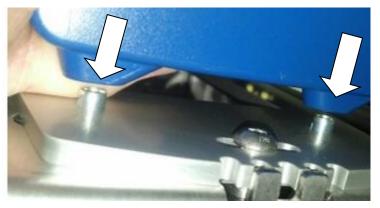


Figure 70: Placing DM3610 on the hollow Spirol™ spring dowel

3. Once all three pins are aligned and the replacement DM3610 is resting flat on the UMB mounting plate, insert the three screws using a 4 mm Allen[™] wrench as shown below.

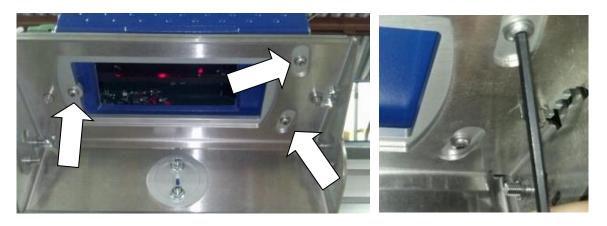


Figure 71 and Figure 72: Securing the DM3610

4. Reconnect all the cables on the side panel as they were previously installed.



Figure 73: Cable connections

5. Reconnect the power to the DM3610.

5.5.4 Restoring the Parameter Data from the Backup Module:

- 1. On the DM3610 interface panel, press and hold for at least one second. When you release the button you will notice the Bar Graph LEDs (1-5) flashing quickly.
- 2. Press again for less than one second. If the action was successful, the Bar Graph LEDs (1 to 5) will cycle, and then LED 3 (yellow) will light indicating the parameters are being retrieved from the BM100. Next, LEDs 4 & 5 will light for 2 seconds, and when they turn off, the retrieval is complete.

If, however, the Bar Graph LEDs do not cycle (1 to 5) with an upward motion, the parameters were not retrieved and you must repeat step 1 and 2 again.



NOTE: Please note that the B&R button on the backup module inside the CBX100 should not be used.

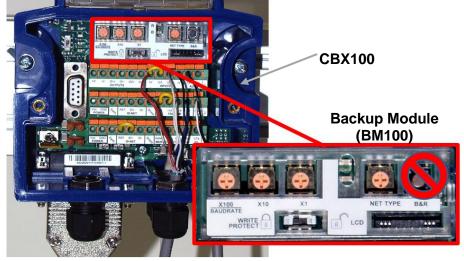


Figure 74: CBX100 with BM100 backup module installed



NOTE: If the parameters were saved to a file on your PC hard drive or on a network using the DM3610 User Interface, they can be retrieved and uploaded to the DM3610. See *Modify Settings | Save/Retrieve in chapter 4.*

5.5.5 Checking the Operation of the Replacement DM3610

Once the replacement unit is in place and the previously saved parameters have been uploaded, check the calibration of the unit by running some test boxes through the system. If the calibration is not within tolerances, *see all sub-paragraphs under 5.6* in this chapter for instructions on calibrating the DM3610.

5.6 DIMENSIONER CALIBRATION

Now that you understand how the dimensioner "sees" objects on the belts, let's look how the system is able to relate the point data to real world measurements.

After the dimensioner is installed, it needs to be calibrated to its installed position over the conveyor so that its engineering units of measurement can be converted to real world units (e.g., mm/inches). Once its position in relation to the conveyor has been established, test boxes of known dimensions are run through the system and various factors are adjusted until the system is able to measure the test boxes within +/- 5mm [0.2"] tolerance.

To facilitate calibration, a Calibration Kit is available from Datalogic in either Metric or Imperial versions.

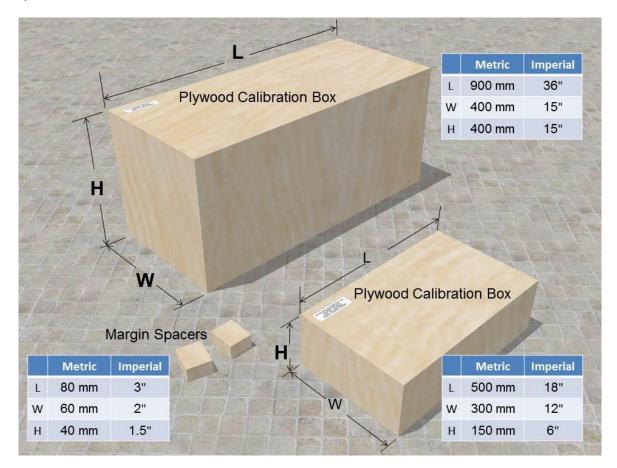


Figure 75: DM3610 Calibration Kit

5.6.1 Static Calibration

The process of static calibration locates the dimensioner in space above the conveyor. It is important that the dimensioner is properly installed (See chapter 2, **Mechanical Installation**) on a sturdy mounting structure with minimal vibration or sway. Any movement of the structure will negatively affect the accuracy of the dimension data.

Many of the settings necessary for calibration are determined automatically using the **Find Belt** command in the User Interface, including:

- Left/right limits of the DM3610 coverage
- DM3610 mounting height
- Scan Points

- Field of View
- Angle Offset

To begin calibration:

- 1. Apply power to the DM3610.
- 2. Establish a connection to the DM3610 User Interface and log on as discussed in *chapter 4*.
- 3. Using the menu tree, navigate to Modify Settings | Dimensioning | Settings.
- 4. For calibration purposes, enter the height of the maximum package size that will be run through your dimensioning system in the text field provided.

DIM-in-Head Enabled	Off	•
Units	Inch	•
Length Reporting	Descending Order	•
Certification Mode	Off	
Length, Width Resolution (d)	0.2 inch	
Height Resolution (d)	0.1 inch	
Minimum Package Size	Length (in) Width (in)	2.4
	Length (in)	2.4
	Height (in)	2.4
	Length (in)	98.0
Maximum Package Size	Width (in)	48.0
	Height (in)	36.0
Discard Package Size	Length/Width (in)	0.5
Discard Fackage SIZE	Height (in)	0.5

5. Click **Update** to save your changes.

Defining the Belt Width

5

When calibrating your dimensioner, you must help the dimensioner find the width of the conveyor belt. If the conveyor does not have side rails, and there is no transitional edge past the edge of the conveyor belt, it will be necessary to place spacers on the left and right side of the conveyor belt. The side margins allow the DM3610 to identify the non-dimensioning area or "ignores" to the right and left side of the belt.

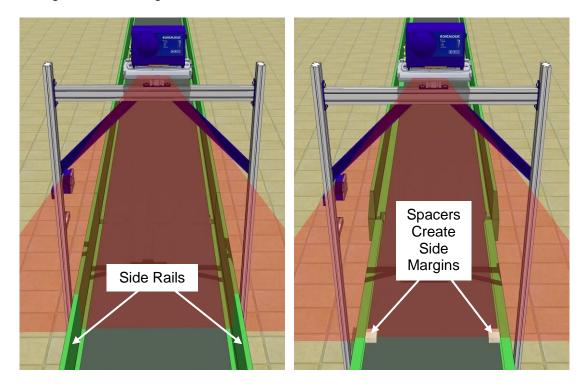


Figure 76: Defining Belt Edges

Since there is only one field in the User Interface to enter the size of the side margins, the two spacers creating the side margins must be the same width and height.

To define the belt width using margin spacers:

1. With the DM3610 powered up and access to the User Interface with a computer, place the spacers at the edge of the conveyor belt within the dimensioner's laser line. If space allows, the spacer can be placed outside the edges of the belt, if not, place the spacers along the edges of the belt as shown below.

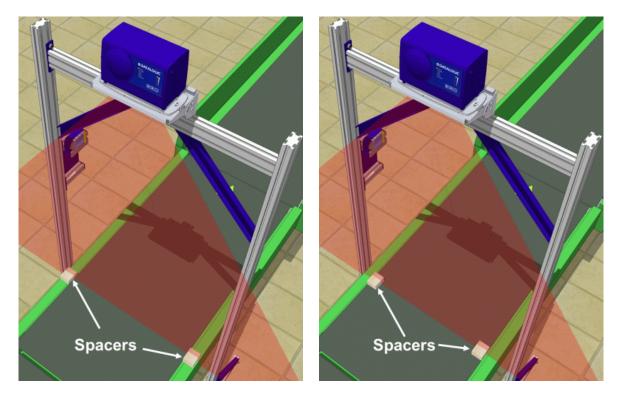


Figure 77: Placing the Spacers

- 2. In the User Interface, navigate to Modify Settings | Dimensioning | Calibration.
- 3. Enter the width of the spacers in the Side Margins text field.

Belt Analysis Side Margins	0	in	Find Belt	Use Belt
Side Margins	P		1 III Delt	030 Delt
Dimensioning Area				
Scan Points (100-1000)	1000		0	
Field of View (2-73°)	73		0	
Angle Offset (0-32°)	16		0	
Scanner Height	64	in	0	in
Left Ignore	21.875	in	0	in
Right Ignore	21.875	in	0	in

If the spacers are placed outside the edges of the conveyor belt, enter a value of 0 (zero) in the **Side Margins** text field. This also applies if the conveyor has side rails.

If the spacers are placed on top of the conveyor belt aligned with the edges of the belt, enter the width of the spacers in the Side Margins text field.



IMPORTANT: Since the Side Margins text field only allows one value, the spacers must have the exact same width.

 Click Find Belt. When clicked, the dimensioner runs calculations to provide the Scan Points, Field of View, Angle Offset, Scanner Height, Left Ignore, and Right Ignore in the greyed fields included in the Dimensioning Area of the window.

de Margins	3	in	Find Belt	Use Belt
nensioning Area				
an Points (100-1000)	1000		590	
eld of View (2-119°)	73		59	1
gle Offset (0-32°)	16		20.6	1
anner Height	64	in	52.375	in
ft Ignore	21.875	in	14.71875	in
ght Ignore	21.875	in	15.4375	in



NOTE: When **Find Belt** is clicked, the system calculates the dimensioner's position over the conveyor. If the system determines that the dimensioner is not centered on the belt, it will return this message:

WARNING: DM3610 mounting misses belt center by more than 1". Recommend remounting.

If the system determines that the mounting height compared to the system's maximum package size (See **Modify Settings | Dimensioning | Settings** *in chapter 4*) does not allow the system to adequately dimension the package, it will return this message:

WARNING: FINDBELT calculated FOV > 73°. Confirm Maximum Package Height setting and check DM3610 mounting height.

If the system determines that the mounting height is above 1727mm [68"], it will return this message:

WARNING: FINDBELT calculated Scanner Height > 68". Recommend mounting DM3610 lower.

The **Find Belt** calculation measures the dimensioner height from the bottom of the DM3610 housing to the belt. *Maximum* height to this point for best results is 1727mm [68"].

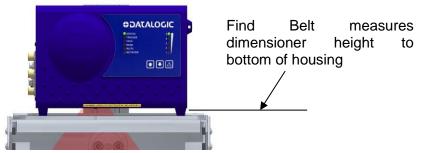


Figure 78: Find Belt height indicator

5. Click **Use Belt** to use the data calculated by **Find Belt** when dimensioning packages.

Side Margins	3	in	Find Belt	Use Belt	
Dimensioning Area					
Scan Points (100-1000)	590		590	[
Field of View (2-119°)	59		59	[
Angle Offset (0-32°)	20.6		20.6	[
Scanner Height	52.375	in	52.375	in	
Left Ignore	14.71875	in	14.71875	in	
Right Ignore	15.4375	in	15.4375	in	

6. Click **Update** to save the data in the system.

5.6.2 Dynamic Calibration

5

The final part of the calibration operation involves adjusting the system settings in the DM3610 User Interface to match the requirements of your application and then running test boxes through the system to test its accuracy.

To adjust system settings for your specific application:

- 1. Open the DM3610 User Interface and adjust the following items to match your application (See chapter 4, User Interface):
 - Tachometer
 - Trigger
 - Transmit Point
 - Communications
 - Relays
- 2. Configure the **Modify Settings | Dimensioning | Settings** window according to the application specifications. (See chapter 4, User Interface)

DIM-in-Head Enabled	Off	-	
Units	Inch	•	
ength Reporting	Descending Order	•	
Certification Mode	Off	•	
Length, Width Resolution (d)	0.2 inch	•	
Height Resolution (d)	0.1 inch		
ackage Size Options			
	Length (in)	2.4	
Minimum Package Size	Width (in)	2.4	
	Height (in)	2.4	
	Length (in)	98.0	
Maximum Package Size	Width (in)	48.0	
	Height (in)	36.0	
	Length/Width (in)	0.5	
Discard Package Size	Height (in)	0.5	

3. Start the conveyor.



WARNING: Make sure the work area and conveyor are clear of people and debris. Warn others working in the area that you are starting the conveyor and that they should stand clear.

- 4. Navigate to the **Diagnostics | Monitor** window in the User Interface.
- 5. Run one of the calibration boxes through the system.
- 6. Compare the dimensions reported by the DM3610 on the **Monitor** window with the actual size of the box.

7. The box run for this example is the $18 \times 12 \times 6$ " box from the Imperial measurement calibration kit.

Status LEDs Status Network Trigger OUT 1 Good/No Dim OUT 2 Tach AUX IN Polarizer	System Information Bett Speed (fpm) 110 Scan Rate 0600 Scan Rate Variance 019	Legal For Trade Status Ready Show Temp Comp Scan Rate	Messages
Message: Stated 18.1 12.0 B.1 in;NOTREADY			Started 18.1 12.0 6.1 in;NOTREADY

If the length of the box is within system tolerance, your system is ready to run.

If, however, length of the box is NOT within specification, you can make small adjustments to correct the dimension in the Tach Scale Factor input field found on the Modify Settings | Tach/Trigger/Transmit window.

Tachometer Tach Source Hardware/External Pulse per in 16.00 Tach Scale Factor 1.000 Tach Controlled Laser	Trigger Trigger Source Hardware Trigger Polarity Active High Debounce Duration (ms) 10 Trigger Reference Point 6.0
Transmit Transmit Edge Trailing Edge ▼ Transmit Point 20.0 in	Tach Scale Factor

- 8. If adjustments need to be made, change the **Tach Scale Factor** by fractional increments. For example, try changing the **Tach Scale Factor** from 1.000 to 0.998.
- 9. Click **Update** to save the change.
- 10. Run the test box through the system and continue to adjust the **Tach Scale Factor** until the dimensions fall within the requirements for your system.

6 MAINTENANCE

6.1 OVERVIEW

This chapter provides instructions for maintaining optimum performance and life for your DM3610. It provides specific information on:

- Maintenance Procedures
- Exterior Cleaning
- Mounting Hardware Checks
- Wiring Connection Checks

Item	Description
Soft-bristle brush	For cleaning the DM3610's exterior
Clean, soft cloths	For cleaning the DM3610's exterior
Cleaning solutions	Mild detergent solution for cleaning the DM3610's exterior.
	70% denatured alcohol, 30% de-ionized water solution for cleaning exit window
Soft cotton swabs or lint-free cloth	Use to clean DM3610 reader's exit window

Tools and Materials Required



IMPORTANT: Due to the complex and application-specific nature of dimensioning / certified dimensioning installations, the DM3610 must be setup and serviced by authorized technicians trained by Datalogic.

The maintenance procedures in this chapter may be performed by an end user technician. Training is recommended if the end user intends to do more than the maintenance procedures provided in this chapter.

There are no user serviceable parts within the DM3610 Dimensioner. **DO NOT OPEN THE UNIT.** Opening the DM3610 may void its warranty.

CAUTION: Proceeding with any setup, calibration, or service procedures without proper training may void the warranty.

Training is available through specific Service Programs and Maintenance Agreements. See our website at <u>www.datalogic.com</u>.



CAUTION: RISK OF EXPLOSION IF BATTERY IS REPLACED BY AN INCORRECT TYPE.

PROPERLY DISPOSE OF USED BATTERIES.

6.2 MAINTENANCE TASKS

Perform the maintenance tasks on an "as needed" basis to assure proper operation of the DM3610. Task schedule frequency depends upon the application environment conditions. It only requires a few minutes to complete each maintenance task.

6.2.1 Exterior Cleaning



WARNING: Shut down the DM3610 before performing this maintenance task. Do not stare into the DM3610's exit window at the laser light. Avoid direct eye exposure. The laser light level does not constitute a health hazard, however staring at the laser light for prolonged periods could result in eye damage.



CAUTION: Do not use any chemical on the DM3610 that is unsafe for plastics, such as benzene, acetone, or similar products. Before performing this maintenance task, be sure to shutdown the DM3610.

The exterior cleaning procedure may be performed without removing the reader from the mounting structure.

- 1. Turn off the DM3610 by disconnecting the power source.
- 2. Clean the exterior (except the exit window) with a clean, soft-bristle brush. Be sure not to brush any dust, dirt, or debris onto the exit window.
- 3. Carefully remove any debris in or around the exit window.
- 4. Wipe the exterior (except the exit window) with a clean, soft cloth dampened slightly with a mild detergent solution.
- 5. The exit window should be cleaned after this task is completed.

6.2.2 Cleaning the Exit Window



WARNING: Shut down the DM3610 before performing this maintenance task. Do not stare into the DM3610's exit window at the laser light. Avoid direct eye exposure. The laser light level does not constitute a health hazard, however staring at the laser light for prolonged periods could result in eye damage.



CAUTION: Never apply cleaning solution directly to the exit window. Always apply the solution to a cloth, and then the cloth to the window. Do not use any chemical on the DM3610 that is unsafe for plastics, such as benzene, acetone, or similar products.

The exit window cleaning procedure may be performed without removing the reader from the mounting structure if it is possible to do so.

- 1. Turn off the DM3610 by disconnecting the power source.
- 2. Follow the exterior cleaning procedure before cleaning the exit window
- 3. Check the exit window surface for any dust, dirt, or smudges. If the window needs to be cleaned, proceed to Step 4.
- 4. Make a solution of seven parts denatured alcohol and three parts water.
- 5. Apply the cleaning solution to a cotton swab or lint-free cloth.
- 6. Apply the cleaning solution to the exit window.
- 7. Remove any streaks or remaining moisture from the exit window with a dry, soft, lintfree cloth or lens paper.
- 8. Verify DM3610 operation.

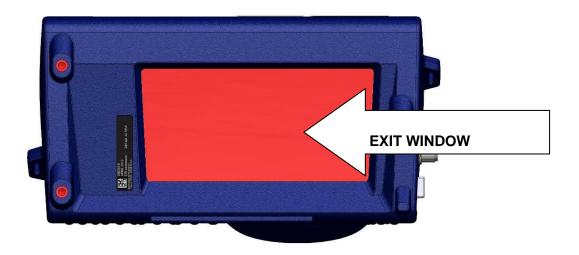


Figure 79: DM3610 Exit Window Location

6.2.3 Cleaning the Photoelectric Sensor

If your application uses the photoelectric sensor option as a hardware trigger, be sure to clean the photoelectric sensor periodically as outlined below.

- 1. Turn off the product transport.
- 2. Turn off the DM3610 by disconnecting the power source.
- 3. Clean the photoelectric sensor's lens using the denatured alcohol solution and a cotton swab or lens paper.
- 4. Clean the reflector using the denatured alcohol solution and a cotton swab or lens paper.
- 5. Verify photoelectric sensor operation.

6.2.4 Cleaning the Tachometer

6

If your application uses the tachometer option for tracking purposes, be sure to clean the tachometer wheels periodically as outlined below.

- 1. Turn off the product transport.
- 2. Turn off the DM3610 by disconnecting the power source.
- 3. Using a clean, soft cloth, wipe the wheels of the tachometer clean using a mild detergent solution.
- 4. Before restarting the system, be sure the tachometer is making good contact with the product transport.
- 5. Verify tachometer operation.

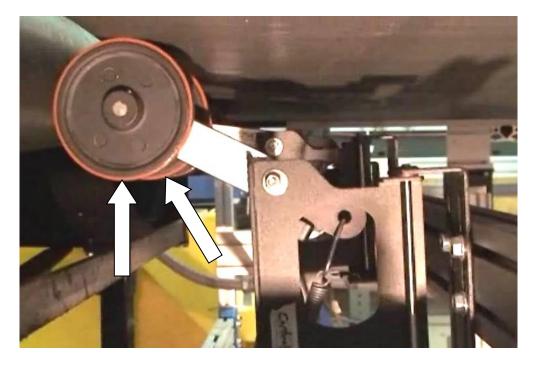


Figure 80: Tachometer Wheel

6.2.5 Tighten Mounting Hardware

- 1. Check all DM3610 Dimensioner, CBX100 connection box, and power supply mounting hardware. Tighten as necessary. Do not over-tighten. Be sure not to disturb the equipment's alignment as it relates to the product transport.
- 2. Check the mounting hardware of the Photoelectric Sensor (if this option is being used). Tighten as necessary. Do not over-tighten.
- 3. Check the mounting hardware of the tachometer (if this option is being used). Tighten as necessary. Do not over-tighten.

6.2.6 Checking Dimensioning System Connections

Wiring connections to the DM3610 are made to the connector panel and CBX100. (See chapter 3, Electrical Installation.)

- Check all wiring connections to the connector panel. Tighten any loose connections as necessary. Do not over-tighten.
- 2. Check all wiring connections to the CBX100. Tighten any loose connections as necessary. Do not over-tighten.
- 3. Check all cabling/conduit for signs of wear/damage. Repair/replace any damaged cable connections as necessary.

6.2.7 Verify DM3610 Operation

If after performing maintenance, the DM3610 system continues to perform below the normal operations experienced with the system under normal daily conditions, contact Datalogic through the **Technical Support** page on our website at <u>www.datalogic.com</u>.

6.2.8 Verify Photoelectric Sensor Operation

- 1. Block the Photoelectric Sensor emitter beam to confirm it is aligned properly with the reflector.
- 2. Verify that the TRIGGER LED on DM3610 is green when photoelectric sensor beam is blocked.
- 3. If the photoelectric sensor's LED does not change status, adjust the photoelectric sensor so that it is properly aligned with the reflector.
- 4. If the TRIGGER LED on the DM3610 is not green when the photoelectric sensor's beam is blocked, check the cabling between the photoelectric sensor and CBX100 for damage.

6.2.9 Verify Tachometer Operation

- 1. Rotate the tachometer wheel.
- 2. The TACH LED on the DM3610's connector panel should flash indicating the tachometer is operational.
- 3. If the TACH LED does not flash when the tachometer wheel is rotated, check the cabling between the tachometer and the CBX100 for damage.

7 TROUBLESHOOTING

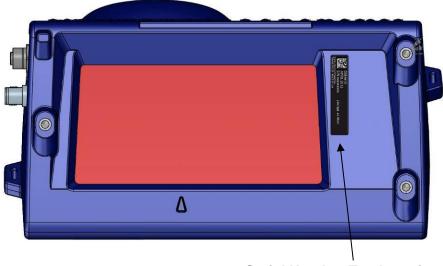
IMPORTANT: Due to the complex and application-specific nature of dimensioning / certified dimensioning installations, operational deficiencies of the DM3610 must be diagnosed and serviced by a trained and authorized Datalogic technician.

There are no user serviceable components or field replaceable units (FRUs) inside the DM3610.

Training is available through specific Service Programs and Maintenance Agreements. See our website at <u>www.datalogic.com</u>.



NOTE: When contacting Datalogic Technical Support for help with a DM3610 Dimensioner, please be ready to share the unit serial number with the Datalogic technician. The unit's serial number tag is located on the bottom of the device, as shown below. Technical Support for Industrial Automation Products is available at <u>www.datalogic.com</u>.



Serial Number Tag Location

Figure 81: Serial Tag Location

7.1 ERROR CODES AND RESOLUTIONS



7

NOTE: The following error codes pertain to a DM3610 using certified dimensioning. If the DM3610 is providing volume information only, some of these codes do not apply.

Error Code(s)	Possible Cause	Corrective Action
SUCCESS	N/A	None
BOX_BAD_HISTOGRAM	Parcels are not cuboidal and present non-squared	Run a calibration box to confirm whether the
BOX_LONG_SIDE_VEC_ERR	corners to the DM3610	DM3610 is returning accurate dimensions
BOX_LONGEST_SIDES_ERR	Black parcel reflectivity is below DM3610's reflectivity	Confirm that all parcels
BOX_MAX_COSINE	minimum	passing under the DM3610 are cuboidal
BOX_MAX_COSINE2	Parcels may be highly specular and may cause	Determine whether parcel
BOX_PEAK_VS_BORDER	false transitions in the DM3610	material may be causing the problem. (i.e. Specular)
BOX_PEAK_VS_INTERNAL	Dinico ro	
BOX_POINT_BORDER_DIST		Replace the DM3610
BOX_POINT_COUNT_ERR		
BOX_SHORT_SIDE_VEC_ ERR		
BOX_SIDES_TOO_NOISY		
BOX_TOO_FEW_SIDE_ POINTS		
BOX_NO_HISTPEAKS		

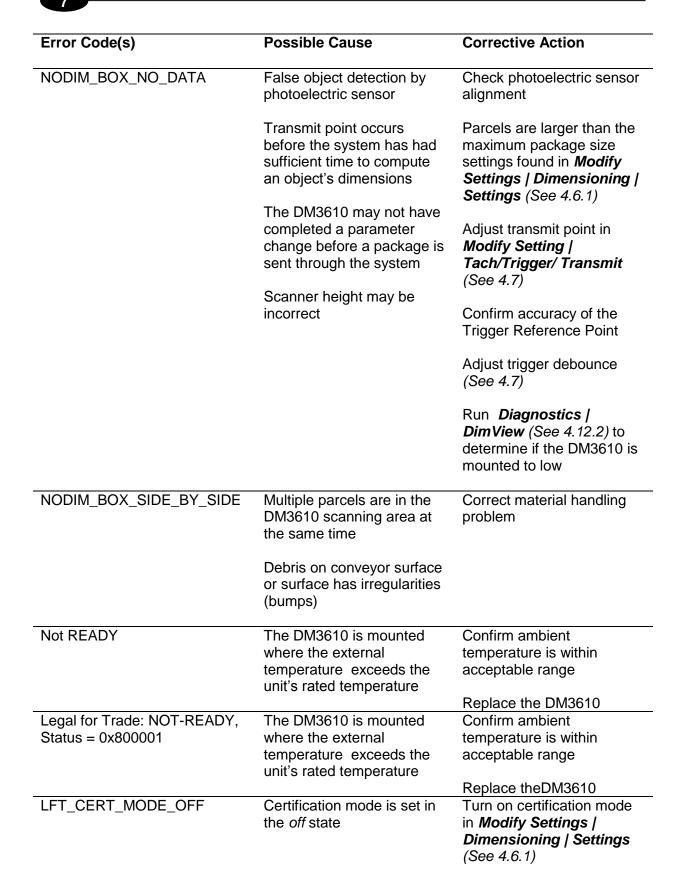
Error Code(s)	Possible Cause	Corrective Action
BOX_NODIM_UNKNOWN	Parcels are not cuboidal and present non-squared corners to the DM3610 Black parcel reflectivity is below DM3610's reflectivity minimum	Confirm the parcels are within the minimum/ maximum package size options set in <i>Modify</i> <i>Settings Dimensioning </i> <i>Settings (See 4.6.1)</i> Run a calibration box to determine whether the DM3610 returns no dimensions or only dimensions for certain packages Run <i>Diagnostics </i> <i>DimView (See 4.12.2)</i> in the user interface to determine whether the
		DM3610 detecting packages Replace the DM3610
BOX_SAME_STORBOX_BAD	Multiple parcels are in the DM3610 scanning area at the same time, and some may be misshapen	Confirm that there are no parcels side-by-side when they pass under the DM3610
		Run a calibration box to confirm whether the DM3610 is returning accurate dimensions
		Confirm that all parcels passing under the DM3610 are cuboidal
		Determine whether the parcel material may be causing the problem. (i.e. Specular)
		Replace the DM3610

Error Code(s)	Possible Cause	Corrective Action
BOX_SIDE_LEN_TOO_ SHORT	Parcels are smaller than the minimum package size settings found in <i>Modify</i> <i>Settings Dimensioning </i> <i>Settings (See 4.6.1)</i>	Run a calibration box to confirm whether the DM3610 is returning accurate dimensions Confirm that all parcels passing under the DM3610 are cuboidal Determine whether the parcel material may be causing the problem (i.e. Specular) Replace the DM3610
BOX_TOL_FAIL_HEIGHT	Parcels being conveyed are less than the Minimum Package Size - Height settings found in <i>Modify</i> <i>Settings Dimensioning </i> <i>Settings (See 4.6.1)</i>	Run a calibration box to confirm whether the DM3610 is returning accurate dimensions Run <i>Diagnostics </i> <i>DimView</i> (See 4.12.2) in the user interface to determine whether the DM3610 is detecting packages Run the Find Belt calculation under <i>Modify</i> <i>Settings Dimensioning </i> <i>Calibration</i> (See 4.6.2) in the user interface Replace DM3610

Error Code(s)	Possible Cause	Corrective Action
BOX_TOL_FAIL_WIDTH	Parcels being conveyed under the DM3610 are less than the Minimum Package Size - Width settings found in <i>Modify Settings </i> <i>Dimensioning Settings</i> (See 4.6.1)	Run a calibration box to confirm whether the DM3610 is returning correct dimensions Run <i>Diagnostics </i> <i>DimView</i> (See 4.12.2) in the user interface to determine whether the DM3610 is detecting packages Run the Find Belt calculation under <i>Modify</i> <i>Settings Dimensioning </i> <i>Calibration</i> (See 4.6.2) in the user interface Replace DM3610
BOX_POINTS_NEAR_ CORNERS	Parcels are not cuboidal and present non-squared corners to the DM3610 Black parcel reflectivity is below the DM3610's reflectivity minimum	Confirm that the parcels are within the min/max size settings found in <i>Modify</i> <i>Settings Dimensioning </i> <i>Settings (See 4.6.1)</i> Run a calibration box to determine whether the DM3610 returns no dimensions or only dimensions for certain packages Run <i>Diagnostics </i> <i>DimView (See 4.12.2)</i> in the user interface to determine whether the DM3610 is detecting packages Replace DM3610

Error Code(s)	Possible Cause	Corrective Action
BOX_SIDE_LEN_TOO_LONG	Parcels are larger than the maximum package size settings found in <i>Modify</i> <i>Settings Dimensioning </i> <i>Settings (See 4.6.1)</i>	Run a calibration box to confirm whether the DM3610 is returning accurate dimensions
		Confirm that all parcels passing under the DM3610 are cuboidal
		Determine whether the parcel material may be causing the problem (i.e. Specular)
		Replace the DM3610
BOX_STACKED	Multiple parcels are in the DM3610 scanning area at the same time	Confirm that the packages are singulated when passing under the DM3610 scan line
BOX_SYSTEM_FAULT	Temperature compensation or scan rate fault. This is indicated on the user interface <i>Diagnostic </i> <i>Monitor</i> screen (See 4.12.1)	Replace the DM3610

Error Code(s)	Possible Cause	Corrective Action
BOX_TOL_FAIL_LENGTH	Incorrect tachometer (encoder) signal	On the user interface <i>Diagnostic Monitor</i> screen (See 4.12.1), check
	Package rubbing on the side rail causing it to go slower through the DM3610 scan line	the belt speed and confirm that it matches the actual belt speed
	Parcels are larger than the maximum package size settings found in <i>Modify</i>	Confirm that the parcels are within the min/max ignore range on the configuration page
	Settings (See 4.6.1)	Run a calibration box to confirm whether the DM3610 is returning accurate dimensions
		Run <i>Diagnostics</i> <i>DimView</i> (See 4.12.2) in the user interface to determine whether the DM3610 is detecting packages
		Run the Find Belt calculation under <i>Modify</i> <i>Settings Dimensioning </i> <i>Calibration</i> (See 4.6.2) in the user interface
		Replace the DM3610
BOX_WRITE_ALIBI_FAIL	DM3610 Internal malfunction	Replace the DM3610



Error Code(s)	Possible Cause	Corrective Action
LFT_ALIBI_OPEN_FAIL	Alibi memory storage failed	Cycle power on the DM3610
LFT_ALIBI_WRITE_FAIL		
LFT_ALIBI_READ_FAIL		Monitor to confirm that the problem does not reoccur
LFT_AUDIT_OPEN_FAIL		Replace the DM3610
LFT_AUDIT_WRITE_FAIL		
LFT_AUDIT_READ_FAIL		
LFT_DSP_COMPONENT_ INVALID	Internal memory failure	Confirm that the software has not changed
LFT_FPGA_COMPONENT_ INVALID	May occur after software upgrade	Cycle power on the DM3610
LFT_LIBRARY_COMPONENT_ INVALID		Replace the DM3610
LFT_COMPONENT_ SIGNATURE_FILE_FAIL		
LFT_PARAMETER_SET_ INVALID		
LFT_CALIBRATION_ PARAMETER_SET_INVALID		
LFT_CLOCK_FAULT LFT_CLOCK_DATE_FAULT	The internal Real Time Clock failed	Replace the DM3610
LFT_CONVEYOR_SPEED_ FAULT	Tachometer signal is not present or is sporadic	Check tachometer mounting and connections
		Check tachometer's settings in <i>Modify Setting Tach/</i> <i>Trigger/ Transmit</i> (See 4.7)
		Replace the DM3610
LFT_MOTOR_SPEED_FAULT	Scanning motor failed or is not regulated	Replace the DM3610

Error Code(s)	Possible Cause	Corrective Action
LFT_TEMP_COMP_FAULT	The DM3610 is determines that the ambient temperature is fluctuating and it is unable to compensate for the change	Confirm that the DM3610 is not mounted where there is a sudden and drastic change in temperature Replace the DM3610
LFT_UNIT_SKEW_FAULT	The DM3610 has determined that the left/right ignores are not where they were original calculated	Using the static calibrations steps, make sure that the DM3610 tilt, pitch, and skew mounting is correct (See 5.6) Run both Static and Dynamic calibration on the DM3610 (See 5.6)
LFT_UNIT_HEIGHT_FAULT	The DM3610 is calculating that it is not level with the conveyor surface	Check that the DM3610 is mounted correctly above conveyor surface. If it is not, preform both the Static and Dynamic calibration <i>(See</i> <i>5.6)</i> If the mounting bracket is mounted in the correct orientation above the conveyor, replace the DM3610
LFT_INTERNAL_TACH_MODE	The DM3610 tachometer source is set to Constant/ Internal in <i>Modify Setting </i> <i>Tach/Trigger/ Transmit</i> (See 4.7)	Change tachometer setting to Hardware/External in Modify Setting Tach/Trigger/ Transmit (See 4.7)
ID_SEND_BUFFER_ON_AUX_ PORT Fail (11) (16)	No Backup Module in CBX connection box or Backup Module failed	Install or replace the Backup Module in the CBXconnection box Change RS232 Mode in <i>Modify Settings Serial </i> <i>Port #N</i> to RS232 Direct (See 4.9.1)
BOX_BAD_JAC_CHOL BOX_BAD_CHOL BOX_SIZE_CORRECTION_ ERROR	DM3610 Internal malfunction	This error may occur randomly. If the error continues to occur then replace DM3610

8 TECHNICAL FEATURES

8.1 TECHNICAL SPECIFICATIONS

DM3610 Dimensioner

ELECTRICAL FEATURES

Power Requirements	24VDC +/- 10%
Power Consumption	19 W Average (75 W Max) based on 600 scans/second
Communication Interfaces	Ethernet (TCP/IP), RS232/ RS422 (RS485 for custom only)
Inputs	(1) Tachometer, (1) Trigger, (2) SW programmable general purpose

Visible laser diode (red) 660nm, Class 2

OPTICAL FEATURES

Laser Type

DIMENSIONING FEA	TURES
Dimensioning	
Accuracy	
• NTEP/	\pm 0.20" for length and width and \pm 0.10" for height
• OIML	± 5.0 mm for length, width and height
Conveyor Speeds	Up to 3.1 m/s [620 fpm]
Box Size (maximum)	L 2500 mm [98"] x W 1200 mm [48"] x H 900 mm [36"]
Box Size (minimum)	
NTEP	L 2.4" x W 2.4" x H 1.2"
• OIML	L 50 mm x W 50 mm x H 50 mm
USER INTERFACE	
Status Indicators	LEDs - STATUS, TRIGGER, TACH, READ, RX/TX, NETWORK,
	DIMENSION STATUS INDICATORS

	DIMENSION STATUS INDICATORS
Keypad	3 keys
Programming	On board HTML web server interface

ENVIRONMENTAL FEATURES	
Temperature	Operating: 0° to 50° C [32° to 122° F] Storage: -20° to +70° C [-4° to +158° F]
Relative Humidity	10-90% non-condensing

PHYSICAL FEATURES		
Overall Dimensions	L 279 mm [11.0"] x W 152 mm [6.0"] x H 175 mm [6.9"]	
Mounting Dimensions	L 340 mm [13.39"] x W 182 mm [7.15"] x H 281 mm [11.07"]	
Weight	5.5 kg [12 lbs.]	
Enclosure	IP 65, Aluminum	

OPTIONS AND WARRANTY Options Side-by-side package detection, irregulars, out-of-gauge detection

Service Options	Installation services and on-site training
Warranty	2-year limited, parts and labor

The latest product documentation can be downloaded from our website, <u>www.datalogic.com</u>.

Alignment

The position of a dimensioner, scanner, or light source in relation to the target of a receiving element.

ASCII (American Standard Code for Information Interchange)

Pronounced ask-ee. A seven bit plus parity code established by ANSI to achieve compatibility between data services.

Barcode

A pattern of variable-width bars and spaces which represents numeric or alphanumeric data in machine-readable form. The general format of a barcode symbol consists of a leading margin, start character, data or message character, check character (if any), stop character, and trailing margin. Within this framework, each recognizable symbology uses its own unique format.

Barcode Label

A label that carries a barcode and can be affixed to an article.

Baud Rate

A unit used to measure communications speed or data transfer rate.

BCC (Block Check Character)

Used to check transmission accuracy, a character transmitted by the sender after each message block and compared with a block check character computed by the receiver.

Belt width

The width of the conveyor belt measured in millimeters or inches.

CDRH (Center for Devices and Radiological Health)

This organization (a service of the Food and Drug Administration) is responsible for the safety regulations governing acceptable limitations on electronic radiation from laser devices. Datalogic devices are in compliance with the CDRH regulations.

Configuration

The arrangement and interconnection of hardware components within a system, and the hardware (switch and jumper) and software selections that determine the operating characteristics of the system.

Conveyor speed

The speed that the conveyor is moving measured in meters per second (mps) or feet per minute (fpm). Conveyor speed directly impacts the time that the parcel passes below the dimensioner, and therefore, affects the possible transmission and quality of the dimensions returned to the host.

(d)

Represents the smallest interval between two consecutive values used in the dimension calculations.

Default(s)

Original parameters as programmed at the factory.

Dimensioner

A device that captures and calculates the length, width, and height of an object, and then sends that information to a host system.

Drop-down list, menu

A graphical user interface component that allows the user to select from a list of options that are displayed when a specific function has been selected. This options list drops down from the selected function.

Field of view (FOV)

Defines the coverage area across the conveyor belt width over which the dimensioner can detect objects. FOV is a linear measurement of the length of the scan line and should be qualified with a throw distance (e.g.: 24 FOV @ 60 throw).

A maximum theoretical FOV is the absolute maximum scan line length assuming sufficient uniform illumination along the whole scan line. Effective FOV is the useful length of the scan line as limited by the illumination and/or the camera. (For example: At a throw of 60, a camera may have a maximum theoretical FOV of 24 but the illumination may only cover a 20 FOV, so the effective FOV of the camera/illumination system would be 20.)

Full Duplex

Simultaneous, two-way, independent transmission in both directions.

Gateway

A device used to connect networks using different protocols so that information can be passed from one system or network to the other(s).

Gateway address

Like all other devices on a network, the device serving as the gateway must also have an IP address so that devices wishing to communicate with devices outside its own network can fine the gateway which will forward its data. Like all other addresses, it is displayed in the dotted-decimal format.

Half Duplex

Transmission in either direction, but not simultaneously.

Handshaking

Exchange of predetermined signals between two devices establishing a connection. Usually part of a communications protocol.

Header

A means of identifying the beginning of a message to be sent to the host. One example is <STX> or Start of Text.

Hexadecimal

A base-16 numbering system that uses the symbols 0,1,2,3,4,5,6,7,8,9,A,B,C,D,E,F.

Host

A computer that serves other terminals in a network, providing services such as network control, database access, special programs, supervisory programs, or programming languages.

Interface

A shared boundary defined by common physical interconnection characteristics, signal characteristics and meanings of interchanged signals.

IP (internet protocol) address

Jumper

A wire that connects a number of pins on one end of a cable only, such as looping back Request to Send from Clear to Send pins 4 and 5.

LED (Light Emitting Diode)

A low power electronic device that can serve as a visible or near infrared light source when voltage is applied continuously or in pulses. It is commonly used as an indicator light and uses less power than an incandescent light bulb but more than a Liquid Crystal Display (LCD). LEDs have extremely long lifetimes when properly operated.

Memory

A computer can contain several different forms of memory, such as RAM, ROM, and video memory. The term memory is generally used to define RAM. When a computer has 8 MB of memory, it actually has 8 MB of RAM.

Measurement Canada

A Canadian government organization created "to ensure equity and accuracy where goods and services are bought and sold on the basis of measurement, in order to contribute to a fair and competitive marketplace for Canadians."

Message

1) A meaningful combination of alphanumeric characters that establishes the content and format of a report. 2) In a communication network, the unit of exchange at the application layer.

MID (Measuring Instruments Directive)

Directive by the European Union, which seeks to regulate many aspects of legal metrology across all member states of the EU.

NCWM/NTEP (National Conference On Weights and Measure)

Organization that regulates the United States technical standards for weights and measures.

Net mask

A numeric value that is used by devices to determine whether the device it wishes to communicate with is on the same network. If not, the data must be forwarded via a gateway. May also be referred to as subnet mask.

Network

A series of stations (nodes) connected by some type of communication medium. A network may be made up of a single link or multiple links.

No dim

When the dimensioner is unable to calculate dimensions within specified parameters as a parcel passes through the scan zone.

OIML

The International Organization of Legal Metrology (Organisation Internationale de Métrologie Légale) formed to set technical standard regulations globally for weights and measures.

Parameter

A value that you specify to a program. Typically parameters are set to configure a device to have particular operating characteristics.

Pitch

Rotation of a device about the X-axis.

Position

The position of a scanner or light source in relation to the target of a receiving element.

Photoelectric Sensor

Device used, often as a *trigger*, to detect the absence or presence of a parcel by using a light transmitter and reflector. Sometimes referred to as a *photo eye*.

Protocol

A formal set of conventions governing the formatting and relative timing of message exchange between two communicating systems.

Pulses per centimeter - Defines the number of pulses per centimeter of transport travel as provided by the tachometer.

Pulses per inch

Defines the number of pulses per inch of transport travel as provided by the tachometer.

Relay

Relays are simply electrical switches that are typically used to control external diverts, alarms, etc. Relay types available are FORM A and FORM C. FORM C type relays have both normally open and normally closed contacts available while FORM A type relays have only normally open contacts available.

Resolution (d), Length, Width, Height

Represents the smallest length, width, or height interval between two consecutive values used in calculating dimensions.

RS232

Interface between data terminal equipment and data communication equipment employing serial binary data interchange.

RS485

Interface that specifies the electrical characteristics of generators and receivers for use in balanced digital multipoint systems such as on a Multidrop line.

Scanner

A device that examines a printed pattern (barcode) and either passes the uninterpreted data to a decoder or decodes the data and passes it onto the Host system (sometimes used interchangeably with *dimensioner*.)

Serial Port

An I/O port used to connect a scanner to your computer.

Signal

An impulse or fluctuating electrical quantity (i.e.: a voltage or current) the variations of which represent changes in information.

Skew

Rotation of a device about the Y-axis.

STX (Start of Text)

A transmission control character that precedes a text and is used to terminate a heading. (^B)

Symbol

A combination of characters including start/stop and checksum characters, as required, that form a complete scannable barcode.

Tachometer (tach)

Hardware device used to provide conveyor speed information to the dimensioner in x pulses per centimeter or inch.

TCP/IP

An industry standard suite of protocols providing communications in a heterogeneous network environment. TCP/IP stands for Transport Control Protocol/Internet Protocol.

Tilt

Rotation of a device about the Z axis.

Tracking

Process of keeping track of packages as they travel through the scanning area. Tracking can be done based on the leading edge or trailing edge of packages. Belt speed (as monitored via the tachometer signal) and camera mounting also figure into the tracking process.

Trailer

A means of identifying the end of a message sent to the host. One example is <ETX> or End of Text.

Transmit point

The time it takes to transmit the calculated results from the time the object is first sensed until the completion of transmission to the host.

Trigger Signal

A signal, typically provided by a photoelectric sensor or proximity switch, which informs the scanner of the presence of an object within its reading zone.

UPC

Acronym for Universal Product Code. The standard barcode type for retail food packaging in the United States.

Visible Laser Diode

A light source used in scanners to illuminate the barcode symbol. Generates visible red light at wavelengths between 630 and 680 nm.

WELMEC (European cooperation in the field of legal metrology)

Regulating body set up to promote European cooperation in the field of legal metrology.

Write protect Read-only files are said to be *write-protected*. The backup module has a switch to toggle its write-protect mode.

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DIMENSIONING CERTIFICATIONS

Certifications Included:

- NTEP
- OIML
- Measurement Canada



Certificate Number: 13-040P Page 1 of 2

NATIONAL TYPE EVALUATION PROGRAM

Certificate of Conformation for Weighing and Measuring Devices ormance

For: Multiple Dimension Measuring Device Model: DM3610 Maximum: (see below) Minimum: (see below) d_{min}: (see below) Submitted By: Datalogic Automation 511 Schoolhouse Road Telford, PA 18969 Tel: 800-227-2633 (1-800-BARCODE) Contact: Anthony Romeo Email: <u>anthony.romeo@datalogic.com</u> Web site: <u>www.datalogic.com</u>

Standard Features and Options

Dynamic Dimensioning only

Standard Features: This system consists of a minimum amount of required equipment: one DM3610 (dimensioner), one power supply, one tachometer, one photo-eye (optional) and one 2 line by 20 character display (optional).

Axis ID	dmin	Minimum Dimension	Maximum Dimension	Minimum Velocity	Maximum Velocity
Length	0.2 inch	2.4 in	98.0 in		
Width	0.2 inch	2.4 in	48.0 in	50 ft/min	620 ft/min
Height	0.1 inch	1.2 in	36.0 in		

- Minimum Spacing between packages: 2 inches
- Width= shortest horizontal plane; Length= longest horizontal plane; Height= vertical plane
- Minimum operating requirements and screen explanations: see the "Operation" section on page 2.

Options:

System may be composed of equipment equal in function as stated in the Standard section. The photo eye is optional and is only used to control the message transmit distance and has no metrological significance. The power supply may be replaced with a similar power supply. The tachometer may be replaced by a tachometer of similar design. The 2 line by 20 character display may be replaced with a similar display.

An optional bar code scanner(s) or camera(s) may be used with the DM3610. An optional controller may be used to match the bar code data with the dimension data.

Temperature Range: 0 °C to 40 °C (32 °F to 104 °F)

This device was evaluated under the National Type Evaluation Program and was found to comply with the applicable technical requirements of "NIST Handbook 44: Specifications, Tolerances and Other Technical Requirements for Weighing and Measuring Devices." Evaluation results and device characteristics necessary for inspection and use in commerce are on the following pages. *Editorial changes, not affecting the type or metrological content, corrected this certificate.

Stephen Benjamin Chairman, NCWM, Inc.

Kurt Floren

Committee Chair, National Type Evaluation Program Committee Issued: April 24, 2013

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Datalogic Automation

Multiple Dimension Measuring Device / DM3610

Application: The DM3610 is used to calculate the dimensions of an opaque cuboidal object in a dynamic (conveyor) scenario. The DM3610 must work in conjunction with a tachometer. The tachometer generates a pulse signal with a frequency proportional to the speed of the conveyor, which in turn allows the device to calculate the correct along the belt measurement.

Identification: The required information appears on an adhesive badge attached to the top of the of the DM3610 housing.

Sealing: The DM3610 has a Category 1 physical seal and a Category 3 Audit Trail. The device and is physically sealed by provisions for a wire seal.

Operation:

The DM3610 is a dynamic dimensioning system that mounts over a conveyor system. Cuboidal objects must travel on the conveyor with a minimum 2 inch separation between objects.

- User operation is via a web interface via any Ethernet port.
- Software Identification and version is displayed on the 2 line by 20 character display on power up or on the GUI.
- The 2 line by 20 character display shows dimensioning data for the most recent object. An error condition is indicated on the display.

<u>Test Conditions</u>: For the purpose of this evaluation, a DM3610-1100, power supply, tachometer, photo-eye (is optional and was only used to show its function) and 2 line by 20 character display were submitted for evaluation. The emphasis of the evaluation was on device design, marking, operation, performance, and compliance with influence factor requirements. Several measurements were performed near maximum, near minimum, and near mid-range for the ranges listed. The device(s) were tested over a temperature range of 0 °C to 50 °C (32 °F to 122 °F). Measurements were also conducted with power supplies of 16 VDC and 24 VDC.

NOTE: This Certificate is issued as a provisional NTEP Certificate of Conformance (CC). This evaluation is based on the current draft checklist, procedures and technical policy contained in NCWM Publication 14 for this device type. When work on the NCWM Publication 14 section for this device is completed, the test report and this NTEP CC will be reviewed. If all current requirements have been met by this evaluation, the provisional status will be removed.

Evaluated By: J. Morrison (OH)

Type Evaluation Criteria Used: *NIST Handbook 44 Specifications, Tolerances, and Other Technical Requirements for Weighing and Measuring Devices,* 2013 Edition. *NCWM Publication 14 Measuring Devices,* 2013 Edition.

<u>Conclusion</u>: The results of the evaluation and information provided by the manufacturer indicate the device complies with applicable requirements.

Information Reviewed By: J. Truex (NCWM)

Example(s) of Device:



DIMENSIONING SYSTEM





OIML Certificate of Conformity

OIML Member State The Netherlands Number R129/2000-NL1-13.01 Project number 13200217 Page 1 of 2

Issuing authority	NMi Certin B.V. Person responsible: C. Oosterman			
Applicant	Datalogic Automation Srl Via Lavino n. 265 Monte San Pietro 40050 Italy			
ldentification of the certified type	A Multi-Dimensional Measuring Type	instrument : DM3610		
Characteristics	See next page			

This Certificate attests the conformity of the above identified Type (represented by the sample(s) identified in the OIML Test Report) with the requirements of the following Recommendation of the International Organization of Legal Metrology (OIML):

OIML R129 - Edition 2000 (E)

This Certificate relates only to the metrological and technical characteristics of the type of measuring instrument covered by the relevant OIML International Recommendation above-identified. This Certificate does not bestow any form of legal international approval.

Important note: Apart from the mention of the Certificate's reference number and the name of the OIML Member State in which the Certificate was issued, partial quotation of the Certificate and of the associated OIML Test Report(s) is not permitted, although either may be reproduced in full.

Issuing Authority

NMi Certin B.V., OIML Issuing Authority NL1 6 August 2013

Costerman

Head Certification Board

NMi Certin B.V. Hugo de Grootplein 1 3314 EG Dordrecht the Netherlands T +31 78 6332332 certin@nmi.nl www.nmi.nl This document is issued under the provision that no liability is accepted and that the applicant shall indemnify third-party liability.

The notification of NMi Certin B.V. as Issuing Authority can be verified at www.oiml.org Parties concerned can lodge objection against this decision, within six weeks after the date of submission, to the general manager of NMi (see www.nmi.nl),...





OIML Certificate of Conformity

OIML Member State The Netherlands

Number R129/2000-NL1-13.01 Project number 13200217 Page 2 of 2

The conformity was established by the results of tests and examinations provided in the associated OIML Test Report(s):

- No. NMi-13200217-01 dated 6 August 2013 that includes 64 pages.

Characteristics of the multi-dimensional measuring instrument

Suitability for measuring objects ^{*)}	Objects that are rectangular, opaque, and have regular surfaces				
Determination of dimensions of objects during automatic operation	dynamically				
Type of package flow	Instrument is capable of measuring single objects or multiple objects simultaneously in the measurement area				
Max	L		W	Н	
	Max _L ≤ 2500 mm		Max _w ≤ 1200 mm	Max _H ≤ 900 mm	
Min	Min _L ≥ 50 mm		Min _w ≥ 50 mm	Min _H ≥ 50 mm	
Scale interval	d _L ≥5 mm		d _w ≥5 mm	d _H ≥5 mm	
Maximum number of partial measuring ranges	1				
Maximum belt speed	V _{max} ≤ 3,15 m/s				
Temperature range	-10 °C / +50 °C				
Environment classes	M2 / E1				
Power supply voltage	22,5 – 26,5 V DC				
Software identification	MD5 hashes				
	DSP software 9769FD1C96438C5AB910F725545FFDB3			F725545FFDB3	
	FPGA software 61A92F0F152949924F17152E063A9236			52E063A9236	
	LFT library	y 94092F384948235EB4E70E30667D8991			

¹⁾ The smallest rectangular box that fully encloses the object is determined.

The above-mentioned limitations of use shall be clearly marked on the markings plate in a visible place to the operator.

The software identification can be shown as follows:

- Upon start-up of the instrument (it is displayed on the (optional) remote display), or;
- The system runs a web server through which the software identification can be accessed. From the main screen press the following sequence:
 - 'Modify Settings' -> 'Configuration'.

APPROVAL No. - N° D'APPROBATION AM-5924C

NOTICE OF CONDITIONAL APPROVAL

Issued by statutory authority of the Minister of Industry for the following device model(s):

TYPE OF DEVICE

Electronic Multiple Dimension Measuring Device

APPLICANT

AVIS D'APPROBATION CONDITIONNELLE

Émis en vertu du pouvoir statutaire du ministre de l'Industrie pour le(s) modèle(s) d'instrument suivant(s):

TYPE D'APPAREIL

Appareil électronique de mesure multidimensionnelle

REQUÉRANT

Datalogic Automation Inc. 511 School House Rd. Telford, PA U.S.A / É-U 18969

MANUFACTURER

FABRICANT

Datalogic Automation Inc. 511 School House Rd. Telford, PA U.S.A / É-U 18969

MODEL NUMBER(S) - NUMÉRO(S) DE MODÈLE(S)

DM3610-1300 DM3610-2300

USE □ General Use ⊠ Restricted Use USAGE □ Usage général ⊠ Usage restreint



SECTION 1 (including cover page) - Model Identification and Summary of Device Main Metrological Characteristics

NOTE: This approval applies only to devices, the design, composition, construction and performance of which are, in every material respect, identical to that described in the material submitted, and that are typified by samples submitted by the applicant for evaluation for approval in accordance with sections 14 and 15 of the *Weights and Measures Regulations*. The following is a summary of the principal features only.

SECTION 2 - Model(s) Identification and Summary of the Parameters and Limitations

The model(s) listed at the top of the following table is (are) approved according to the metrological characteristics indicated in the other corresponding columns of the table. Models produced for use in trade must comply, namely in terms of settings and use, with the metrological characteristics indicated in the table.

When values in columns are in imperial and in metric units, the device can be operated in dual units. If one of these units is in brackets, this unit selection is programmable and sealable; if it is not in brackets, the operator can select the unit through the keyboard.

PARTIE 1 (incluant la page couverture) - Identification du(des) modèle(s) et sommaire des caractéristiques métrologiques principales de l'appareil.

REMARQUE : Cette approbation ne vise que les appareils dont la conception, la composition, la construction et le rendement sont identiques, en tout point, à ceux qui sont décrits dans la documentation reçue et pour lesquels des échantillons représentatifs ont été fournis par le requérant aux fins d'évaluation, conformément aux articles 14 et 15 du Règlement sur les poids et mesures. Ce qui suit est une brève description de leurs principales caractéristiques.

PARTIE 2 - Identification du(des) modèle(s) et sommaire des paramètres-limites

Le(les) modèle(s) énuméré(s) dans la colonne 1 du tableau suivant, est (sont) approuvé(s) en fonction des paramètres indiqués dans les autres colonnes correspondantes du tableau. Le(les) modèle(s) construit(s) pour usage dans le commerce doit(vent) être réglé(s) et utilisé(s) selon les fonctions métrologiques indiquées dans le tableau.

Lorsque des valeurs sont indiquées en unités impériales et en unités métriques, l'appareil peut fonctionner dans les deux unités. Si une des unités est entre parenthèses, la sélection de l'unité est programmable et scellable; si elle est indiquée sans parenthèses, l'opérateur peut choisir l'unité au moyen du clavier.

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SECTION 2- TABLE 1 - Device Main Metrological Characteristics

PARTIE 2 -TABLEAU 1 - Les caractéristiques métrologiques principales des appareils

Models / Modèles →	DM3610-1300 DM3610-2300								
Speed/Vitesse (v)	d				Min		Max		
	X	Y	Z	X	Y	Z	X	Y	Z
v ≤ 3.2 m/s (630 ft/pi / min)		nm n /po)	5 mm (0.1 in /po)		mm in /po)	60 mm (1.2 in /po)	2450 mm (98 in /po)	1220 mm (48 in /po)	900 mm (36 in /po)
Temperature limits	/ Limites de 1	température:					-10 °C to/à 50 °	°C	
 ① Fixed Speed / Vitesse fixe ② Variable Speed / Vitesse variable ③ Unidirectional / Unidirectionnel ④ Bidirectional / Bidirectionnel 					2 3				
Minimum speed of	measurement	t/ Vitesse mir	nimale de mesu	ires:		0.02	2 m / s, 5 ft/pi	/ min	
Maximum speed of	measuremen	t/ Vitesse ma	ximale de mesu	ires:	3.2 m / s, 630 ft/pi / min				
		Minimum	spacing betwe	een objects/ I	Espacement m	ninimal entre l	es objets		
Speed / Vitesse (v)					Distance between objects / distance entre les objets ① in the direction of travel / dans la direction du déplacement ② surrounding the objects / autour des objets ③ touching / en contact				
0.02 m/s to/à 3.2 m/s, 5 ft/pi / min to /à 630 ft/pi / min				① 25 mm , 1 in/po (DM3610-1300) ② 25 mm , 1 in/po (DM3610-2300)					
			Туре	e of device / (Genre d'appai	reil			
 Cuboïdal objects only / Seulement pour objets cuboïdaux Non-Cuboïdal objects / Objets non-cuboïdaux Palletized Freight / fret sur palette 				0					
 Static measurement / Mesure statique In-motion measurement / Mesure en mouvement 				2					
 Singulated measurement / Mesure singulière Touching objects / Objets qui se touchent Non-singulated non-touching objects / Mesure non-singulière, objets qui ne se touchent pas 				① DM3610-1300 ③ DM3610-2300					
Describe measurem X: Horizontal meas Y: Horizontal meas Z: Measurement per Meaning of the cod informations :	urement long urement perp rpendicular to	titudinal to the pendicular to the plane of	e transport dire the transport dir the measuring	ction / Mesur rection / Mes surface/ Mes	ure horizontale ure perpendice	e perpendiculai ulaire au plan d	re à la direction e la surface de	n du transport mesure	tres

The DM3610-1300 is for singulated measurement whereas the DM3610-2300 is for non-singulated, non-touching measurement. / L'appareil DM3610-1300 est utilisé pour les mesures singulières, tandis que l'appareil DM3610-2300 est utilisé pour les mesures non singulières et pour des objets qui ne se touchent pas.

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SECTION 3 - Device Description

If an "X" appears in table columns, it means that the function or the element is present while a "---" indicates that the element or the function is absent or that it is not applicable. A "*" indicates that more information is provided in the "Other" section

SECTION 3 - TABLE 2 - Display Features

PARTIE 3 - Description de l'appareil

Le symbole "X" qui apparaît dans les colonnes des tableaux signifie que la fonction ou le dispositif est présent; alors que le symbole "----" signifie l'absence du dispositif ou de la fonction; ou que celui ou celle-ci ne s'applique pas. Le symbole "*" signifie que de plau amples reseignements sont disponibles à la section "Autre".

PARTIE 3 - TABLEAU 2 - Caractéristiques de l'affichage

Models/Modèles →	DM3610-1300, DM3610-2300				
General / Générales					
 Integrated display / Affichage intégré Separate indicator / Indicateur séparé 	2				
Indicator model if separate / Modèle de l'indicateur si séparé.	GP018				
Indicator material if separate / Matériel de l'indicateur si séparé	Aluminium				
Power Supply of indicator if separate/ Alimentation électrique de l'indicateur si séparé	The indicator is powered separately by mains power / L'indicateur est alimenté séparément par une alimentation principale				
Operator's Display / Affichage destiné à l'opérateur					
Zero or ready / Zéro ou prêt	Ready condition ¹ / Condition « prêt » ¹				
Tare (Type)					
Sleep Mode/Mode sommeil① Standby / Veille② Shut-off / Arrêt					
Dimensions as shown / présentation des dimensions	L, W, H L = Horizontal measurement longitudinal to the transport direction / Mesure horizontale longitudinale à la direction du transport W = Horizontal measurement perpendicular to the transport direction / Mesure horizontale perpendiculaire à la direction du transport H = Vertical dimension of the object / Dimension verticale de l'objet or/ou L = longest dimension of the object in horizontal plane/ la dimension la plus longue dans le plan horizontal W = shortest dimension of the object in horizontal plane / la dimension la plus courte dans le plan horizontal H = Vertical dimension of the object / Dimension verticale de l'objet				
Type of display and number of digits for / Type d'affichage et nombre de chiffres pour: ① Gross/Brut ② Tare ③ Net	 ① Vacuum fluorescent display (VFD) Affichage fluorescent sous vide (AFSV) 40 digits (20 per line) - Dot Matrix / 40 chiffres (20 chaque ligne) - Matrice de points 				
Units /Unités	mm (in/po)				

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SECTION 3 - TABLE 2 - Display Features (continued)

PARTIE 3 -TABLEAU 2 - Caractéristiques de l'affichage (suite)

Models/Modèles ➡	DM3610-1300, DM3610-2300
Metrological Annunciators /	
Voyants métrologiques:	
 ① Ready condition / Condition "prêt ② Unit of measure / Unité de mesure 	
③ Tare Entered / Entrée de tare	
 Tare Entred / Entree de tare Ange Selection / Sélection de l'étendue 	
 Measuring Device Selection / 	
Sélection du dispositif de mesure	
6 Other / Autres	
Other/ Autres	
Note / remarque 1:	
A ready condition is one of the following / l	'état "prêt" est une des conditions suivantes:
-The word "DIM READY" with the previous ainsi que les dimensions précédentes et le nur	e display / L'expression « DIM READY » est en haut de l'écran measurements and object count number are displayed / L'expression « DIM READY» néro de compte des objets précédents sont affichés nied by "DIM READY" at the top of the display / Une mesure est valide seulement si
elle s'accompagne de l'inscription « DIM RE	ADY » dans la partie supérieure de l'afficheur

Customers' Display / Affichage destiné aux clients

NA / s.o.

Keyboard and Operator Controls/ Clavier et boutons de contrôle destinés à l'opérateur

NA / s.o.

SECTION 3 - TABLE 3 - Measuring Element Features

PARTIE 3 -TABLEAU 3 - Caractéristiques des dispositifs de mesure

Models/Modèles →	DM3610-1300, DM3610-2300				
Widdels/Widdeles					
General / Générales					
Power Supply / Alimentation électrique ① V AC / V c.a. ② V DC / V c.c. ③ AC-DC adapter / Adaptateur c.ac.c.	© 24 V DC / V c.c. ③ 120 - 240 V AC-DC adapter / Adaptateur c.ac.c.				
Material /Matériau ① Housing / Boîtier ② Frame / Châssis ③ Sub-frame / Sous châssis ④ Measuring surface / surface de mesure	① Aluminium				
Specific installation requirements / Exigences spécifiques pour l'installation	The device is installed perpendicular above a conveyor belt. Before and after the instrument the conveyor must be straight and have a length equal to or greater than the certified horizontal (length) capacity of the device. / L'appareil est installé perpendiculairement au-dessus d'un convoyeur à courroie. Avant et aprés l'instrument, le convoyeur doit être droit et d'une longueur égale ou supérieure à la capacité horizontale certifiée (longueur) de l'appareil.				
Communication Ports/ Sorties de communication	Х				
Installation ① Permanent ② Mobile	(I)				
Other features and additional information / Au	tres caractéristiques et informations				

SECTION 3 - TABLE 3 - Measuring Element Features (continued)

PARTIE 3 -TABLEAU 2 - Caractéristiques des dispositifs de mesure (suite)

Models/Modèles →	DM3610-1300, DM3610-2300			
Dimension determination / Détermination de la mesure				
Components / Composantes	1 DM3610 laser dimensioning head / tête de mesure au laser 1 Tachometer / Tachymètre Junction box (CBX 100) / Boîte de junction (CBX 100) 1 Photo-eye (optional) / Cellule photoélectrique (en option)			
Description	The device is mounted perpendicularly over the belt conveyor system. A fan of light beams is generated across the conveyor, thus creating the measuring area. The measured object is then passed through these light beams. The information collected from the object passing through the fan of light together with the speed of the conveyor is used to calculate the dimensions of the object.			
	For non-singulated, non-touching operation a bar code scanner is used to assign the measurements to the correct object. /			
	L'appareil est monté perpendiculairement au-dessus d'un système de convoyeur à bande. Un éventail de faisceaux lumineux est projeté sur le convoyeur, ce qui crée la zone de mesurage. L'objet mesuré passe ensuite à travers ces faisceaux lumineux. Les données recueillies pendant que l'objet passe à travers le faisceau lumineux et la vitesse du convoyeur servent à calculer les dimensions de l'objet.			
	Dans le cas des mesures non singulières ou des objets qui ne se touchent pas, un lecteur de codes à barres est utilisé pour associer les mesures au bon objet.			
Laser Class / Classe du laser	IEC 60825-1 class/ classe 3R *			
Laser Power Output / Puissance de sortie du laser	< 9.6 mW (peak / crête)* < 1.0 mW (average / moyenne)*			
Laser Wavelength / Longueur d'onde du laser	658 nm*			

Other / Autres

*The laser class, power and wavelength listed in this Notice of Approval are for informational purposes only and should not be used to determine appropriate safety precautions. / La classe du laser, la puissance de sortie du laser et la longueur d'onde qui sont indiquées dans l'avis d'approbation sont à titre d'information seulement. Cette information ne devrait pas être utilisée pour déterminer les précautions de sécurité appropriées.

SECTION 4 - Sealing of Calibration and Configuration Parameters

Event Logger

The DM3610 is a Category 3 device with unlimited remote calibration and configuration capability and as such is sealed by means of an event logger audit trail and several physical seals.

Ready access to the contents of the event logger must be possible at all times. A hard copy printout of the contents of the event logger shall be available upon demand from the device or from an associated device on site.

Access to the event logger is through the DM3610 GUI. To enter:

- -Connect a PC to the DM3610
- -Using the PC's web browser enter the DM3610's IP address
- -Select "Modify Setting", "Dimensioning"
- -Ensure "Certification Mode" is set to "On"
- -Press "Update"
- -Select "Diagnostic", "Audit and Alibi"
- -The audit trail can be queried by date

-The log information is now displayed and can be copied and pasted.

After initial inspection the "*Certification Mode*" must be set to "*On*"

Dimensioning Head

Two wire seals are threaded through loops on either side of the housing, preventing disassembly of the dimensioning head.

Tachometer

The wheels of the tachometer are sealed with a paper seal.

The dip switch access panel on the tachometer is sealed with a paper seal.

The connection from the tachometer to the junction box is sealed at both ends with a paper seal. This seal is affixed over top of a sealing paste that will be applied to the connector by the manufacturer.

PARTIE 4 - Scellage des paramètres d'étalonnage et de configuration

Enregistreur d'événements

DM3610 est un dispositif de catégorie 3 doté d'une capacité illimitée de configuration et de certification à distance et, pour cette raison, il est scellé au moyen d'un enregistreur d'événements et de plusieurs sceaux.

Le contenu de l'enregistreur d'événements doit être facilement accessible en tout temps. Un imprimé du contenu de l'enregistreur d'événements doit être disponible sur demande à partir de l'appareil ou d'un appareil relié qui est sur place.

L'accès à l'enregistreur d'événements se fait à travers l'interface graphique du DM3610. Pour entrer :

- Brancher un ordinateur personnel au DM3610
- Dans le navigateur Web de l'ordinateur, entrer l'adresse IP du DM3610
- Sélectionner «Modify Setting» , «Dimensioning »
- Vérifier que le «Certification Mode» est réglé à «On »
- Appuyer sur «Update»
- Sélectionner « Diagnostic », «Audit and Alibi»
- Il est possible de consulter le registre électronique d'événements métrologiques par date

- Les renseignements du registre s'affichent alors; il est possible de les « copier-coller » ailleurs.

Après l'inspection initiale, le *«Certification Mode »* doit être réglé à *«On »*.

Tête de mesure

Deux fils métalliques sont enfilés dans les boucles se trouvant de chaque côté de l'appareil pour empêcher le démontage de la tête de mesure.

Tachymètre

On scelle les roues du tachymètre avec un scellé de papier.

On scelle le panneau du commutateur DIP sur le tachymètre avec un scellé de papier.

La connexion entre le tachymètre et la boîte de jonction est scellée aux deux extrémités avec un sceau en papier. Le sceau est posé sur la pâte de scellage qui sera appliquée par le fabricant sur le connecteur.

SECTION 5 - Limitations / Specific Installation and Marking Requirements

Device must be affixed permanently and according to the manufacturer's specifications.

A bar code reader or similar ID technology is required when the device is certified for non-singulated operation in order to assign the measurements to the correct object (DM3610-2300).

The device will have two marking labels. One on the sensor head and a second located near the display. These marking labels are identical, however only the label on the sensor head is to be used for inspection purposes.

Specific marking requirements:

- "Only opaque non- reflective cuboidal objects shall be measured".
- "Do not stack objects".
- "Dimensions shown are those of the smallest hexahedron in which the object may be enclosed."
- "Bar code must be present on objects and be visible to the bar code scanner array at all times" (Non-Singulated / Non Touching mode of operation)
- "Minimum distance between successive objects is 2.5 cm (1.0 inch)" (Singulated and/or Non Touching mode of operation)

SECTION 6 - Limitations and Use Requirements

The device shall only be used for the determination of freight, shipping and storage costs of objects based on their dimensions.

Ready access to the contents of the event logger must be possible at all times. A hard copy printout of the contents of the event logger shall be available upon demand from the device or from an associated device on site.

A measurement is only valid if it is accompanied by "DIM READY" at the top of the display and the transmitted measurements are only valid if accompanied by "READY" with no additional error codes. Any measurements accompanied by "DIM NOT READY" or transmitted with "NOT READY" or any error code, are not legal for trade and may not be used in a trade transaction.

PARTIE 5 - Les restrictions / exigences particulières d'installation et de marquage

L'appareil doit être fixé de façon permanente et conformément aux spécifications du fabricant.

Un lecteur de codes à barres, ou une technologie d'identification similaire, est nécessaire lorsque l'appareil est certifié pour les mesures non singulières pour associer les mesures au bon objet (DM3610-2300).

L'appareil comportera deux étiquettes de marquage. Une première sur la tête du capteur et la seconde, à proximité du dispositif d'affichage. Ces étiquettes de marquage sont identiques toutefois, seule l'étiquette apposée sur la tête du capteur sera utilisée aux fins d'inspection.

Exigences particulières relatives au marquage:

- « Seuls les objets cuboïdaux non réfléchissants et opaques doivent être mesurés. »
- « Ne pas empiler les objets. »
- « Les dimensions indiquées sont celles du plus petit hexaèdre pouvant contenir l'objet. »
- « Un code à barres doit être présent sur les objets et doit être visible au réseau de lecteurs de codes à barres en tous temps» (mode d'opération non-singulière, objets qui ne se touchent pas)
- «La distance minimale entre des objets successifs est de 2,5 cm (1,0 po)» (mode d'opération unique et/ou sans contact)

PARTIE 6 - Les restrictions/exigences d'utilisation

L'appareil ne doit être utilisé que pour déterminer les frais de transport, d'expédition et d'entreposage d'objets basés sur leursdimensions.

Le contenu du registre des événements doit être facilement accessible en tout temps. Un imprimé du contenu du registre desévénements doit être disponible sur demande à partir de l'appareil ou d'un appareil relié qui est sur place.

Une mesure est valide seulement si elle est accompagnée de la mention « PRÊT POUR LA MESURE » (*DIM READY*) au haut du dispositif d'affichage et les mesures transmises ne sont valides que si elles sont accompagnées de la mention « PRÊT » (*READY*) sans aucun code d'erreur. Toutes les mesures accompagnées de la mention « NON PRÊT POUR LA MESURE » (*DIM NOT READY*) ou transmises avec la mention « NON PRÊT » (*NOT READY*) ou tout autre code d'erreur ne sont pas légales pour le commerce et ne peuvent être utilisées dans une transaction commerciale.

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SECTION 6 - Limitations and Use Requirements (cont.)

The device will be used in a manner where the customer is not present.

Specific device limitations:

- Only opaque non- reflective cuboidal objects shall be measured
- objects cannot be stacked

SECTION 7 - Terms and Conditions

This/these device types(s) has/have been assessed against and found to comply with the requirements of the Terms and Conditions for the Approval of Multiple Dimension Measuring Devices (2006-03-16) and the Terms and Conditions for the Approval of Metrological Audit trail (2006-03-16).

This conditional approval will expire upon the adoption of the specifications related to these devices and no further devices will be authorized to be placed in service unless permitted by transitory measures announced at the time of the promulgation.

Devices installed, initially inspected, and verified under the authority of this conditional approval may require subsequent modifications by the applicant to comply with the adopted Specifications.

SECTION 8 - Photographs and Drawings

PARTIE 6 - Les restrictions/exigences d'utilisation (suite)

L'appareil sera utilisé en l'absence du client.

Restrictions spécifiques à cet appareil :

- Seuls les objets cuboïdaux non réfléchissants et opaques doivent être mesurés.
- les objets ne peuvent être superposés

PARTIE 7 - Termes et conditions

Ce(s) type(s) d'appareil(s) a/ont été évalué(s) et jugé(s) conforme(s) aux exigences des Conditions pour l'approbation des appareils de mesure multidimensionnelle (2006-03-16) et des Conditions pour l'approbation des registres électroniques des événements métrologiques (2006-03-16).

La présente approbation conditionnelle prendra fin lors de l'adoption de la norme relative à ces appareils et aucun autre appareil ne pourra être mis en service à moins qu'il en soit prévu autrement dans des mesures transitoires annoncées au moment de la promulgation.

Les appareils installés, soumis à une inspection initiale et vérifiés selon la présente approbation conditionnelle peuvent nécessiter des modifications subséquentes par le requérant afin de les rendre conformes à la norme adoptée.

PARTIE 8 - Photos et dessins



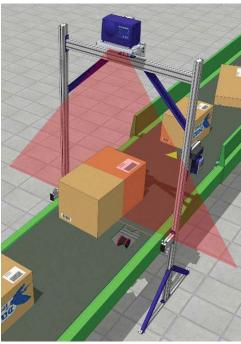
Typical Indicator / Indicateur typique

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SECTION 8 - Photographs and Drawings (continued)

PARTIE 8 - Photos et dessins

Typical Sensor Head / Capteur typique



Typical Dimensioning Arrangement / Configuration de mesure typique

Page 11 of/de 13

Project/Projet:AP-AM-13-0019

APPROVAL No. - N° D'APPROBATION AM-5924C

SECTION 9 - Evaluated by

This device was evaluated by:

Justin Rae Senior Legal Metrologist

Tested by Measurement Canada

SECTION 10 - Revision

NA

SECTION 11 - Approval

The design, composition, construction and performance of the device type(s) identified herein have been evaluated in accordance with regulations and terms and conditions established under the *Weights and Measures Act*. Approval is hereby granted accordingly pursuant to subsection 3(2) of the said Act.

The marking, installation and manner of use of trade devices are subject to inspection in accordance with regulations and terms and conditions established under the Weights and Measures Act.

Requirements relating to marking are set forth in sections 18 to 26 of the Weights and Measures Regulations, and in section 10 of the Terms and Conditions for the Approval of Multiple Dimension Measuring Devices (2006-03-16)

Installation and use requirements are set forth in Part V of the Weights and Measures Regulations and in section 14 of the Terms and Conditions for the Approval of Multiple Dimension Measuring Devices (2006-03-16) and in Terms and Conditions for the Approval of Metrological Audit trail (2006-03-16).

A verification of conformity is required in addition to this approval. Inquiries regarding inspection and verification should be addressed to the local office of Measurement Canada

PARTIE 9 - Évalué par

Cet appareil a été évalué par:

Justin Rae Métrologiste légal principal

Testé par Mesures Canada

PARTIE 10 - Révision

s.o.

PARTIE 11 – Approbation

a conception, la composition, la construction et le rendement du (des) type(s) d'appareil(s) identifié(s) cidessus, ayant fait l'objet d'une évaluation conformément au règlement et aux conditions établis aux termes de la *Loi sur les poids et mesures*, la présente approbation est accordée en application du paragraphe 3(2) de ladite Loi.

Le marquage, l'installation, et l'utilisation commerciale des appareils sont soumis à l'inspection conformément au règlement et aux conditions établis aux termes de la *Loi sur les poids et mesures*.

Les exigences de marquage sont définies dans les articles 18 à 26 du Règlement sur les poids et mesures et dans l'article 10 des Conditions pour l'approbation des appareils de mesure multidimensionnelle (2006-03-16).

Les exigences d'installation et d'utilisation sont définies dans la partie V du Règlement sur les poids et mesures, à la partie 14 des Conditions pour l'approbation des appareils de mesure multidimensionnelle (2006-03-16) ainsi que dans les Conditions pour l'approbation des registres électroniques des événements métrologiques (2006-03-16).

Une vérification de conformité est requise. Toute question sur l'inspection et la vérification de conformité doit être adressée au bureau local de Mesures Canada.

 $\label{eq:approval no. - N° d'approbation} AM-5924C$

SECTION 12 - Signature and Date

Original copy signed by:

Ronald Peasley Senior Engineer - Gravimetry Engineering and Laboratory Services Directorate

Notice of Approval issued on: 2013-11-12

PARTIE 12 - Signature et date

Copie authentique signée par :

Ronald Peasley Ingénieur principal - Gravimétrie Direction de l'ingénierie et des services de laboratoire

Avis d'approbation émis le : 2013-11-12

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