

Installation instructions

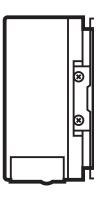
FECTOF 400

Incremental encoders

RP

UK





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UK

Preliminary note

An instruction is indicated by "▶":
 Example: ▶ Disconnect power.

1 Safety instructions

- Please read the product description prior to set-up of the unit. Ensure that the product is suitable for your application without any restrictions.
- The unit conforms to the relevant regulations and EC directives.
- Improper or non-intended use may lead to malfunctions of the unit or to unwanted effects in your application.
- That is why installation, electrical connection, set-up, operation and maintenance of the unit must only be carried out by qualified personnel authorised by the machine operator.

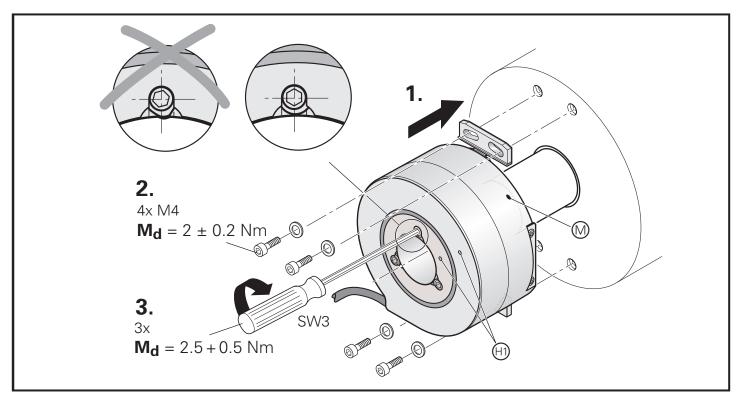
2 Functions and features

The encoder converts rotary movements into digital pulses. The evaluation of the pulses allows the determination of angular positions, lengths or rotational speeds.

- Supply voltage and resolution according to the type label
- Max. revolution mechanical
 - 20 mm hollow shaft: 6,000 rpm
 - 50 mm hollow shaft: 4,000 rpm

3 Installation

- ▶ Disconnect power. The drive must not be started during installation.
- ► The encoder shaft must not be hit; do not use a file or a similar tool on the shaft, it could destroy the unit.
- ➤ Slide the encoder over the shaft, min. 41 mm (20 mm hollow shaft); min. 56 mm (50 mm hollow shaft).
- Fix the stator coupling by means of 4 M4 screws $M_d = 2 \text{ Nm}$ (± 0.2 Nm)
- ► Tighten the clamping nut $_d$ = 2.5 Nm (+ 0.5 Nm)



H1: position of the reference mark ± 15°

M: measurement point operating temperature

4 Electrical connection

!

The unit must be connected by a qualified electrician.

The national and international regulations for the installation of electrical equipment must be adhered to.

▶ Disconnect power.

4.1 Laying the cable

- Extension by means of a screened extension cable; max. length 100 m (TTL units RP1xxx), 300 m (HTL units RP6xxx).
- ► Lay separately from sources of interference (minimum spacing 0.2 m).
- ► Connect and ground the encoder housing, the connector/ terminal box and the evaluation electronics via the screen.
- ► Connect the unit according to the indications on the type label.

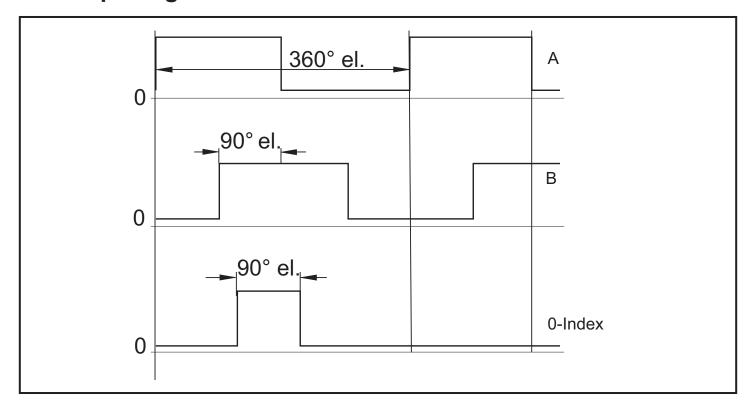
4.2 Connection of cable units

Brown	Green	Grey	Pink	Red	Black
А	A (inv.)	В	B (inv.)	0 index	0 index (inv.)

Blue	White	Brown/ green	White/green	Lilac	Screen
Up (sensor)	0 V (sensor)	Up	0 V (Un)	error (inv.)	Housing

5 Operation

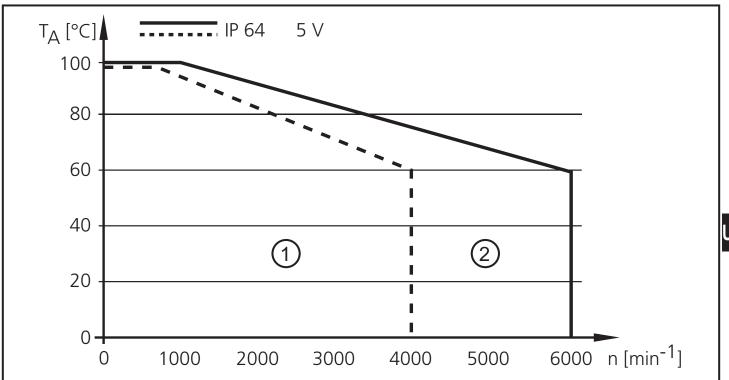
5.1 Output signals



6 Technical data

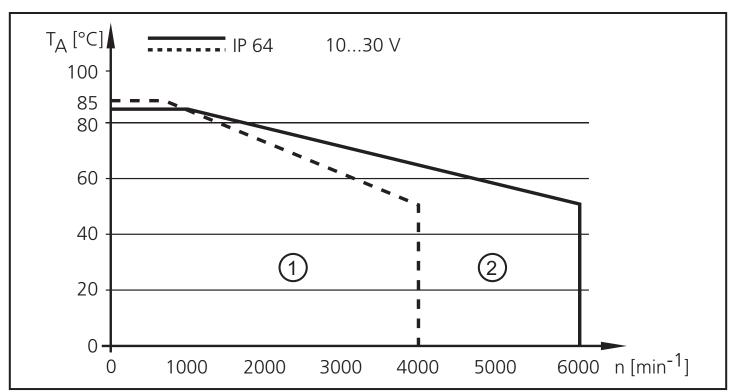
- Supply voltage and resolution (pulses per revolution / "pulses") according to the type label
- Outputs (without U_{as}) short-circuit protected against U_N (TTL units RP1xxx) and U_P (HTL units RP6xxx) < 1 minute
- Max. revolution mechanical
 - 20 mm hollow shaft: 6,000 rpm
 - 50 mm hollow shaft: 4,000 rpm
- The direct relationship between the technical data "max. revolution mechanical, operating temperature, protection" must be considered (see the following diagram).

Permissible operating temperature (T_A), depending on rpm, RP1xxx



- 1: 50 mm hollow shaft
- 2: 20 mm hollow shaft

Permissible operating temperature (T_A), depending on rpm, RP6xxx



- 1: 50 mm hollow shaft
- 2: 20 mm hollow shaft

Example:

An encoder with 5 V operating voltage and a hollow shaft diameter of 20 mm is used. To guarantee the protection IP 64 for rpm of 6000 min⁻¹ the operating temperature of +60 °C must not be exceeded.

7 Maintenance, repair and disposal

The operation of the unit is maintenance-free. It is not possible to repair the unit. After use dispose of the unit in an environmentally friendly way in accordance with the applicable national regulations.

Technical data and further information at www.ifm.com \rightarrow Select your country \rightarrow Data sheet direct: